

TPS65217A, TPS65217B, TPS65217C

www.ti.com

SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

SINGLE-CHIP PMIC FOR BATTERY-POWERED SYSTEMS

Check for Samples: TPS65217A, TPS65217B, TPS65217C

FEATURES

CHARGER/POWER PATH

- 2-A Output Current on Power Path
- Linear Charger; 700-mA Maximum Charge • Current
- 20-V Tolerant USB and AC Inputs
- 100-mA, 500-mA, 1300-mA or 1800-mA Current Limit on USB Input
- **Thermal Regulation, Safety Timers**
- **Temperature Sense Input** ٠

STEP-DOWN CONVERTER (DCDC1, 2, 3)

- **Three Step-Down Converter With Integrated** Switching FETs
 - DCDC1: 0.9 V 1.8 V at 1.2 A
 - DCDC2: 0.9 V 3.3 V at 1.2 A
 - DCDC3: 0.9 V 1.5 V at 1.2 A
- VIN Range: 2.7 V 5.8 V
- 2.25-MHz Fixed Frequency Operation
- Power Save Mode at Light Load Current
- Output Voltage Accuracy in PWM Mode ±2.0%
- 100% Duty Cycle for Lowest Dropout
- Typical 15-µA Quiescent per Converter ٠
- Passive Discharge to Ground When Disabled

LDOs (LDO1, 2)

- Two Adjustable LDOs ٠
 - LDO1: 1.0 V 3.3 V (1.8-V Default) at 100 mA
 - LDO2: 0.9V 3.3 V (3.3-V Default) at 100 mA
- VIN Range: 1.8 V 5.8 V
- LDO2 Can Be Configured to Track DCDC3
- Typical 15-µA Quiescent Current

LOAD SWITCHES (LDO3, 4)

- Two Independent Load Switches That Can Be **Configured as LDOs**
- **Configured as Switches:**
 - VIN Range: 1.8 V 5.8 V

- Switch Impedance 300 mΩ (Typical)
- 200-mA Current Limit
- Passive Discharge to Ground When Disabled
- Configured as LDOs:
 - LDO Output Voltage Range: 1.5 V 3.3 V
 - VIN Range: 2.7 V 5.8 V
 - 200-mA Current Limit (TPS65217A, B)
 - 400-mA Current Limit (TPS65217C)
 - Passive Discharge to Ground When Disabled

WLED DRIVER

- Internally Generated PWM for Dimming Control
- **38-V Open LED Protection**
- Supports Two Strings of Up To 10 LEDs at 25 mA Each
- Internal Low-Side Current Sinks

PROTECTION

- **Undervoltage Lockout and Battery Fault** Comparator
- **Always-On Push-Button Monitor**
- **Hardware Reset Pin** •
- Password Protected I²C[®] Registers

INTERFACE

- I²C Interface (Address 0x24)
- Password Protected I²C Registers PACKAGE
- Available in 6-mm × 6-mm, 48-Pin QFN

APPLICATIONS

- AM335x ARM[®] Cortex[™]-A8 Microprocessors
- **Portable Navigation Systems**
- **Tablet Computing**
- **5-V Industrial Equipment** •



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet. Cortex is a trademark of ARM Ltd or its subsidiaries.

ARM is a registered trademark of ARM Ltd or its subsidiaries. I²C is a registered trademark of Philips Semiconductors Corporation. SLVSB64E - NOVEMBER 2011-REVISED JULY 2012



www.ti.com

DESCRIPTION

The TPS65217 is a single chip power management IC specifically designed to support the AM335x series of application processors in portable and 5-V, non-portable applications. It provides a linear battery charger for single-cell Li-ion and Li-Polymer batteries, dual-input power path, three step-down converters, four LDOs, and a high-efficiency boost converter to power two strings of up to 10 LEDs each. The system can be supplied by any combination of USB port, 5-V AC adaptor, or Li-Ion battery. The device is characterized across a -40°C to +105°C temperature range which makes it suitable for industrial applications. Three high-efficiency 2.25-MHz step-down converters are targeted at providing the core voltage, memory, and I/O voltage for a processor based system.

They enter a low power mode at light load for maximum efficiency across the widest possible range of load currents. For low-noise applications the devices can be forced into fixed frequency PWM using the I²C interface. The step-down converters allow the use of small inductors and capacitors to achieve a small solution size.

LDO1 and LDO2 are intended to support system-standby mode. In SLEEP state output current is limited to 100 µA to reduce quiescent current whereas in normal operation they can support up to 100 mA each. LDO3 and LDO4 can support up to 200 mA each and can be configured as load switches instead of regulators. All four LDOs have a wide input voltage range that allows them to be supplied either from one of the DCDC converters or directly from the system voltage node.

By default only LDO1 is always ON but any rail can be configured to remain up in SLEEP state. Especially the DCDC converters can remain up in a low-power PFM mode to support processor suspend mode.

The TPS65217 offers flexible power-up and power-down sequencing and several house-keeping functions such as power-good output, pushbutton monitor, hardware reset function and temperature sensor to protect the battery.

TPS65217A is targeted at the AM335x processor in the ZCE package which does not support DVFS (dynamic voltage and frequency scaling). In this package, the VDD_MPU and VDD_CORE supplies are shorted together and require a single power rail only. DCDC1 output voltage is set to 1.8 V to supply DDR2 memory. TPS65217B is targeted at the AM335x processor in the ZCZ package which supports DVFS and requires dedicated DCDC converters for VDD_MPU and VDD_CORE rails. DCDC1 output voltage is set to 1.8V to supply DDR2 memories. TPS65217C is also targeted at the AM335x processor in the ZCZ package, but DCDC1 output voltage is set to 1.5 V to supply DDR3 memories. LDO3 is set to 1.8 V and supports up to 400-mA of current. Please see Application note SLVU551 for details.

The TPS65217A, TPS65217B and TPS65217C come in a 48-pin leadless package (6-mm x 6-mm QFN) with a 0.4-mm pitch.

2



TPS65217A, TPS65217B, TPS65217C

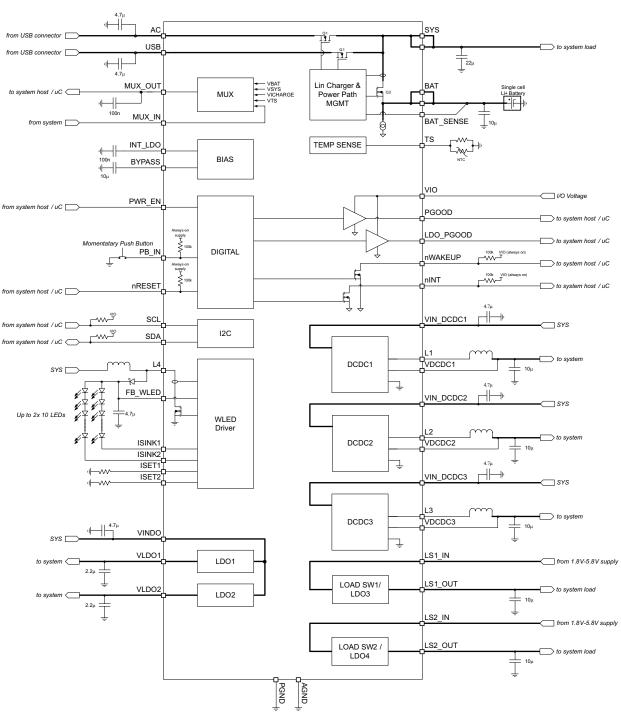
SLVSB64E-NOVEMBER 2011-REVISED JULY 2012



www.ti.com

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.



FUNCTIONAL BLOCK DIAGRAM

TPS65217A, TPS65217B, TPS65217C



STRUMENTS www.ti.com

XAS

	ORDERING INFORMATION ⁽¹⁾								
T _A	PACKAGE	ORDERABLE PART NUMBER ⁽²⁾	TOP-SIDE MARKING						
		TPS65217ARSL	TPS65217A						
-40°C to 105°C	RSL	TPS65217BRSL	TPS65217B						
		TPS65217CRSL	TPS65217C						

(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI web site at www.ti.com.

(2) The RSL package is available in tape and reel. Add R suffix (TPS65217xRSLR) to order quantities of 2500 parts per reel or suffix T (TPS65217xRSLT) to order quantities of 250 parts per reel.

		5217A AM335x - ZCE)	TPS65217B (Targeted at AM335x - ZCZ)		TPS65 (Targeted at A	
	VOLTAGE (V)	SEQUENCE (STROBE)	VOLTAGE (V)	SEQUENCE (STROBE)	VOLTAGE (V)	SEQUENCE (STROBE)
DCDC1	1.8	1	1.8	1	1.5	1
DCDC2	3.3	2	1.1	5	1.1	5
DCDC3	1.1	3	1.1	5	1.1	5
LDO1 ⁽¹⁾	1.8	15	1.8	15	1.8	15
LDO2	3.3	2	3.3	2	3.3	3
LS1/LDO3	Load switch	1	3.3 (LDO, 200 mA)	3	1.8 (LDO, 400 mA)	2
LS2/LDO4	Load switch	4	3.3 (LDO, 200 mA)	4	3.3 (LDO, 400 mA)	4

(1) Strobe 15 (LDO1) is the first rail to be enabled in a sequence, followed by strobe 1-7. See "Wake-Up and Power Up Sequencing" section for details.

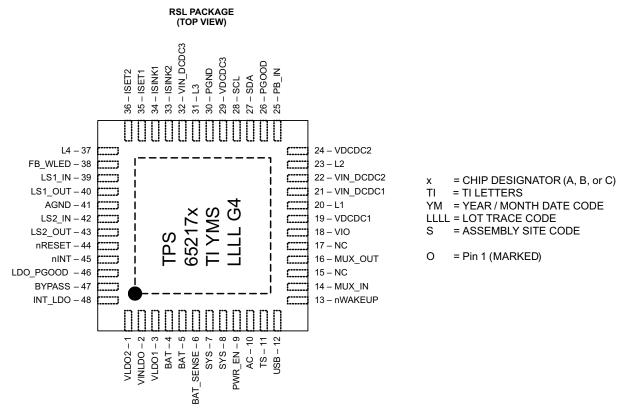
4

EXAS

INSTRUMENTS

SLVSB64E-NOVEMBER 2011-REVISED JULY 2012





48-PIN 6mm x6mm x1mm QFN

TERMINAL FUNCTIONS

TERM	INAL	- I/O	DESCRIPTION
NAME	NO.	1/0	DESCRIPTION
VLDO2	1	0	Output voltage of LDO2
VINLDO	2	I	Input voltage for LDO1 and LDO2
VLDO1	3	0	Output voltage of LDO1
BAT	4, 5	I/O	Battery charger output. Connect to battery.
BAT_SENSE	6	I	Battery voltage sense input, connect to BAT directly at the battery terminal.
SYS	7, 8	0	System voltage pin and output of the power path. All voltage regulators are typically powered from this output.
PWR_EN	9	I	Enable input for DCDC1, 2, 3 converters and LDO1, 2, 3, 4. Pull this pin high to start the power-up sequence.
AC	10	I	AC adapter input to power path. Connect to an external DC supply.
TS	11	I	Temperature sense input. Connect to NTC thermistor to sense battery temperature. Works with 10k and 100k thermistors. See charger section for details.
USB	12	I	USB voltage input to power path. Connect to external voltage from a USB port.
nWAKEUP	13	0	Signal to host to indicate a power on event (active low, open-drain output)
MUX_IN	14	0	Input to analog multiplexer
NC	15		Not used
MUX_OUT	16	0	Output pin of analog multiplexer
NC	17		Not used
VIO	18	I	Output-high supply for output buffers
VDCDC1	19	I	DCDC1 output/ feedback voltage sense input

Copyright © 2011–2012, Texas Instruments Incorporated

Submit Documentation Feedback 5

TPS65217A, TPS65217B, TPS65217C

SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

www.ti.com

NSTRUMENTS

Texas

TERM	INAL		
NAME	NO.	- I/O	DESCRIPTION
L1	20	0	Switch pin for DCDC1. Connect to inductor.
VIN_DCDC1	21	I	Input voltage for DCDC1. Must be connected to SYS pin.
VIN_DCDC2	22	I	Input voltage for DCDC2. Must be connected to SYS pin.
L2	23	0	Switch pin for DCDC2. Connect to inductor.
VDCDC2	24	0	DCDC2 output/feedback voltage sense input
PB_IN	25	I	Push-button monitor input. Typically connected to a momentary switch to ground (active low).
PGOOD	26	0	Power-good output (push/pull output). Pulled low when any of the power rails are out of regulation. Behavior is register programmable.
SDA	27	I/O	Data line for the I ² C interface
SCL	28	I	Clock input for the I ² C interface
VDCDC3	29	0	DCDC3 output/feedback voltage sense input
PGND	30		Power ground. Connect to ground plane.
L3	31	0	Switch pin for DCDC3. Connect to Inductor.
VIN_DCDC3	32	I	Input voltage for DCDC3. Must be connected to SYS pin.
ISINK2	33	I	Input to the WLED current SINK2. Connect to the cathode of the WLED string. Current through SINK1 equals current through ISINK2. If only one WLED string is used, short ISINK1 and ISINK2 together.
ISINK1	34	I	Input to the WLED current SINK1. Connect to the cathode of the WLED string. Current through SINK1 equals current through ISINK2. If only one WLED string is used, short ISINK1 and ISINK2 together.
ISET1	35	I	Low-level WLED current set. Connect a resistor to ground to set the WLED low-current level.
ISET2	36	Ι	High-level WLED current set. Connect a resistor to ground to set the WLED high-current level.
L4	37	0	Switch Pin of the WLED boost converter. Connected to Inductor.
FB_WLED	38	I	Feedback pin for WLED boost converter. Also connected to the Anode of the WLED strings.
LS1_IN	39	I	Input voltage pin for load switch 1/LDO3
LS1_OUT	40	0	Output voltage pin for load switch 1/LDO3
AGND	41	POWER	Analog GND, connect to PGND (PowerPad)
LS2_IN	42	I	Input voltage pin for load switch 2/LDO4
LS2_OUT	43	0	Output voltage pin for load switch 2/LDO4
nRESET	44	I	Reset pin (active low). Pull this pin low and the PMIC will shut down, and after 1s power- up in its default state.
nINT	45	ο	Interrupt output (active low, open drain). Pin is pulled low if an interrupt bit is set. The output goes high after the bit causing the interrupt in register INT has been read. The interrupt sources can be masked in register INT, so no interrupt is generated when the corresponding interrupt bit is set.
LDO_PGOOD	46	0	LDO power good (LDO1 and LDO2 only, push/pull output). Pulled low when either LDO1 or LDO2 is out of regulation.
BYPASS	47	0	Internal bias voltage (2.25 V). It is not recommended to connect any external load to this pin.
INT_LDO	48	0	Internal bias voltage (2.30 V). It is not recommended to connect any external load to this pin.
POWERPAD		POWER	Power ground connection for the PMU. Connect to GND

Copyright © 2011–2012, Texas Instruments Incorporated

6



SLVSB64E-NOVEMBER 2011-REVISED JULY 2012

www.ti.com

ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range (unless otherwise noted) (1)(2)

			VALUE	UNIT
		BAT	-0.3 to 7	N/
	Supply voltage range (with respect to PGND)	USB, AC	-0.3 to 20	V
		All pins unless specified separately	-0.3 to 7	
	Input/Output voltage range (with respect to PGND)	ISINK	-0.3 to 20	V
		L4, FB_WLED	-0.3 to 44	
	Absolute voltage difference between SYS and any VINLDO	VIN_DCDCx pin or SYS and	0.3	V
	Terminal current	SYS, USB, BAT	3000	mA
	Source or Sink current	PGOOD, LDO_PGOOD	6	mA
	Sink current	nWAKEUP, nINT	2	mA
) _{JA}	Junction-to-ambient thermal resistance	JEDEC 4-layer high-K board	30	°C/W
ſj	Operating junction temperature		125	°C
Γ _A	Operating ambient temperature		-40 to 105	°C
Г _{stg}	Storage temperature		-65 to 150	°C
-	v .	(HBM) Human body model	±2000	V
	ESD rating	(CDM) Charged device model	±500	v

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions is not implied. Exposure to absolute maximum rated conditions for extended periods may affect device reliability.

(2) All voltage values are with respect to network ground terminal.

RECOMMENDED OPERATING CONDITIONS

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM MAX	UNIT
Supply voltage, USB, AC		4.3	5.8	V
Supply voltage, BAT		2.75	5.5	V
Input current from AC			2.5	А
Input current from USB			1.3	А
Battery current			2	А
Input voltage range for DCDC1, DCDC2, and DCDC3		2.7	5.8	V
Input voltage range for LDO1, LDO2		1.8	5.8	V
Input voltage range for LS1/LDO, LS2/LDO4 configured as LDC)s	2.7	5.8	V
Input voltage range for LS1/LDO, LS2/LDO4 configured as load	switches	1.8	5.8	V
Output voltage range for LDO1		1.0	3.3	V
Output voltage range for LDO2		0.9	3.3	V
Output voltage range for LS1/LDO3, LS2/LDO4		1.8	3.3	V
Output current DCDC1		0	1.2	А
Output current DCDC2		0	1.2	А
Output current DCDC3		0	1.2	А
Output current LDO1, LDO2		0	250	mA
	TPS65217A	0	200	
Output current LS1/LDO3, LS2/LDO4 configured as LDOs	TPS65217B	0	200	mA
	TPS65217C	0	400	
Output current LS1/LDO, LS2/LDO4 configured as load switche	S	0	200	mA

TEXAS INSTRUMENTS

SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

ELECTRICAL CHARACTERISTICS

 $V_{BAT} = 3.6 \text{ V} \pm 5\%$, $T_J = 27^{\circ}C$ (unless otherwise noted)

	PARAMETER	TEST CO	ONDITIONS	MIN	TYP	MAX	UNIT
INPUT VOL	TAGE AND CURRENTS						
	5	USB or AC supply con	nected	0		5.5	
V _{BAT}	Battery input voltage range	USB and AC not conn	ected	2.75		5.5	V
V _{AC}	AC adapter input voltage range	Valid range for charging		4.3		5.8	V
V _{USB}	USB input voltage range	Valid range for chargin	ng	4.3		5.8	V
			UVLO[1:0] = 00		2.73		
		Measured in respect	UVLO[1:0] = 01		2.89		.,
	Under voltage lock-out	to V_{BAT} ; supply falling; $V_{AC} = V_{USB} = 0 V$	UVLO[1:0] = 10		3.18		V
V _{UVLO}		UVLO[1:0] = 11			3.3		
	Accuracy			-2		2	%
	Deglitch time	Not tested in production	n	4		6	ms
V _{OFFSET}	AC/USB UVLO offset	V _{BAT} < V _{UVLO} ; Device s V _{USB} drop below V _{UVLC}			200		mV
I _{OFF}	OFF current, Total current into VSYS, VINDCDCx, VINLDO	All rails disabled, T _A = 27°C			6		μA
I _{SLEEP}	Sleep current, Total current into VSYS, VINDCDCx, VINLDO	LDO1 and LDO2 enabled, no load. All other rails disabled. $V_{SYS} = 4 V, T_A = 0.105^{\circ}C$			80	106	μA
POWER PA	ATH USB/AC DETECTION LIMITS						
		V _{BAT} > V _{UVLO}	AC/USB valid when $V_{AC/USB} - V_{BAT} > V_{IN(DT)}$	190			mV
V _{IN(DT)}	AC/USB voltage detection threshold	V _{BAT} < V _{UVLO}	AC/USB valid when $V_{AC/USB} > V_{IN(DT)}$	4.3			V
M	AC/USB voltage removal detection	V _{BAT} > V _{UVLO}	AC/USB invalid when $V_{AC/USB} - V_{BAT} < V_{IN(DT)}$			125	mV
V _{IN(NDT)}	threshold	V _{BAT} < V _{UVLO}	AC/USB invalid when $V_{AC/USB} < V_{IN(DT)}$		V _{UVLO} + V _{OFFSET}		V
T _{RISE}	VAC, VUSB rise time	Voltage rising from 100 is exceeded, device m	0 mV to 4.5 V. If rise time ay not power-up.			50	ms
T _{DG(DT)}	Power detected deglitch	AC or USB voltage inc Not tested in production			22.5		ms
V _{IN(OVP)}	Input over voltage detection threshold	USB and AC input		5.8	6	6.4	V
POWER PA	ATH TIMING						
T _{SW(PSEL)}	Switching from AC to USB	Not tested in production	n			150	μs
POWER PA	ATH MOSFET CHARACTERISTICS						
V _{DO, AC}	AC input switch dropout voltage	IAC[1:0] = 11 (2.5 A), I	I _{SYS} = 1 A		150		mV
		IUSB[1:0] = 01 (500 m	A), I _{SYS} = 500 mA		100		
V _{DO, USB}	USB input switch dropout voltage	IUSB[1:0] = 10 (1300 r	mA), I _{SYS} = 800 mA		160		mV
V _{DO, BAT}	Battery switch dropout voltage	V _{BAT} = 3 V, I _{BAT} = 1 A			60		mV

8





SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

www.ti.com

ELECTRICAL CHARACTERISTICS (continued)

 $V_{BAT} = 3.6 \text{ V} \pm 5\%$, $T_J = 27^{\circ}C$ (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
POWER PAT	H INPUT CURRENT LIMITS					
		IAC[1:0] = 00	90		130	
		IAC[1:0] = 01	480		580	
ACLMT	Input current limit; AC pin	IAC[1:0] = 10	1000	1500		mA
	$\begin{tabular}{ c c c c c c } Input current limit; AC pin in the part of th$					
		IUSB[1:0] = 00	90		130	
		IUSB[1:0] = 01	460		500	
IUSBLMT	Input current limit; USB pin	IUSB[1:0] = 10	1000	1300		mA
			1500	1800		
I _{BAT}	Battery load current				2	А
		·				
V _{BSUP}				40		mV
• BSUP	Hysteresis	V _{SYS} rising		20		
POWER PAT		.				
V _{BAT(SC)}			1.3	1.5	1.7	V
I _{BAT(SC)}	Source current for BAT pin short-circuit					mA
INPUT BASE	D DYNAMIC POWER MANAGEMENT					
V _{DPM}	Threshold at which DPPM loop is	I ² C selectable	3.5		4.25	V
BATTERY CI	HARGER					
	Battery charger voltage	I ² C selectable	4.10		4.45	V
V _{OREG}						%
		VPRECHG = 0	_	2.9		70
V _{LOWV}						V
t _{DGL1(LOWV)}						ms
t _{DGL2(LOWV)}		Not tested in production		25		ms
		ICHRG[1:0] = 00		300		
		ICHRG[1:0] = 01		400		
I _{CHG}	$V_{OREG} > V_{BAT} > V_{LOWV},$ $V_{IN} = V_{USB} = 5 V$	ICHRG[1:0] = 10	450	500	550	mA
	*IN - *USB - 0 *	ICHRG[1:0] = 11		700		
		ICHRG[1:0] = 00		30		
		ICHRG[1:0] = 01		40		
I _{PRECHG}	Pre-charge current	ICHRG[1:0] = 10	25	50	75	mA
		ICHRG[1:0] = 11		70		
		TERMIF[1:0] = 00		2.5		
	Charge autrent value for termination	TERMIF[1:0] = 01	3	7.5	10	
I _{TERM}	Charge current value for termination detection threshold (fraction of I _{CHG})	TERMIF[1:0] = 10	0	15	10	%
		TERMIF[1:0] = 11		18		
tool (TEDL)	Deglitch time, termination detected	Not tested in production		125		ms
t _{DGL(TERM)}	Recharge detection threshold		150	123	70	mV
V _{RCH} t _{DGL(RCH)}	Deglitch time, recharge threshold detected	Voltage below V _{OREG} Not tested in production	150	125	70	ms
	Sink current for battery detection	T _{.1} = 27°C	3	7.5	10	mA
I _{BAT(DET)}	Battery detection timer. I _{BAT(DET)} is pulled from the battery for t _{DET} . If BAT voltage remains above V _{RCH} threshold the battery is connected.	$V_{BAT} < V_{RCH;}$ Not tested in production		250	10	ms
T _{CHG}	Charge safety timer	Safety timer range, thermal and DPM not active, selectable by I ² C; Not tested in production	4		8	h

Copyright © 2011–2012, Texas Instruments Incorporated



SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

www.ti.com

ELECTRICAL CHARACTERISTICS (continued)

 $V_{BAT} = 3.6 \text{ V} \pm 5\%$, $T_J = 27^{\circ}C$ (unless otherwise noted)

	PARAMETER	TEST CO	NDITIONS	MIN	TYP	MAX	UNIT
T _{PRECHG}	Precharge timer	Pre charge timer range. DPM/DPPM loops not a Not tested in production	active, selectable by I ² C;	30		60	min
BATTERY N	ITC MONITOR						
T _{THON}	Thermistor power on time at charger off, sampling mode on				10		ms
T _{THOFF}	Thermistor power sampling period at charger off, sampling mode on				1		S
	Pull-up resistor from thermistor to Internal	NTC_TYPE = 1 (10k N	TC)		7.35		
R _{NTC_PULL}	LDO I2C selectable	NTC_TYPE = 0 (100K NTC)			60.5		kΩ
	Accuracy	T _A = 27°C		-3		3	%
N/	Low temp foilure threshold	Temperature falling			1660		
V _{LTF}	Low temp failure threshold	Temperature rising			1610		mV
		Temperature falling			910		
		Temperature rising	TRANGE = 0		860		
V _{HTF}	High temp failure threshold	Temperature falling			667		mV
		Temperature rising	TRANGE = 1		622		
V _{DET}	Thermistor detection threshold			1750		1850	mV
t _{BATDET}	Thermistor not detected. Battery not present deglitch.	Not tested in production	1		26		ms
THERMAL R	REGULATION						
T _{J(REG)}	Temperature regulation limit	Temperature at which o	harge current is reduced	111		123	°C
DCDC1 (BU	СК)	ł				I	
V _{IN}	Input voltage range	VIN_DCDC1 pin		2.7		V _{SYS}	V
I _{Q,SLEEP}	Quiescent current in SLEEP mode	No load, V _{SYS} = 4 V, T _A	= 25°C		30		μA
		External resistor divider (XADJ1 = 1)		0.6		V _{IN}	
	Output voltage range	I ² C selectable in 25-mV (XADJ1 = 0)	' steps	0.9		1.8 ⁽¹⁾	V
V _{OUT}	DC output voltage accuracy	$V_{IN} = V_{OUT} + 0.3 V \text{ to } 5.0 \text{ mA} \le I_{OUT} \le 1.2 \text{ A}$	8 V;	-2		3	%
	Power save mode (PSM) ripple voltage	I_{OUT} = 1 mA, PFM mode L = 2.2 µH, C _{OUT} = 20 µ			40		$\mathrm{mV}_{\mathrm{pp}}$
I _{OUT}	Output current range			0		1.2	А
	High side MOSFET on-resistance	V _{IN} = 2.7 V			170		_
R _{DS(ON)}	Low side MOSFET on-resistance	V _{IN} = 2.7 V			120		mΩ
	High side MOSFET leakage current	V _{IN} = 5.8 V				2	
LEAK	Low side MOSFET leakage current	V _{DS} = 5.8 V				1	μA
I _{LIMIT}	Current limit (high and low side MOSFET).	2.7 V < V _{IN} < 5.8 V			1.6		А
f _{SW}	Switching frequency			1.95	2.25	2.55	MHz
V _{FB}	Feedback voltage	XADJ = 1			600		mV
t _{SS}	Soft-start time	Time to ramp V _{OUT} from	n 5% to 95%, no load		750		μs
R _{DIS}	Internal discharge resistor at L1 ⁽²⁾				250		Ω
L	Inductor			1.5	2.2		μH
<u> </u>	Output capacitor	Ceramic		10	22		μF
C _{OUT}	ESR of output capacitor				20		mΩ
DCDC2 (BU	ск)						
V _{IN}	Input voltage range	VIN_DCDC2 pin		2.7		V _{SYS}	V

(1) Contact factory for 3.3-V option.

(2) Can be factory disabled.

10 Submit Documentation Feedback

Copyright © 2011–2012, Texas Instruments Incorporated



SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

www.ti.com

ELECTRICAL CHARACTERISTICS (continued)

 $V_{BAT} = 3.6 \text{ V} \pm 5\%$, $T_J = 27^{\circ}C$ (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
		External resistor divider (XADJ2 = 1)	0.6		V _{IN}	
	Output voltage range	I ² C selectable in 25-mV steps (XADJ2 = 0)	0.9		3.3	V
V _{OUT}	DC output voltage accuracy		-2		3	%
	Power save mode (PSM) ripple voltage	I_{OUT} = 1 mA, PFM mode L = 2.2 µH, C _{OUT} = 20 µF		40		$\mathrm{mV}_{\mathrm{pp}}$
I _{OUT}	Output current range		0		1.2	А
2	High side MOSFET on-resistance	V _{IN} = 2.7 V		170		0
R _{DS(ON)}	Low side MOSFET on-resistance	V _{IN} = 2.7 V		120		mΩ
	High side MOSFET leakage current	V _{IN} = 5.8 V			2	•
I _{LEAK}	Low side MOSFET leakage current	V _{DS} = 5.8 V			1	μA
I _{LIMIT}	Current limit (high and low side MOSFET).	2.7 V < V _{IN} < 5.8 V		1.6		А
f _{SW}	Switching frequency		1.95	2.25	2.55	MHz
V _{FB}	Feedback voltage	XADJ = 1		600		mV
t _{SS}	Soft-start time	Time to ramp V_{OUT} from 5% to 95%, no load		750		μs
R _{DIS}	Internal discharge resistor at L2			250		Ω
L	Inductor		1.5	2.2		μH
	Output capacitor	Ceramic	10	22		μF
C _{OUT}	ESR of output capacitor			20		mΩ
DCDC3 (BL						
V _{IN}	Input voltage range	VIN_DCDC3 pin	2.7		V _{SYS}	V
I _{Q,SLEEP}	Quiescent current in SLEEP mode	No load, $V_{SYS} = 4 \text{ V}$, $T_A = 25^{\circ}\text{C}$		30	010	μA
Q,OLLLI		External resistor divider (XADJ3 = 1)	0.6		V _{IN}	
	Output voltage range	I ² C selectable in 25-mV steps (XADJ3 = 0)	0.9		1.5 ⁽³⁾	V
V _{OUT}	DC output voltage accuracy	$V_{IN} = V_{OUT} + 0.3 V \text{ to } 5.8 V;$ 0 mA ≤ I _{OUT} ≤ 1.2 A	-2		3	%
	Power save mode (PSM) ripple voltage	I _{OUT} = 1 mA, PFM mode L = 2.2 μH, C _{OUT} = 20 μF		40		$\mathrm{mV}_{\mathrm{pp}}$
I _{OUT}	Output current range		0		1.2	А
_	High side MOSFET on-resistance	V _{IN} = 2.7 V		170		
R _{DS(ON)}	Low side MOSFET on-resistance	V _{IN} = 2.7 V		120		mΩ
	High side MOSFET leakage current	V _{IN} = 5.8 V			2	
LEAK	Low side MOSFET leakage current	V _{DS} = 5.8 V			1	μA
I _{LIMIT}	Current limit (high and low side MOSFET).	2.7 V < V _{IN} < 5.8 V		1.6		А
f _{SW}	Switching frequency		1.95	2.25	2.55	MHz
V _{FB}	Feedback voltage	XADJ = 1		600		mV
t _{SS}	Soft-start time	Time to ramp V _{OUT} from 5% to 95%, no load		750		μs
R _{DIS}	Internal discharge resistor at L1, L2			250		Ω
L	Inductor		1.5	2.2		μH
•	Output capacitor	Ceramic	10	22		μF
C _{OUT}	ESR of output capacitor			20		mΩ
LDO1, LDO	02	· · ·				
V _{IN}	Input voltage range		1.8		5.8	V
		1				



SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

www.ti.com

ELECTRICAL CHARACTERISTICS (continued)

 $V_{BAT} = 3.6 \text{ V} \pm 5\%$, $T_J = 27^{\circ}C$ (unless otherwise noted)

	PARAMETER	TEST	CONDITIONS	MIN	TYP	MAX	UNIT
		LDO1, I ² C selectable	9	1.0		3.3	V
	Output voltage range	LDO2, I ² C selectable	9	0.9		3.3	v
	DC output voltage accuracy	I_{OUT} = 10 mA, V_{IN} > V_{OUT} + 200 mV, V_{OUT} > 0.9 V		-2		2	
V _{OUT}	Line regulation	V _{IN} = 2.7 V - 5.5 V, V I _{OUT} = 100 mA	/ _{OUT} = 1.2 V,	-1		1	
		I _{OUT} = 1 mA - 100 m. V _{IN} = 3.3 V	A, V _{OUT} = 1.2 V,	-1		1	%
	Load regulation	I _{OUT} = 0 mA - 1 mA, V _{IN} = 3.3 V	V _{OUT} = 1.2 V,	-2.5		2.5	
		Sleep state		0		1	
IOUT	Output current range	Active state		0		100	mA
I _{SC}	Short circuit current limit	Output shorted to GN	ND	100	250		mA
V _{DO}	Dropout voltage	I _{OUT} = 100 mA, V _{IN} =	: 3.3 V			200	mV
R _{DIS}	Internal discharge resistor at output				430		Ω
	Output capacitor	Ceramic			2.2		μF
C _{OUT}	ESR of output capacitor				20		mΩ
LS1/LDO3	& LS2/LDO4, CONFIGURED AS LDOs					1	
V _{IN}	Input voltage range			2.7		5.8	V
I _{Q,SLEEP}	Quiescent current in SLEEP mode	No load, V _{SYS} = 4 V,	T _A = 25°C		30		μA
	Output voltage range	LS1LDO3 = 1, LS2L $I^{2}C$ selectable	DO4 =1	1.5		3.3	V
.,	DC output voltage accuracy	I _{OUT} = 10 mA, V _{IN} > V	V _{OUT} + 200 mV, V _{OUT} > 1.8	-2		2	
V _{OUT}	Line regulation	V _{IN} = 2.7 V - 5.5 V, V I _{OUT} = 200 mA	/ _{OUT} = 1.8 V,	-1		1	%
	Load regulation	I _{OUT} = 1 mA - 200 m. V _{IN} = 3.3 V	A, V _{OUT} = 1.8 V,	-1		1	
		TPS65217A		0		200	
I _{OUT}	Output current range	TPS65217B		0		200	mA
		TPS65217C		0		400	
			TPS65217A	200	280		
I _{SC}	Short circuit current limit	Output shorted to GND	TPS65217B	200	280		mA
			TPS65217C	400	480		
V _{DO}	Dropout voltage	I _{OUT} = 200 mA, V _{IN} =	3.3 V			200	mV
R _{DIS}	Internal discharge resistor at output ⁽⁴⁾				375		Ω
	Output capacitor	Ceramic		8	10	12	μF
C _{OUT}	ESR of output capacitor				20		mΩ

(4) Can be factory disabled.



SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

www.ti.com

ELECTRICAL CHARACTERISTICS (continued)

 $V_{BAT} = 3.6 \text{ V} \pm 5\%$, $T_J = 27^{\circ}C$ (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNI
LS1/LDO3 &	LS2/LDO4, CONFIGURED AS LOAD SWI	TCHES				
V _{IN}	Input voltage range	LS1_VIN, LS2_VIN pins	1.8		5.8	V
R _{DS(ON)}	P-channel MOSFET on-resistance	V_{IN} = 1.8 V, over full temperature range		300	650	mΩ
SC	Short circuit current limit	Output shorted to GND	200	280		mA
R _{DIS}	Internal discharge resistor at output			375		Ω
0	Output capacitor	Ceramic	1	10	12	μF
C _{OUT}	ESR of output capacitor			20		mΩ
WLED BOOS	ST	-				
V _{IN}	Input voltage range		2.7		5.8	V
V _{OUT}	Max output voltage	I _{SINK} = 20 mA	32			V
V _{OVP}	Output over-voltage protection		37	38	39	V
R _{DS(ON)}	N-channel MOSFET on-resistance	V _{IN} = 3.6 V		0.6		Ω
ILEAK	N-channel leakage current	$V_{DS} = 25 \text{ V}, \text{ T}_{A} = 25^{\circ}\text{C}$		2		μA
I _{LIMIT}	N-channel MOSFET current limit			1.6	1.9	A
fsw	Switching frequency			1.125		MH
		V _{IN} = 3.6 V, 1% duty cycle setting		1.1		
INRUSH	Inrush current on start-up	V _{IN} = 3.6 V, 100% duty cycle setting		2.1		A
L	Inductor			18		μŀ
	Output capacitor	Ceramic		4.7		μF
C _{OUT}	ESR of output capacitor			20		m
WLED CURR	ENT SINK1, SINK2					
V _{SINK1,2}	Over-voltage protection threshold at ISINK1, ISINK2 pins				19	V
V _{DO, SINK1,2}	Current sink drop-out voltage	Measured from ISINK to GND		400		m∖
VISET1,2	ISET1, ISET2 pin voltage			1.24		V
- ,	WLED current range (ISINK1, ISINK2)		1		25	
		R _{ISET} = 130.0 kΩ		10		
		R _{ISET} = 86.6 kΩ		15		m/
	WLED sink current	$R_{ISET} = 64.9 \text{ k}\Omega$		20		
		$R_{\text{ISET}} = 52.3 \text{ k}\Omega$		25		
I _{SINK1,2}	DC current set accuracy	I _{SINK} = 5 mA to 25 mA, 100% duty cycle	-5		5	
	DC surrent matching	$\label{eq:Rset1} \begin{array}{l} R_{SET1}=52.3 \ k\Omega, \ I_{SINK}=25 \ m\text{A}, \\ V_{BAT}=3.6 \ V, \\ 100\% \ duty \ cycle \end{array}$	-5		5	%
	DC current matching	R_{SET1} = 130 kΩ, I_{SINK} = 10 mA, V_{BAT} = 3.6 V, 100% duty cycle	-5		5	
		FDIM[1:0] = 00		100		
c.		FDIM[1:0] = 01		200		
f _{PWM}	PWM dimming frequency	FDIM[1:0] = 10		500		Hz
		FDIM[1:0] = 11		1000		

SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

NSTRUMENTS

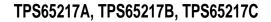
Texas

www.ti.com

ELECTRICAL CHARACTERISTICS (continued)

 V_{BAT} = 3.6 V ±5%, T_{J} = 27°C (unless otherwise noted)

	PARAMETER	TEST	CONDITIONS	MIN	TYP	MAX	UNIT	
ANALOG N	MULTIPLEXER							
	Gain, VBAT, VSYS	V _{BAT} /V _{OUT,MUX} ; V _{SYS} /	V _{OUT,MUX}		3			
	Gain, VTS, MUX_IN	V _{TS} /V _{OUT,MUX} ; V _{MUX_IN} /V _{MUX_OUT}			1		V/V	
			ICHRG[1:0] = 00b		7.575			
g			ICHRG[1:0] = 01b		5.625		V/A	
	Gain, VICHARGE	V _{OUT,MUX} /V _{ICHARGE}	ICHRG[1:0] = 10b		4.500			
			ICHRG[1:0] = 11b		3.214			
V _{OUT}	Buffer headroom	V _{SYS} - V _{MUX,OUT} , V _{SYS} = 3.6 V, MUX[2:0] = 101 (V _{MUX,IN} - V _{MUX,OUT})/V _{MUX,IN} > 1%			0.7	1	V	
R _{OUT}	Output Impedance				180		Ω	
I _{LEAK}	Leakage current	MUX[2:0] = 000 (HiZ) V _{MUX} = 2.25 V),			1	μA	
	VELS AND TIMING CHARACTERISTICS , PB_IN, PGOOD, LDO_PGOOD, PWR_EN, r	NINT, NWAKEUP, NRES	SET)					
P _{GTH}	PGOOD comparator treshold,	Output voltage falling (not tested in product	, % of set voltage tion)		90		%	
GIH	All DCDC converters and LDOs	Output voltage rising (not production tested	d)	95			%	
P _{GDG}	PGOOD deglitch time	Output voltage falling	, DCDC1, 2, 3	2		4	ms	
GDG		Output voltage falling	, LDO1, 2, 3, 4	1		2	2 115	
P _{GDLY}	PGOOD delay time	PGDLY[1:0] = 00			20			
		PGDLY[1:0] = 01			100		ms	
		PGDLY[1:0] = 10			200		1115	
		PGDLY[1:0] = 11			400			
t _{HRST}	PB-IN "Hard Reset Detect" time	Not tested in product	ion		8		s	
	PB_IN pin deglitch time	Not tested in production			50			
t _{DG}	PWR_EN pin deglitch time	Not tested in product	ion		50		ms	
	nRESET pin deglitch time	Not tested in production			30]	
_	PB_IN internl pull-up resistor				100			
R _{PULLUP}	nRESET internl pull-up resistor				100		kΩ	
V _{IH}	High level input voltage PB_IN, SCL, SDA, PWR_EN, nRESET			1.2		V _{IN}	V	
V _{IL}	Low level input voltage PB_IN, SCL, SDA, PWR_EN, nRESET			0		0.4	V	
I _{BIAS}	Input bias current PB_IN, SCL, SDA				0.01	1	μA	
		nINT, nWAKEUP	I _O = 1 mA			0.3		
V _{OL}	Output low voltage	PGOOD, LDO_PGOOD	I _O = 1 mA			0.3	V	
V _{OH}	Output high voltage	PGOOD, LDO_PGOOD	$I_0 = 1 \text{ mA}$	V _{IO} - 0.3			V	
I _{LEAK}	Pin leakage current nINT, nWAKEUP	Pin pulled up to 3.3-\	/ supply			0.2	μA	
	I ² C slave address				0x24h			
OSCILLAT	OR							
fass	Oscillator frequency				9		MHz	
fosc Frequency accuracy		$T_A = -40^{\circ}C$ to $105^{\circ}C$		-10		10	%	
OVER TEN	IPERATURE SHUTDOWN							
т –	Over temperature shutdown	Increasing junction te	emperature		150		°C	
T _{OTS}	Hysteresis	Decreasing junction t	emperature		20		°C	





SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

MODES OF OPERATION

- **OFF** In OFF mode the PMIC is completely shut down with the exception of a few circuits to monitor the AC, USB, and push-button input. All power rails are turned off and the registers are reset to their default values. The I²C communication interface is turned off. This is the lowest-power mode of operation. To exit OFF mode one of the following wake-up events has to occur:
 - The push button input is pulled low.
 - The USB supply is connected (positive edge).
 - The AC adapter is connected (positive edge).

To enter OFF state, set the OFF bit in the STATUS register to '1' and then pull the PWR_EN pin low. Please note that in normal operation OFF state can only be entered from ACTIVE state. Whenever a fault occurs during operation such as thermal shutdown, power-good fail, under voltage lockout, or PWR_EN pin timeout, all power rails are shut-down and the device goes to OFF state. The device will remain in OFF state until the fault has been removed and a new power-up event has occurred.

ACTIVE This is the typical mode of operation when the system is up and running. All DCDC converters, LDOs, load switches, WLED driver, and battery charger are operational and can be controlled through the I²C interface.

After a wake-up event the PMIC enables all rails not controlled by the sequencer and pulls the nWAKEUP pin low to signal the event to the host processor. The device will enter ACTIVE state only if the host asserts the PWR_EN pin within 5 seconds after the wake-up event. Otherwise it will enter OFF state. In ACTIVE state the sequencer is triggered to bring up the remaining power rails. The nWAKEUP pin returns to HiZ mode after PWR_EN pin has been asserted. A timing diagram is shown in Figure 2. ACTIVE state can also be entered from SLEEP state directly by pulling the PWR_EN pin high. See SLEEP state description for details.

To exit ACTIVE mode the PWR_EN pin needs to be pulled low.

SLEEP SLEEP state is a low-power mode of operation intended to support system standby. Typically all power rails are turned off with the exception of LDO1 and the registers are reset to their default values. LDO1 remains operational but can support only limited amount of current (100 μA typical).

To enter SLEEP state, set the OFF bit in the STATUS register to '0' (default) and then pull the PWR_EN pin low. All power rails controlled by the power-down sequencer will be shut down and after 1s the device enters SLEEP state. If LDO1 was enabled in ACTIVE state, it will remain enabled in SLEEP sate. All rails not controlled by the power-down sequencer will also maintain state. The battery charger will remain active for as long as either USB or AC supply is connected to the device. Please note that all register values are reset as the device enters in SLEEP state, including charger parameters.

The device enters ACTIVE state after it detects a wake-up event as described in the sections above. In addition, the device transitions from SLEEP to ACTIVE state when the PWR_EN pin is pulled high. This allows the system host to switch the PMIC between ACTIVE to SLEEP state by control of the PWR_EN pin only.

RESET The TPS65217 can be reset by either pulling the nRESET pin low or holding the PB_IN pin low for more than 8 seconds. All rails will be shut-down by the sequencer and all register values are reset to their default values. Rails not controlled by the sequencer are shut down immediately. The device remains in this state for as long as the reset pin is held low and the nRESET pin must be high to exit RESET state. However, the device will remain in RESET state for a minimum of 1s before it returns to ACTIVE state. As described in the ACTIVE section, the PWR_EN pin must be asserted within 5 seconds of nWAKEUP-pin-low to enter ACTIVE state. Please note that the RESET function power-cycles the device and only shuts down the output rails temporarily. Resetting the device does not lead to OFF state.

If the PB_IN pin is kept low for an extended amount of time, the device will continue to cycle between ACTIVE and RESET state, entering RESET every 8 s.

SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

Texas Instruments

www.ti.com

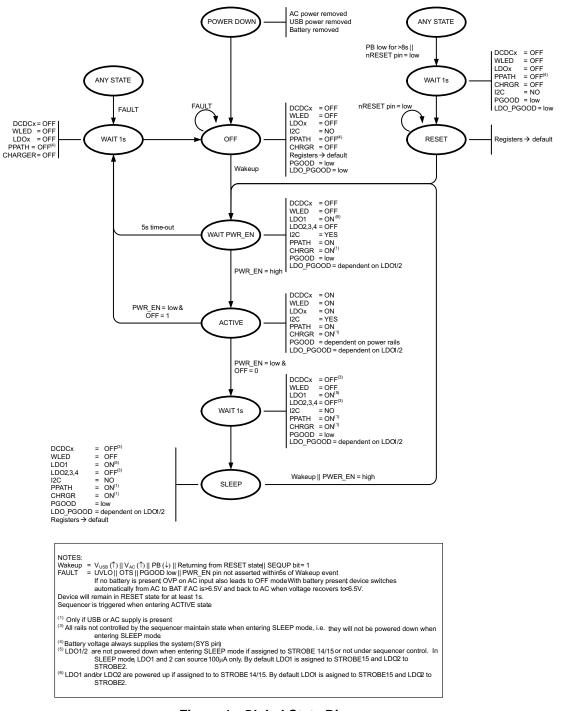


Figure 1. Global State Diagram

Copyright © 2011–2012, Texas Instruments Incorporated



SLVSB64E-NOVEMBER 2011-REVISED JULY 2012

WAKE-UP AND POWER UP SEQUENCING

The TPS65217 has a pre-defined power-up / power-down sequence which in a typical application does not need to be changed. However, it is possible to define custom sequences under l^2C control. The power-up sequence is defined by strobes and delay times. Each output rail is assigned to a strobe to determine the order in which the rails are enabled and the delay times between strobes are selectable in a range from 1 ms to 10 ms.

NOTE

Although the user can modify the power-up and power-down sequence through the SEQx registers, those registers are reset to default values when the device enters SLEEP, OFF or RESET state. In practice this means that the power-up sequence is fixed and a other-than-default power-down sequence has to be written every time the device is powered up.

Custom power-up/down sequences can be checked out in ACTIVE mode (PWR_EN pin high) by using the SEQUP and SEQDWN bits. To change the power-up default values, please contact the factory.

Power-Up Sequencing

When the main power-up sequence is initiated, STROBE1 occurs and any rail assigned to this strobe will be enabled. After a delay time of DLY1 STROBE2 occurs and the rail assigned to this strobe is powered up. The sequence continues until all strobes have occurred and all DLYx times have been executed.

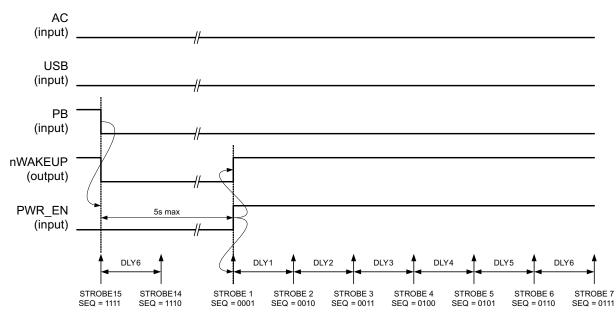


Figure 2. Power-Up Sequence is Defined by Strobes and Delay Times. In This Example Push-Button Low is the Power-Up Event.

The default power-up sequence can be changed by writing to the SEQ1-6 registers. Strobes are assigned to rails by writing to the SEQ1-4 registers. A rail can be assigned to only one strobe but multiple rails can be assigned to the same strobe. Delays between strobes are defined in registers SEQ5 and SEQ6.

SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012



www.ti.com

The power up sequence is executed if one of the following events occurs:

From OFF State:

- Push-button is pressed (falling edge on PB_IN) OR
- USB voltage is asserted (rising edge on USB) OR
- AC adaptor is inserted (rising edge on AC) AND
- PWR_EN pin is asserted (pulled high) AND
- Device is not in Under Voltage Lockout (UVLO) or Over Temperature Shutdown (OTS).

The PWR_EN pin is level sensitive (opposed to edge sensitive) and it makes no difference if it is asserted before or after the above power-up events. However, it must be asserted within 5 seconds of the power-up event otherwise the power-down sequence will be triggered and the device enters either OFF state.

From SLEEP State:

- Push-button is pressed (falling edge on PB_IN) OR
- USB voltage is asserted (rising edge on USB) OR
- AC adaptor is inserted (rising edge on AC) AND
- Device is not in Under Voltage Lockout (UVLO) or Over Temperature Shutdown (OTS) OR
- PWR_EN pin is asserted (pulled high).

In SLEEP state the power-up sequence can be triggered by asserting the PWR_EN pin only and the push-button press or USB/AC assertion are not required.

From ACTIVE State:

The sequencer can be triggered any time by setting the SEQUP bit of the SEQ6 register high. The SEQUP bit is automatically cleared after the sequencer is done.

Rails that are not assigned to a strobe (SEQ=0000b) are not affected by power-up and power-down sequencing and will remain in their current ON/OFF state regardless of the sequencer. Any rail can be enabled/disabled at any time by setting the corresponding enable bit in the ENABLE register with the only exception that the ENABLE register cannot be accessed while the sequencer is active. Enable bits always reflect the current enable state of the rail, i.e. the sequencer will set/reset the enable bits for the rails under its control. Also, whenever faults occur that shut-down the power-rails, the corresponding enable bits will be reset.

Power-Down Sequencing

By default, power-down sequencing follows the reverse power-up sequence. When the power-down sequence is triggered, STROBE7 occurs first and any rail assigned to STROBE7 will be shut down. After a delay time of DLY6, STROBE6 occurs and any rail assigned to it will be shut down. The sequence continues until all strobes have occurred and all DLYx times have been executed.

In some applications it is desired to shut down all rails simultaneously with no delay between rails. Set the INSTDWN bit in the SEQ6 register to bypass all delay times and shut-down all rails simultaneously when the power-down sequence is triggered.

A power-down sequence is executed if one of the following events occurs:

- The SEQDWN bit is set.
- The PWR_EN pin is pulled low.
- The push-button is pressed for > 8 s.
- The nRESET pin is pulled low.
- A fault occurs in the IC (OTS, UVLO, PGOOD failure).
- The PWR_EN pin is not asserted (pulled high) within 5 seconds of a power-up event and the OFF bit is set to 1.

When transitioning from ACTIVE to OFF state, any rail not controlled by the sequencer is shut down after the power-down sequencer has finished. When transitioning from ACTIVE to SLEEP state any rail not controlled by the power-down sequencer will maintain state. This allows keeping selected power rails up in SLEEP state.



SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

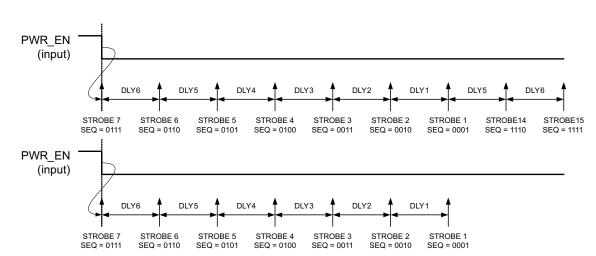


Figure 3. Power-Down Sequence Follows Reverse Power-Up Sequence. TOP: Power-down sequence from ON state to OFF state (all rails are turned OFF). BOTTOM: Power-down sequence from ON state to SLEEP state. STROBE14 and 15 are omitted to allow LDO1/2 to remain ON.

Special Strobes (STROBE 14 and 15)

STROBE 14 and STORBE 15 are not assigned to the main sequencer but used to control rails that are 'alwayson', i.e. are powered up as soon as the device exits OFF state and remain ON in SLEEP state. STROBE 14/15 options are available only for LDO1 and LDO2 and not for any of the other rails.

STROBE 14 occurs as soon as the push-button is pressed or the USB or AC adaptor is connected to the device. After a delay time of DLY6 STROBE 15 occurs. LDO1 and LDO2 can be assigned to either strobe and therefore can be powered up in any order (contact factory for details - default settings must be factory programmed since all registers are reset in SLEEP mode).

When a power-down sequence is initiated, STOBE 15 and STOBE 14 will occur only if the OFF bit is set. Otherwise both strobes are omitted and LDO1 and LDO2 will maintain state.

POWER GOOD

Power-good is a signal used to indicate if an output rail is in regulation or at fault. Internally, all power-good signals of the enabled rails are monitored at all times and if any of the signals goes low, a fault is declared. All PGOOD signals are internally deglitched. When a fault occurs, all output rails are powered down and the device enters OFF state.

The TPS65217 has two PGOOD outputs, one dedicated to LDO1 and 2 (LDO_PGOOD), and one programmable output (PGOOD). The following rules apply to both outputs:

- The power-up default state for PGOOD/LDO_PGOOD is low. When all rails are disabled, PGOOD and LDO_PGOOD outputs are both low.
- Only enabled rails are monitored. Disabled rails are ignored.
- Power-good monitoring of a particular rail starts 5ms after the rail has been enabled. It is continuously monitored thereafter. This allows the rail to power-up.
- PGOOD and LDO_PGOOD outputs are delayed by the PGDLY (20 ms default) after the sequencer is done.
- If an enabled rail goes down due to a fault (output shorted, OTS, UVLO), PGOOD and/or LDO_PGOOD is declared low, and all rails are shut-down.
- If the user disables a rail (either manually or through sequencer), it has no effect on the PGOOD or LDO_PGOOD pin.
- If the user disables all rails (either manually or through sequencer) PGOOD and/or LDO_PGOOD will be pulled low.

Copyright © 2011–2012, Texas Instruments Incorporated



SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

LDO1, LDO2 PGOOD (LDO_PGOOD)

LDO_PGOOD is a push-pull output which is driven to high-level whenever LDO1 and/or LDO2 are enabled and in regulation. It is pulled low when both LDOs are disabled or at least one is enabled but has encountered a fault. A typical fault is an output short or over-current condition. In normal operation LDO_PGOOD is high in ACTIVE and SLEEP state and low in RESET or OFF state.

Main PGOOD (PGOOD)

The main PGOOD pin has similar functionality to the LDO_PGOOD pin except that it monitors DCDC1, DCDC2, DCDC3, and LS1/LDO3, LS2/LDO4 if they are configured as LDOs. If LS1/LDO3 and/or LS2/LDO4 are configured as load switches, their respective PGODD status is ignored. In addition, the user can choose to also monitor LDO1 and LDO2 by setting the LDO1PGM and LDO2PGM bits in the DEFPG register low. By default, LDO1 and LDO2 PGOOD status does not affect the PGOOD pin (mask bits are set to 1 by default). In normal operation PGOOD is high in ACTIVE state but low in SLEEP, RESET or OFF state.

In SLEEP mode and WAIT PWR_EN state, PGOOD pin is forced low. PGOOD is pulled high after entering ACTIVE mode, the power sequencer done, and the PGDLY expired. This function can be disabled by the factory.

Load Switch PGOOD

If either LS1/LDO3 or LS2/LDO4 are configured as load switches their respective PGOOD signal is ignored by the system. An over-current or short condition will not affect the PGOOD pin or any of the power rails unless the power dissipation leads to thermal shut-down.

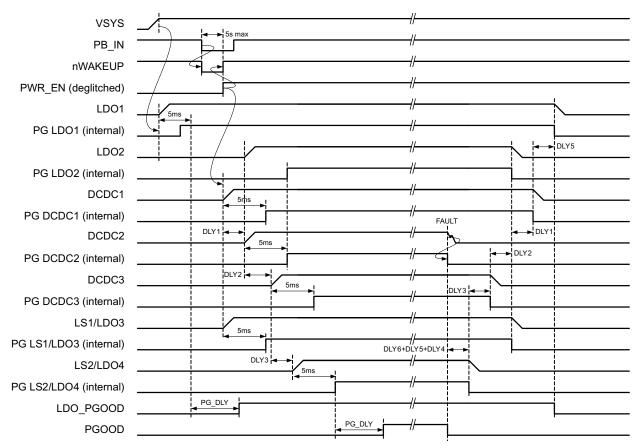
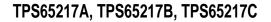


Figure 4. Default Power-Up Sequence. Also shown is the power-down sequence for the case of a short on DCDC2 output.



EXAS

INSTRUMENTS

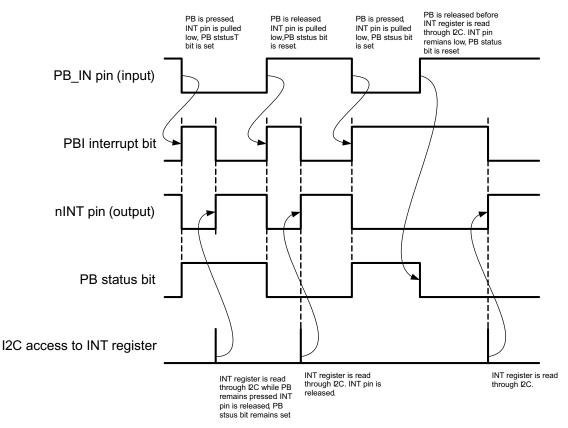
SLVSB64E-NOVEMBER 2011-REVISED JULY 2012

PUSH BUTTON MONITOR (PB_IN)

The TPS65217 has an active-low push-button input which is typically connected to a momentary switch to ground. The PB_IN input has a 50ms deglitch time and an internal pull-up resistor to an always-on supply. The push button monitor is used to:

- Power-up the device from OFF or SLEEP mode upon detecting a falling edge on PB_IN.
- Power cycle the device when PB_IN is held low for > 8 s.

Both functions are described in the Modes of Operation section. A change in push-button status (PB_IN transitions high to low or low to high) is signaled to the host through the PBI interrupt bit in the INT register. The current status of the interrupt can be checked by reading the PB status bit in the STATUS register. A timing diagram for the push-button monitor is shown in Figure 5.





g

nWAKEUP PIN (nWAKEUP)

The nWAKEUP pin is an open drain, active-low output that is used to signal a wakeup event to the system host. This pin is pulled low whenever the device is in OFF or SLEEP state and detects a wakeup event as described in the Modes of Operation section. The nWAKEUP pin is delayed 50ms over the power-up event and will remain low for 50 ms after the PWR_EN pin has been asserted. If the PWR_EN pin is not asserted within 5 seconds of the power-up event, the device will shut down and enter OFF state. In ACTIVE mode the nWAKEUP pin is always high. The timing diagram for the nWAKEUP pin is shown in Figure 6.

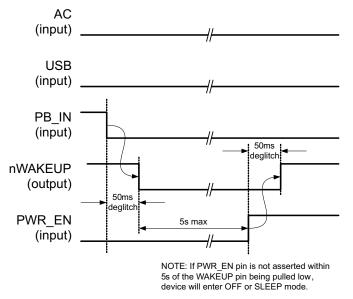


SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

POWER ENABLE PIN (PWR_EN)

The PWR_EN pin is used to keep the unit in ACTIVE mode once it has detected a wakeup event as described in the Modes of Operation section. If the PWR_EN pin is not asserted within 5 seconds of the nWAKEUP pin being pulled low, the device will shut down the power and enter either OFF or SLEEP mode, depending on the OFF bit in the STATUS register. The PWR_EN pin is level sensitive, meaning that it may be pulled high before the wakeup event.

The PWR_EN pin may also be used to toggle between ACTIVE and SLEEP mode. See SLEEP mode description for details.





RESET PIN (nRESET)

When the nRESET pin is pulled low, all power rails, including LDO1 and LDO2 are powered down and default register settings are restored. The device will remain powered down as long as the nRESET pin is held low but for a minimum of 1 second. Once the nRESET pin is pulled high the device enters ACTIVE mode and the default power-up sequence will execute. See RESET section for more information.

INTERRUPT PIN (nINT)

The interrupt pin is used to signal any event or fault condition to the host processor. Whenever a fault or event occurs in the IC the corresponding interrupt bit is set in the INT register, and the open-drain output is pulled low. The nINT pin is released (returns to HiZ state) and fault bits are cleared when the INT register is read by the host. However, if a failure persists, the corresponding INT bit remains set and the nINT pin is pulled low again after a maximum of $32 \,\mu s$.

Interrupt events include pushbutton pressed/released, USB and AC voltage status change.

The MASK bits in the INT register are used to mask events from generating interrupts. The MASK settings affect the nINT pin only and have no impact on protection and monitor circuits themselves. Note that persisting event conditions such as ISINK enabled shutdown can cause the nINT pin to be pulled low for an extended period of time which can keep the host in a loop trying to resolve the interrupt. If this behavior is not desired, set the corresponding mask bit after receiving the interrupt and keep polling the INT register to see when the event condition has disappeared. Then unmask the interrupt bit again.

22 Submit Documentation Feedback

Copyright © 2011–2012, Texas Instruments Incorporated



SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

ANALOG MULTIPLEXER

The TPS65217 provides an analog multiplexer that allow access to critical system voltages such as:

- battery voltage (VBAT)
- system voltage (VSYS)
- temperature sense voltage (VTS), and
- VICHARGE, a voltage proportional to the charging current.

In addition one external input is available to monitor an additional system voltage. VBAT and VSYS are divided down by a factor of 1:3 to be compatible with input voltage range of the ADC that resides on the system host side. The output of the MUX is buffered and can drive a maximum of 1-mA load current.

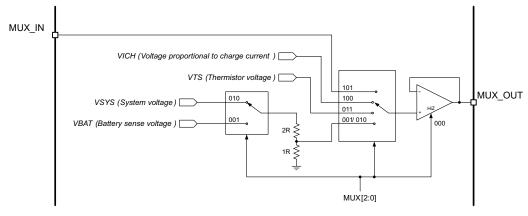


Figure 7. Analog Multiplexer

BATTERY CHARGER AND POWER PATH

TPS65217 provides a linear charger for Li+ batteries and a triple system-power path targeted at space-limited portable applications. The power path allows simultaneous and independent charging of the battery and powering of the system. This feature enables the system to run with a defective or absent battery pack and allows instant system turn-on even with a totally discharged battery. The input power source for charging the battery and running the system can be either an AC adapter or a USB port. The power path prioritizes the AC input over the USB and both over battery input to reduce the number of charge and discharge cycles on the battery. Charging current is automatically reduced when system load increases and if the system load exceeds the maximum current of the USB or AC adapter supply, the battery will supplement, meaning that the battery will be discharged to supply the remaining current. A block diagram of the power path is shown in Figure 8 and an example of the power path management function is shown in Figure 9.



SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

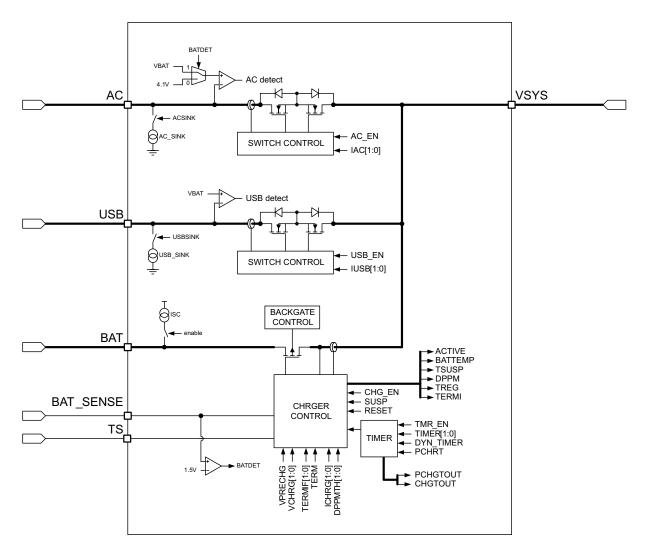


Figure 8. Block Diagram of the Power Path and Battery Charger



SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

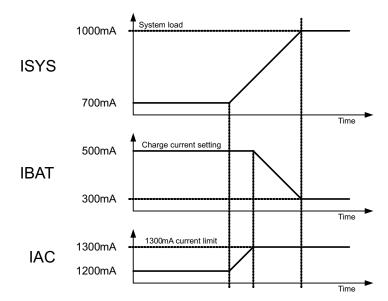


Figure 9. Power Path Management. In this example the AC input current limit is set to 1300 mA, battery charge current is 500 mA and system load is 700 mA. As the system load increases to 1000 mA battery charging current is reduced to 300 mA to maintain AC input current of 1300 mA.

Detection thresholds for AC and USB inputs are a function of the battery voltage and three basic use-cases must be considered:

Shorted or Absent Battery ($V_{BAT} < 1.5 V$)

AC or USB inputs are valid and the chip powers up if V_{AC} or V_{USB} rises above 4.3 V. Once powered up, the input voltage can drop to the $V_{UVLO} + V_{OFFSET}$ level (e.g. 3.3 V + 200 mV) before the chip powers down.

AC input is prioritized over USB input, i.e. if both inputs are valid, current is pulled from the AC input and not USB. If both, AC and USB supplies are available, the power-path switches to USB input if V_{AC} drops below 4.1 V (fixed threshold).

Note that the rise time of V_{AC} and V_{USB} must be less than 50 ms for the detection circuits to operate properly. If the rise time is longer than 50 ms, the IC may fail to power up.

The linear charger periodically applies a 10-mA current source to the BAT pin to check for the presence of a battery. This will cause the BAT terminal to float up to > 3 V which may interfere with AC removal detection and the ability to switch from AC to USB input. For this reason, it is not recommended to use both AC and USB inputs when the battery is absent.

Dead Battery (1.5 V < V_{BAT} < V_{UVLO})

Functionality is the same as for the shorted battery case. The only difference is that once AC is selected as the input and the power-path does not switch back to USB as V_{AC} falls below 4.1 V.

Good Battery (V_{BAT} > V_{UVLO})

AC and USB supplies are detected when the input is 190 mV above the battery voltage and are considered absent when the voltage difference to the battery is less than 125 mV. This feature ensures that AC and USB supplies are used whenever possible to save battery life. USB and AC inputs are both current limited and controlled through the PPATH register.

In case AC or USB is not present or blocked by the power path control logic (e.g. in OFF state), the battery voltage always supplies the system (SYS pin).

Copyright © 2011–2012, Texas Instruments Incorporated

SLVSB64E-NOVEMBER 2011-REVISED JULY 2012

AC and USB Input Discharge

AC and USB inputs have 90- μ A internal current sinks which are used to discharge the input pins to avoid false detection of an input source. The AC sink is enabled when USB is a valid supply and V_{AC} is below the detection threshold. Likewise, the USB sink is enabled when AC is a valid supply and V_{USB} is below the detection limit. Both current sinks can be forced OFF by setting the [ACSINK, USBSINK] bits to 11b. Both bits are located in register 0x01 (PPATH).

EXAS

NSTRUMENTS

www.ti.com

NOTE

[ACSINK, USBSINK] = 01b and 10b combinations are not recommended as these may lead to unexpected enabling and disabling of the current sinks.

BATTERY CHARGING

When the charger is enabled (CH_EN bit set to 1) it first checks for a short-circuit on the BAT pin by sourcing a small current and monitoring the BAT voltage. If the voltage on the BAT pin rises above $V_{BAT(SC)}$, a battery is present and charging can begin. The battery is charged in three phases: pre-charge, constant current fast charge (current regulation) and a constant voltage charge (voltage regulation). In all charge phases, an internal control loop monitors the IC junction temperature and reduces the charge current if an internal temperature threshold is exceeded. Figure 10 shows a typical charging profile.

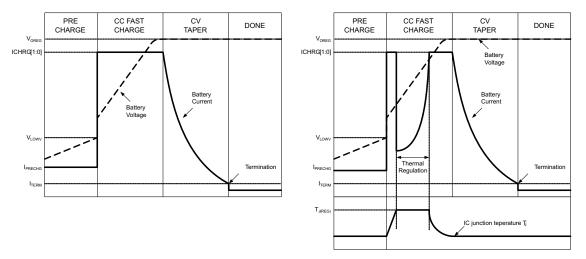


Figure 10. LEFT: Typical charge current profile with termination enabled. RIGHT: Modified charging profile with thermal regulation loop active and termination enabled.

In the pre-charge phase, the battery is charged at a current of IPRECHG which is typically 10% of the fastcharge current rate. The battery voltage starts rising. Once the battery voltage crosses the V_{LOWV} threshold, the battery is charged at a current of I_{CHG} . The battery voltage continues to rise. When the battery voltage reaches V_{OREG} , the battery is held at a constant value of V_{OREG} . The battery current now decreases as the battery approaches full charge. When the battery current reaches I_{TERM} , the TERMI flag in register CHGCONFIGO is set to 1. To avoid false termination when the DPM or thermal loop kicks in, termination is disabled when either loop is active.

The charge current cannot exceed the input current limit of the power path minus the load current on the SYS pin because the power-path manager will reduce the charge current to support the system load if the input current limit is exceeded. Whenever the nominal charge current is reduced by action of the power path manger, the DPM loop, or the thermal loop the safety timer is clocked with half the nominal frequency to extend the charging time by a factor of 2.

Precharge

The pre-charge current is pre-set to a factor of 10% of the fast-charge current ICHRG[1:0] and cannot be changed by the user.



SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

www.ti.com

Charge Termination

When the charging current drops below the termination current threshold, the charger is turned off. The value of the termination current threshold can be set in register CHGCONFIG3 using bits TERMIF[1:0]. The termination current has a default setting of 7.5% of the ICHRG[1:0] setting.

Charge termination is disabled by default and can be enabled by setting the TERM bit or the CHGCONFIG1 register to 1. When termination is disabled, the device goes through the pre-charge, fast-charge and CV phases, then remains in the CV phase. The charger behaves like an LDO with an output voltage equal to V_{OREG} , able to source current up to I_{CHG} or I_{IN-MAX} , whichever is less. Battery detection is not performed.

NOTE

Termination current threshold is not a tightly controlled parameter. Using the lowest setting (2.5% of nominal charge current) is not recommended because the minimum termination current can be very close to 0. Any leakage on the battery-side may cause the termination not to trigger and charging to time-out eventually.

Battery Detection and Recharge

Whenever the battery voltage falls below V_{RCH} , $I_{BAT(DET)}$ is pulled from the battery for a duration t_{DET} to determine if the battery has been removed. If the voltage on the BAT pin remains above V_{LOWV} , it indicates that the battery is still connected. If the charger is enabled (CH_EN = 1), a new battery charging cycle begins.

If the BAT pin voltage falls below V_{LOWV} in the battery detection test, it indicates that the battery has been removed. The device then checks for battery insertion: it turns on the charging path and sources I_{PRECHG} out of the BAT pin for duration t_{DET} . If the voltage does not rise above V_{RCH} , it indicates that a battery has been inserted, and a new charge cycle can begin. If, however, the voltage does rise above V_{RCH} , it is possible that a fully charged battery has been inserted. To check for this, $I_{BAT(DET)}$ is pulled from the battery for t_{DET} and if the voltage falls below V_{LOWV} , no battery is present. The battery detection cycle continues until the device detects a battery or the charger is disabled.

When the battery is removed from the system the charger will also flag a BATTEMP error indicating that the TS input is not connected to a thermistor.

Safety Timer

The TPS65217 hosts internal safety timer for the pre-charge and fast-charge phases to prevent potential damage to either the battery or the system. The default fast-charge time can be changed in register CHGCONFIG1 and the precharge time in CHGCONFIG3. The timer functions can be disabled by resetting the TMR_EN bit of the CHGCONFIG1 register to 0. Note that both timers are disabled when charge termination is disabled (TERM = 0).

Dynamic Timer Function

Under some circumstances the charger current is reduced to react to changes in the system load or junction temperature. The two events that can reduce the charging current are:

- The system load current increases, and the DPM loop reduces the available charging current.
- The device has entered thermal regulation because the IC junction temperature has exceeded T_{J(REG)}.

In each of these events, the timer is clocked with half frequency to extend the charger time by a factor of 2 and charger termination is disabled. Normal operation resumes after IC junction temperature has cooled off and/or the system load drops to a level where enough current is available to charge the battery at the desired charge rate. This feature is enabled by default and can be disabled by resetting the DYNTMR bit in the CHGCONFIG2 register to 0. A modified charge cycle with the thermal loop active is shown in Figure 10.

Timer Fault

A timer fault occurs if:

- If the battery voltage does not exceed V_{LOWV} in time t_{PRECHG} during pre-charging.
- If the battery current does not reach I_{TERM} in fast charge before the safetimer expires. Fast-charge time is
 measured from the beginning of the fast charge cycle.

Copyright © 2011–2012, Texas Instruments Incorporated



SLVSB64E – NOVEMBER 2011–REVISED JULY 2012

www.ti.com

The fault status is indicated by CHTOUT and PCHTOUT bits in CHGCONFIG0 register. Timeout faults are cleared and a new charge cycle is started when either USB or AC supplies are connected (rising edge of V_{USB} or V_{AC}), the charger RESET bit is set to 1 in the CHGCONFIG1 register, or the battery voltage drops below the recharge threshold V_{RCH} .

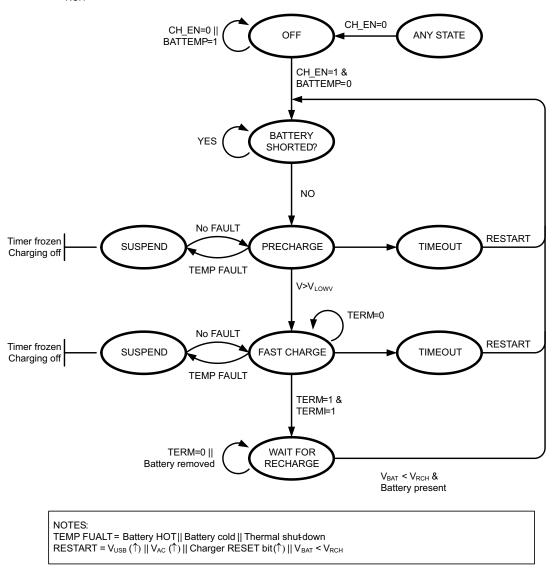


Figure 11. State Diagram of Battery Charger

Battery Pack Temperature Monitoring

The TS pin of the TPS65217 connects to the NTC resistor in the battery pack. During charging, if the resistance of the NTC indicates that the battery is operating outside the limits of safe operation, charging is suspended and the safety timer value is frozen. When the battery pack temperature returns to a safe value, charging resumes with the current timer setting.

By default, the device is setup to support a 10 k Ω the NTC with a B-value of 3480. The NTC is biased through a 7.35-k Ω internal resistor connected to the BYPASS rail (2.25 V) and requires an external 75-k Ω resistor parallel to the NTC to linearize the temperature response curve.

TPS65217 supports two different temperature ranges for charging, 0°C to 45°C and 0°C to 60°C which can be selected through the TRANGE bit in register CHCONFIG3.



SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

NOTE

The device can be configured to support a 100-k Ω NTC (B = 3960) by setting the the NTC_TYPE bit in register CHGCONFIG1 to 1. However it is not recommended to do so. In sleep mode the charger continues charging the battery but all register values are reset to default values, therefore the charger would get wrong temperature information. If 100 k Ω NTC setting is required, please contact the factory.

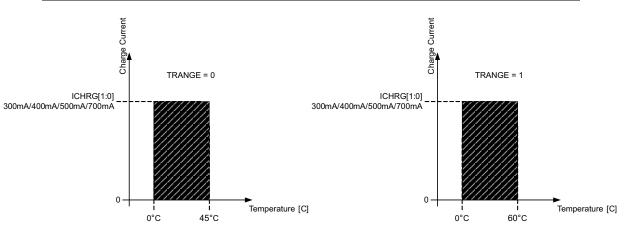


Figure 12. Charge Current as a Function of Battery Temperature

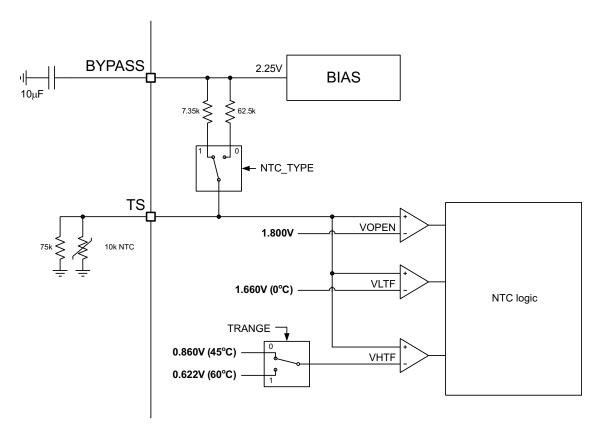


Figure 13. NTC Bias Circuit

SLVSB64E – NOVEMBER 2011 – REVISED JULY 2012



www.ti.com

DCDC CONVERTERS

Operation

The TPS65217 step down converters typically operate with 2.25-MHz fixed frequency pulse width modulation (PWM) at moderate to heavy load currents. At light load currents the converter automatically enters Power Save Mode and operates in PFM (Pulse Frequency Modulation).

During PWM operation the converter use a unique fast response voltage mode controller scheme with input voltage feed-forward to achieve good line and load regulation allowing the use of small ceramic input and output capacitors. At the beginning of each clock cycle the high-side MOSFET is turned on. The current flows from the input capacitor via the high-side MOSFET through the inductor to the output capacitor and load. During this phase, the current ramps up until the PWM comparator trips and the control logic turns off the switch. The current limit comparator will also turn off the switch in case the current limit of the high-side MOSFET switch is exceeded. After a dead time preventing shoot through current, the low-side MOSFET rectifier is turned on and the inductor current ramps down. The current flows now from the inductor to the output capacitor and to the load. It returns back to the inductor through the low-side MOSFET rectifier.

The next cycle turns off the low-side MOSFET rectifier and turs on the on the high-side MOSFET.

The DC-DC converters operate synchronized to each other, with converter 1 as the master. A 120° phase shift between DCDC1/DCDC2 and DCDC2/DCDC3 decreases the combined input RMS current at the VIN_DCDCx pins. Therefore smaller input capacitors can be used.

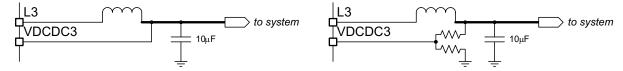
Output Voltage Setting

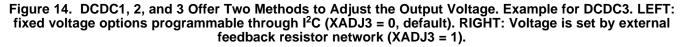
The output voltage of the DCDCs can be set in two different ways:

- As a fixed voltage converter where the voltage is defined in register DEFDCDCx.
- An external resistor network. Set the XADJx bit in register DEFDCDCx register and calculate the output voltage with the following formula:

$$V_{OUT} = V_{REF} \times (1 + \frac{R_1}{R_2})$$

Where V_{REF} is the feedback voltage of 0.6 V. It is recommended to set the total resistance of R1 + R2 to less than 1 M Ω . Shield the VDCDC1, VDCDC2, and VDCDC3 lines from switching nodes and inductor L1, L2, and L3 to prevent coupling of noise into the feedback pins.





Power Save Mode and Pulse Frequency Modulation (PFM)

By default all three DCDC converter enter Pulse Frequency Modulation (PFM) mode at light loads and fixedfrequency Pulse Width Modulation (PWM) mode at heavy loads. In some applications it is desirable to force PWM operation even at light loads which can be accomplished by setting the PFM_ENx bits in the DEFSLEW registers to 0 (default setting is 1). In PFM mode the converter skips switching cycles and operates with reduced frequency with a minimum quiescent current to maintain high efficiency. The converter will position the output voltage typically +1% above the nominal output voltage. This voltage positioning feature minimizes voltage drops caused by a sudden load step.

The transition from PWM to PFM mode occurs once the inductor current in the low-side MOSFET switch becomes 0.



During the Power Save Mode the output voltage is monitored with a PFM comparator. As the output voltage falls below the PFM comparator threshold of V_{OUT} - 1%, the device starts a PFM current pulse. For this the high-side MOSFET will turn on and the inductor current ramps up. Then it is turned off and the low-side MOSFET switch turns on until the inductor current becomes 0 again.

The converter effectively delivers a current to the output capacitor and the load. If the load is below the delivered current the output voltage will rise. If the output voltage is equal or higher than the PFM comparator threshold, the device stops switching and enters a sleep mode with typically 15- μ A current consumption. In case the output voltage is still below the PFM comparator threshold, further PFM current pulses will be generated until the PFM comparator threshold is reached. The converter starts switching again once the output voltage drops below the PFM comparator threshold.

With a single threshold comparator, the output voltage ripple during PFM mode operation can be kept very small. The ripple voltage depends on the PFM comparator delay, the size of the output capacitor and the inductor value. Increasing output capacitor values and/or inductor values will minimize the output ripple.

The PFM mode is left and PWM mode entered in case the output current can no longer be supported in PFM mode or if the output voltage falls below a second threshold, called PFM comparator low threshold. This PFM comparator low threshold is set to -1% below nominal V_{OUT} , and enables a fast transition from Power Save Mode to PWM Mode during a load step.

The Power Save Mode can be disabled through the I²C interface for each of the step-down converters independent from each other. If Power Save Mode is disabled, the converter will then operate in fixed PWM mode.

Dynamic Voltage Positioning

This feature reduces the voltage under/overshoots at load steps from light to heavy load and vice versa. It is active in Power Save Mode. It provides more headroom for both the voltage drop at a load step, and the voltage increase at a load throw-off. This improves load transient behavior. At light loads, in which the converter operates in PFM mode, the output voltage is regulated typically 1% higher than the nominal value. In case of a load transient from light load to heavy load, the output voltage drops until it reaches the PFM comparator low threshold set to -1% below the nominal value and enters PWM mode. During a load throw off from heavy load to light load, the voltage overshoot is also minimized due to active regulation turning on the low-side MOSFET.

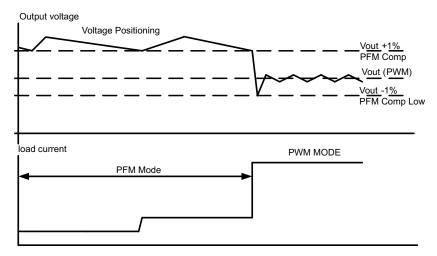


Figure 15. Dynamic Voltage Positioning in Power Save Mode

100% Duty Cycle Low Dropout Operation

The device starts to enter 100% duty cycle Mode once the input voltage comes close the nominal output voltage. In order to maintain the output voltage, the high-side MOSFET is turned on 100% for one or more cycles. As VIN decreases further, the high-side MOSFET is turned on completely. In this case the converter offers a low input-to-output voltage difference. This is particularly useful in battery-powered applications to achieve longest operation time by taking full advantage of the whole battery voltage range.

Copyright © 2011–2012, Texas Instruments Incorporated

TPS65217A, TPS65217B, TPS65217C

SLVSB64E-NOVEMBER 2011-REVISED JULY 2012

The minimum input voltage to maintain regulation depends on the load current and output voltage, and can be calculated as:

$$V_{IN,MIN} = V_{OUT,MAX} + I_{OUT,MAX} \cdot (R_{DSON,MAX} + R_L)$$

where:

 $I_{OUT,MAX}$ = Maximum output current plus inductor ripple current

R_{DSON,MAX} = Maximum upper MOSFETt switch R_{DSON}

 $R_L = DC$ resistance of the inductor

V_{OUT,MAX} = Nominal output voltage plus maximum output voltage tolerance

Short-Circuit Protection

High-side and low-side MOSFET switches are short-circuit protected. Once the high-side MOSFET switch reaches its current limit, it is turned off and the low-sideMOSFET switch is turned ON. The high-side MOSFET switch can only turn on again, once the current in the low-sideMOSFET switch decreases below its current limit.

Soft Start

The 3 step-down converters in TPS65217 have an internal soft start circuit that controls the ramp up of the output voltage. The output voltage ramps up from 5% to 95% of its nominal value within 750 μ s. This limits the inrush current in the converter during start up and prevents possible input voltage drops when a battery or high impedance power source is used. The soft start circuit is enabled after the start up time t_{Start} has expired.

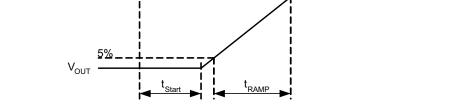


Figure 16. Output of the DCDC Converters is Ramped Up Within 750 µs

Output Filter Design (Inductor and Output Capacitor)

FN

95%

Inductor Selection for Buck Converters

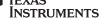
The step-down converters operate typically with $2.2-\mu H$ output inductors. Larger or smaller inductor values can be used to optimize the performance of the device for specific operation conditions. The selected inductor has to be rated for its DC resistance and saturation current. The DC resistance of the inductance will influence directly the efficiency of the converter. Therefore an inductor with lowest DC resistance should be selected for highest efficiency.

The following formula can be used to calculate the maximum inductor current under static load conditions. The saturation current of the inductor should be rated higher than the maximum inductor current because during heavy load transient the inductor current will rise above the calculated value.

$$\Delta I_{L} = Vout \cdot \frac{1 - \frac{Vout}{Vin}}{L \cdot f}$$

$$I_{L \max} = I_{out \max} + \frac{\Delta I_{L}}{2}$$
(3)

Copyright © 2011–2012, Texas Instruments Incorporated



(2)



where:

f = Switching frequency (2.25 MHz typical)

L = Inductor value

 ΔI_L = Peak to peak inductor ripple current

 I_{Lmax} = Maximum inductor current

The highest inductor current will occur at maximum V_{IN} . Open core inductors have a soft saturation characteristic and they can usually handle higher inductor currents versus a comparable shielded inductor.

A more conservative approach is to select the inductor current rating just for the maximum switch current of the corresponding converter. It must be considered, that the core material from inductor to inductor differs and will have an impact on the efficiency especially at high switching frequencies. Also the resistance of the windings will greatly affect the converter efficiency at high load. Please refer to Table 1 for recommended inductors.

PART NUMBER	SUPPLIER	VALUE (µH)	R _{DS} (mΩ) MAX	RATED CURRENT (A)	DIMENSIONS (mm)
LQM2HPN2R2MG0L	Murata	2.2	100	1.3	2 x 2.5 x 0.9
VLCF4018T-2R2N1R4-2	TDK	2.2	60	1.44	3.9 x 4.7 x 1.8

Table 1. Recommended Inductors for DCDC1, 2, and 3

Output Capacitor Selection

The advanced Fast Response voltage mode control scheme of the two converters allow the use of small ceramic capacitors with a typical value of 10 μ F, without having large output voltage under and overshoots during heavy load transients. Ceramic capacitors having low ESR values result in lowest output voltage ripple and are therefore recommended.

If ceramic output capacitors are used, the capacitor RMS ripple current rating must always meet the application requirements. For completeness the RMS ripple current is calculated as:

$$I_{RMSCout} = Vout \cdot \frac{1 - \frac{Vout}{Vin}}{L \cdot f} \cdot \frac{1}{2 \cdot \sqrt{3}}$$
(5)

At nominal load current the inductive converters operate in PWM mode and the overall output voltage ripple is the sum of the voltage spike caused by the output capacitor ESR plus the voltage ripple caused by charging and discharging the output capacitor:

$$\Delta Vout = Vout \cdot \frac{1 - \frac{Vout}{Vin}}{L \cdot f} \cdot \left(\frac{1}{8 \cdot Cout \cdot f} + ESR\right)$$
(6)

Where the highest output voltage ripple occurs at the highest input voltage V_{IN} .

At light load currents the converters operate in Power Save Mode and the output voltage ripple is dependent on the output capacitor value. The output voltage ripple is set by the internal comparator delay and the external capacitor. The typical output voltage ripple is less than 1% of the nominal output voltage.



SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

Input Capacitor Selection

Because of the nature of the buck converter having a pulsating input current, a low ESR input capacitor is required for best input voltage filtering and minimizing the interference with other circuits caused by high input voltage spikes. The converters need a ceramic input capacitor of 10 μ F. The input capacitor can be increased without any limit for better input voltage filtering. Please refer to Table 2 for recommended ceramic capacitors.

PART NUMBER	SUPPLIER	VALUE (µF)	DIMENSIONS
C2012X5R0J226MT	TDK	22	0805
JMK212BJ226MG	Taiyo Yuden	22	0805
JMK212BJ106M	Taiyo Yuden	10	0805
C2012X5R0J106M	TDK	10	0805

Table 2. Recommended Input Capacitors for DCDC1, 2, and 3	Table 2.	Recommended	Input	Capacitors	for	DCDC1,	2,	and 3
---	----------	-------------	-------	------------	-----	--------	----	-------

STANDBY LDOS (LDO1, LDO2)

LDO1 and LDO2 support up to 100 mA each, are internally current limited and have a maximum drop-out voltage of 200 mV at rated output current. In SLEEP mode, however, output current is limited to 100 μ A each. When disabled, both outputs are discharged to ground through a 300- Ω resistor.

LDO1 supports an output voltage range of 1.0 V - 1.8 V which is controlled through the DEFLDO1 register. LDO2 supports an output voltage range from 0.9 V - 1.5 V and is controlled through the DEFLDO2 register. By default, LDO1 is enabled immediately after a power-up event as described in the Modes of Operation section and remains ON in SLEEP mode to support system standby. Each LDO has low standby-current of < 15 μ A typical.

LDO2 can be configured to track the output voltage of DCDC3 (core voltage). When the TRACK bit is set in the DEFLDO2 register, the output is determined by the DCDC3[5:0] bits of the DEFDCDC3 register and the LDO2[5:0] bits of the DEFLDO2 register are ignored.

LDO1 and LDO2 can be controlled through STROBE 1-6, special STROBES 14 and 15, or through the corresponding enable bits in the ENABLE register. By default, LDO1 are controlled through STROBE15 which keeps it alive in SLEEP mode. The STROBE assignments can be changed by the user while in ACTIVE mode but be aware that all register settings are reset to default values in SLEEP or OFF mode. This can cause the LDO to power up automatically when leaving SLEEP mode even tough they have been disabled in SLEEP mode previously by assigning them to a different strobe or resetting the corresponding enable bit. If this is not desired, new default values must be programmed into non-volatile memory by the factory. Contact TI for details.

LOAD SWITCHES/LDOS (LS1/LDO3, LS2/LDO4)

TPS65217 provides two general-purpose load switches that can also be configured as LDOs. As LDOs they support up to 200 mA each, are internally current limited and have a maximum drop-out voltage of 200 mV at rated output current. LDO3 and LDO4 of the TPS65217C device supports up to 400-mA of current. In either mode ON/OFF state can be controlled either through the sequencer or the LS1_EN and LS2_EN bits of the ENABLE register. When disabled, both outputs are discharged to ground through a 300- Ω resistor.

As load switches LS1 and LS2 have a max impedance of 650 m Ω . Different from LDO operation, load switches can remain in current limit indefinitely without affecting the internal power-good signal or affecting the other rails. Please note, however, that excessive power dissipation in the switches may cause thermal shutdown of the IC.

Load switch and LDO mode are controlled by LS1LDO3 and LS2LDO4 bits of the DEFLS1 and DEFLS2 registers.

WHITE LED DRIVER

TPS65217 contains a boost converter and two current sinks capable of driving up to 2 x 10 LEDs at 25 mA or a single string at 50 mA of current. The current per current sink is approximated by the following equation:

$$I_{LED} = 1048 \times \frac{1.24V}{R_{SET}}$$

34 Submit Documentation Feedback

Copyright © 2011–2012, Texas Instruments Incorporated



Two different current levels can be programmed using two external R_{SET} resistors. Only one current setting is active at any given time and both current sinks are always regulated to the same current. The active current setting is selected through the ISEL bit of the WLEDCTRL1 register.

Brightness dimming is supported by an internal PWM signal and I²C control. Both current sources are controlled together and cannot operate independently. By default, the PWM frequency is set to 200 Hz, but can be changed to 100 Hz, 500 Hz, and 1000 Hz. The PWM duty cycle can be adjusted from 1% (default) to 100% in 1% steps through the WLEDCTRL2 register.

When the ISINK_EN bit of WLEDCTRL1 register is set to 1, both current sinks are enabled and the boost output voltage at the FB_WLED pin is regulated to support the same I_{SINK} current through each current sink. The boost output voltage, however, is internally limited to 39 V.

If only a single WLED string is required, short ISINK1 and ISINK2 pins together and connect them to the Cathode of the diode string. Note that the LED current in this case is $2 \times I_{SINK}$.

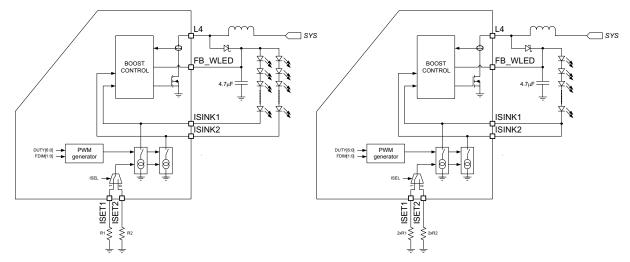


Figure 17. Block Diagram of WLED Driver. LEFT: Dual string operation. RIGHT: Single string operation (same LED current as dual string). Note that for single string operation both ISINK pins are shorted together and RSET values are doubled.

PART NUMBER	SUPPLIER	VALUE (µH)	R _{DS} (mΩ) MAX	RATED CURRENT (A)	DIMENSIONS (mm x mm x mm)
CDRH74NP-180M	Sumida	18	73	1.31	7.5 x 7.5 x 4.5
P1167.183	Pulse	18	37	1.5	7.5 x 7.5 x 4.5

Table 3. Recommended Inductors for WLED Boost Converter

Table 4. Recommended Output Capacitors for WLED Boost Converter

PART NUMBER	SUPPLIER	VOLTAGE RATING (V)	VALUE (µF)	DIMENSIONS	DIELECTRIC
UMK316BJ475ML-T	Taiyo Yuden	50	4.7	1206	X5R

BATTERY-LESS/5-V OPERATION

TPS65217 provides a linear charger for Li+ batteries but the IC can operate without a battery attached. There are three basic use-cases for battery-less operation:

- 1. The system is designed for battery operation, but the battery is not inserted. The system can be powered by connecting an AC adaptor or USB supply.
- A non-portable system running off a (regulated) 5-V supply, but the PMIC must provide protection against input over-voltage up to 20 V. Electrically this is the same as the previous case where the IC is powered off an AC adaptor. The battery pins (BAT, BATSENSE, TS) are floating and power is provided through the AC

Copyright © 2011–2012, Texas Instruments Incorporated



pin. DCDC converters, WLED driver, and LDOs connect to the over-voltage protected SYS pins. Load switches (or LDO3 and LDO4, depending on configuration) typically connect to one of the lower system rails but may also be connected to the SYS pin.

3. A non-portable system running of a regulated 5-V supply that does not require input-over-voltage protection. In this case the 5-V power supply is connected through the BAT pins and the DCDC converter inputs, WLED driver, LDO1, and LDO2 are connected directly to the 5-V supply. A 10-kΩ resistor is connected from TS to ground to simulate the NTC of the battery. Load switches (or LDO3 and LDO4, depending on configuration) typically connect to one of the lower system rails, but may also be connected to the 5-V input supply directly. The main advantage of connecting the supply to the BAT pins is higher power-efficiency because the internal power-path is by-passed and power-loss across the internal switches is avoided.

Figure 18 shows the connection of the input power supply to the IC for 5-V only operation with and without 20-V input over-voltage protection and Table 5 lists the functional differences between both setups.

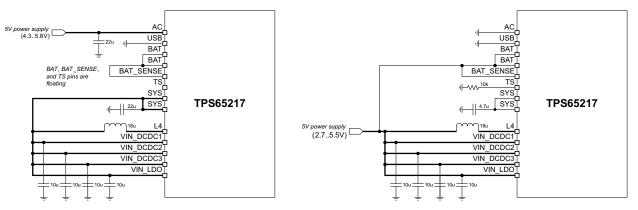
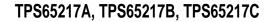


Figure 18. Left: Power-connection for battery-less/5-V only operation. The SYS node and DCDC converters are protected against input over-voltage up to 20 V. Right: Power-connection for 5-V only operation. The DCDC converters are not protected against input over-voltage, but power-efficiency is higher because the internal power-path switches are bypassed.

Table 5. Functional Differences Between Battery-Less/5-V Only Operation With and Without 20-V Input
Over-Voltage Protection

	-					
	POWER SUPPLIED THROUGH AC PIN (CASE (1) AND (2))	POWER SUPPLIED THROUGH BAT PIN (CASE (3))				
Input protection	Max operating input voltage is 5.8 V, but IC is protected against input over-voltage up to 20 V.	Max operating input voltage is 5.5 V.				
Power efficiency	DCDC input current passes through AC-SYS power-path switch (approximately 150 m Ω).	Internal power-path is bypassed to minimize IxR losses.				
BATTEMP bit	BATTEMP bit (bit 0 in register 0x03h) always reads 1, but has no effect on operation of the part.	BATTEMP bit (bit 0 in register 0x03h) always reads 0.				
Output rail status upon initial power connection	LDO1 is automatically powered up when AC pin is connected to 5-V supply and device enters [WAIT PWR_EN] state. IF PWR_EN pin is not asserted within 5s, LDO1 turns OFF.	LDO1 is OFF when BAT is connected to 5-V supply. PB_IN must be pulled low to enter [WAIT PWR_EN] state.				
Response to input-over-voltage	Device enters OFF mode. NOTE: If a battery is present in the system, TPS65217 automatically switches from AC to BAT supply when AC input exceeds 6.5 V and back to AC when AC input recovers to safe operating voltage range.	N/A.				

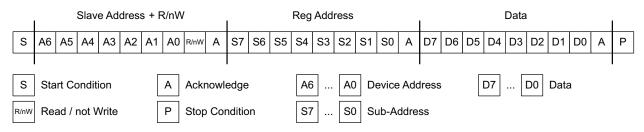


www.ti.com

NSTRUMENTS

I²C BUS OPERATION

The TPS65217 hosts a slave I^2C interface that supports data rates up to 400 kbit/s and auto-increment addressing and is compliant to I^2C standard 3.0.





The I²C Bus is a communications link between a controller and a series of slave terminals. The link is established using a two-wired bus consisting of a serial clock signal (SCL) and a serial data signal (SDA). The serial clock is sourced from the controller in all cases where the serial data line is bi-directional for data communication between the controller and the slave terminals. Each device has an open Drain output to transmit data on the serial data line. An external pull-up resistor must be placed on the serial data line to pull the drain output high during data transmission.

Data transmission is initiated with a start bit from the controller as shown in Figure 21. The start condition is recognized when the SDA line transitions from high to low during the high portion of the SCL signal. Upon reception of a start bit, the device will receive serial data on the SDA input and check for valid address and control information. If the appropriate group and address bits are set for the device, then the device will issue an acknowledge pulse and prepare the receive of sub-address data. Sub-address data is decoded and responded to as per the "Register Map" section of this document. Data transmission is completed by either the reception of a stop condition or the reception of the data word sent to the device. A stop condition is recognized as a low to high transition of the SDA input during the high portion of the SCL signal. All other transitions of the SDA line must occur during the low portion of the SCL signal. An acknowledge is issued after the reception of valid address, sub-address and data words. The I²C interfaces will auto-sequence through register addresses, so that multiple data words can be sent for a given I²C transmission. Reference Figure 20 and Figure 21 for detail.

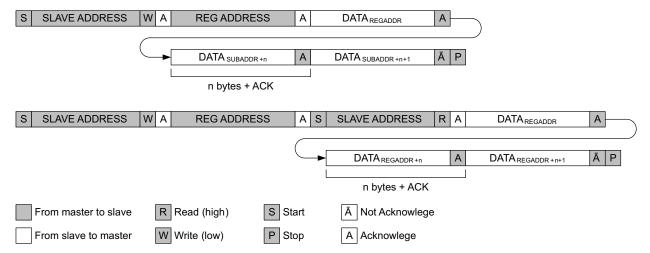


Figure 20. I²C Data Protocol. TOP: Master writes data to slave. BOTTOM: Master reads data from slave.



www.ti.com

SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

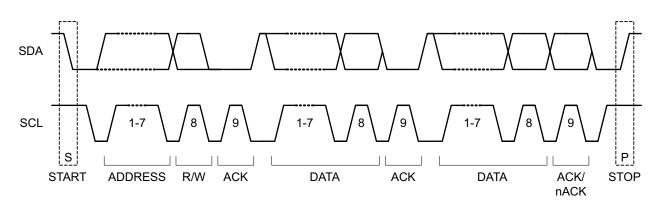


Figure 21. I²C Start/Stop/Acknowledge Protocol

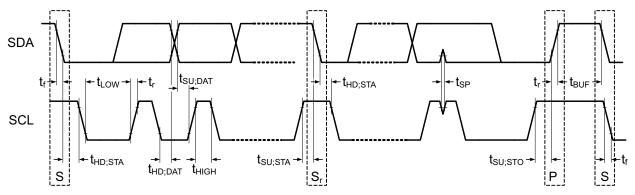


Figure 22. I²C Data Transmission Timing

Copyright © 2011–2012, Texas Instruments Incorporated



www.ti.com

DATA TRANSMISSION TIMING

 $V_{BAT} = 3.6 \text{ V} \pm 5\%$, $T_A = 25^{\circ}\text{C}$, $C_L = 100 \text{ pF}$ (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT	
f _{SCL}	Serial clock frequency		100		400	kHz	
	Hold time (repeated) START	SCL = 100 KHz	4			μs	
t _{HD;STA}	condition. After this period, the first clock pulse is generated	SCL = 400 KHz	600			ns	
	LOW period of the SCL clock	SCL = 100 KHz	4.7				
LOW	LOW period of the SCL clock	SCL = 400 KHz	1.3			μs	
	LUCL period of the CCL clock	SCL = 100 KHz	4			μs	
t _{HIGH}	HIGH period of the SCL clock	SCL = 400 KHz	600			ns	
	Set-up time for a repeated START	SCL = 100 KHz	4.7			μs	
t _{SU;STA} condition		SCL = 400 KHz	600			ns	
	Deta hald the	SCL = 100 KHz	0		3.45	μs	
t _{HD;DAT}	Data hold time	SCL = 400 KHz	0		900	ns	
	Data anti-mating	SCL = 100 KHz	250				
t _{SU;DAT}	Data set-up time	SCL = 400 KHz	100			ns	
	Rise time of both SDA and SCL	SCL = 100 KHz			1000		
t _r	signals	SCL = 400 KHz			300	ns	
	Fall time of both SDA and SCL	SCL = 100 KHz			300		
t _f	signals	SCL = 400 KHz			300	ns	
		SCL = 100 KHz	4			μs	
t _{SU;STO}	Set-up time for STOP condition	SCL = 400 KHz	600			ns	
_	Bus free time between stop and start	SCL = 100 KHz	4.7				
	condition	SCL = 400 KHz	1.3			μs	
t _{SP} Pulse width of spikes which mst be suppressed by the input filter		SCL = 100 KHz	N/A		N/A		
		SCL = 400 KHz	0		50	ns	
•		SCL = 100 KHz			400	_	
C _b Capacitive load for each bus line		SCL = 400 KHz			400	pF	

www.ti.com

PASSWORD PROTECTION

Registers 0x0B through 0x1F with exception of the password register are protected against accidental write by a 8-bit password. The password needs to be written prior to writing to a protected register and is automatically reset to 0x00h after the following I²C transaction, regardless of the register that was accessed and regardless of the transaction type (read or write). The password is required for write access only and is not required for read access.

Level1 Protection

To write to a Level1 protected register:

- 1. Write the address of the destination register, XORed with the protection password (0x7Dh) to the PASSWORD register.
- 2. Write data to the password protected register.
- 3. Only if the content of the PASSWORD register XORed with the address send in step 2 matches 0x7Dh, the data will be transferred to the protected register. Otherwise the transaction will be ignored. In any case the PASSWORD register is reset to 0x00 after the transaction.

The cycle needs to be repeated for any other register that is Level1 write protected.

Level2 Protection

To write to a Level2 protected register:

- 1. Write the address of the destination register, XORed with the protection password (0x7Dh) to the PASSWORD register.
- 2. Write to the password protected register. The register value will not change at this point but the data will be temporarily stored if the content of the PASSWORD register XORed with the address send in step 2 matches 0x7Dh. In any case, the PASSWORD register is reset to 0x00 after the transaction.
- 3. Write the address of the destination register, XORed with the protection password (0x7Dh) to the PASSWORD register.
- 4. Write the same data as in step 2 to the password protected register. Again, the content of the PASSWORD register XORed with the address send in step 4 must match 0x7Dh for the data to be valid.
- 5. The register will be updated only if both data transfers 2, and 4 were valid, and the transferred data matched.

Note that no other I²C transaction is allowed between step 2 and 4 and the register will not be updated if any other transaction occurs in-between. The cycle needs to be repeated for any other register that is Level2 write protected.

RESET TO DEFAULT VALUES

All registers are reset to default values when one or more of the following conditions occur:

- The device transitions from ACTIVE state to SLEEP or OFF state.
- VBAT or VUSB is applied from power-less state (Power-On-Reset).
- Push-button input is pulled high for > 8 s.
- nRESET pin is pulled low.
- A fault occurs.



TPS65217A, TPS65217B, TPS65217C

SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

www.ti.com

REGISTER ADDRESS MAP

REGISTER	ADDRESS (HEX)	NAME	PROTECTION	DEFAULT VALUE	DESCRIPTION
0	0	CHIPID	None	N/A	Chip ID
1	1	PPATH	None	N/A	Power path control
2	2	INT	None	N/A	Interrupt flags and masks
3	3	CHGCONFIG0	None	N/A	Charger control register 0
4	4	CHGCONFIG1	None	N/A	Charger control register 1
5	5	CHGCONFIG2	None	N/A	Charger control register 2
6	6	CHGCONFIG3	None	N/A	Charger control register 3
7	7	WLEDCTRL1	None	N/A	WLED control register
8	8	WLEDCTRL2	None	N/A	WLED PWM duty cycle
9	9	MUXCTRL	None	N/A	Analog Multiplexer control register
10	0A	STATUS	None	N/A	Status register
11	0B	PASSWORD	None	N/A	Write password
12	0C	PGOOD	None	N/A	Power good (PG) flags
13	0D	DEFPG	Level1	N/A	Power good (PG) delay
14	0E	DEFDCDC1	Level2	N/A	DCDC1 voltage adjustment
15	0F	DEFDCDC2	Level2	N/A	DCDC2 voltage adjustment
16	10	DEFDCDC3	Level2	N/A	DCDC3 voltage adjustment
17	11	DEFSLEW	Level2	N/A	Slew control DCDC1-3/PFM mode enable
18	12	DEFLDO1	Level2	N/A	LDO1 voltage adjustment
19	13	DEFLDO2	Level2	N/A	LDO2 voltage adjustment
20	14	DEFLS1	Level2	N/A	LS1/LDO3 voltage adjustment
21	15	DEFLS2	Level2	N/A	LS2/LDO4 voltage adjustment
22	16	ENABLE	Level1	N/A	Enable register
23	18	DEFUVLO	Level1	N/A	UVLO control register
24	19	SEQ1	Level1	N/A	Power-up STROBE definition
25	1A	SEQ2	Level1	N/A	Power-up STROBE definition
26	1B	SEQ3	Level1	N/A	Power-up STROBE definition
27	1C	SEQ4	Level1	N/A	Power-up STROBE definition
28	1D	SEQ5	Level1	N/A	Power-up delay times
29	1E	SEQ6	Level1	N/A	Power-up delay times



www.ti.com

CHIP ID REGISTER (CHIPID)

Address – 0x00h

DAT	A BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD	NAME		CHIP[3:0]			REV[3:0]			
READ	/WRITE	R	R	R	R	R	R	R	R
	TPS65217A	0	1	1	1	0	0	0	1
RESET VALUE	TPS65217B	1	1	1	1	0	0	0	1
TALUL	TPS65217C	1	1	1	0	0	0	0	1

FIELD NAME	BIT DEFINITION
	Chip ID
	0000 – future use
	0001 – future use
CHIP[3:0]	0111 – TPS65217A
Спігіз.0ј	1000 – future use
	1110 – TPS65217C
	1111 – TPS65217B
	Revision code
	0000 – revision 1.0
REV[3:0]	0001 – revision 1.1
	1111 – future use

Copyright © 2011–2012, Texas Instruments Incorporated

TEXAS INSTRUMENTS

TPS65217A, TPS65217B, TPS65217C

SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

www.ti.com

POWER PATH CONTROL REGISTER (PPATH)

Address – 0x01h

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	ACSINK	USBSINK	AC_EN	USB_EN	IAC	[1:0]	IUSE	3[1:0]
READ/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	0	0	1	1	1	1	0	1

FIELD NAME	BIT DEFINITION					
	AC current sink control					
	$0-AC$ sink is enabled when USB is valid supply and V_{AC} is below detection threshold					
ACSINK	1 – Set [ACSINK, USBSINK] = 11 to force both (AC and USB) current sinks OFF					
	NOTE: [ACSINK, USBSINK] = 01b and 10b combinations are not recommended as these may lead to unexpected enabling and disabling of the current sinks.					
	USB current sink control					
	$0-\text{USB}$ sink is enabled when AC is valid supply and V_{USB} is below detection threshold					
USBSINK	1 – Set [ACSINK, USBSINK] = 11 to force both (AC and USB) current sinks OFF					
	NOTE: [ACSINK, USBSINK] = 01b and 10b combinations are not recommended as these may lead to unexpected enabling and disabling of the current sinks.					
	AC power path enable					
AC_EN	0 – AC power input is turned off					
	1 – AC power input is turned on					
	USB power path enable					
USB_EN	0 – USB power input is turned off (USB suspend mode)					
	1 – USB power input is turned on					
	AC input current limit					
	00 – 100 mA					
IAC[1:0]	01 – 500 mA					
	10 – 1300 mA					
	11 – 2500 mA					
	USB input current limit					
	00 – 100 mA					
IUSB[1:0]	01 – 500 mA					
	10 – 1300 mA					
	11 – 1800 mA					



www.ti.com

INTERRUPT REGISTER (INT)

Address – 0x02h

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	not used	PBM	ACM	USBM	not used	PBI	ACI	USBI
READ/WRITE	R/W	R/W	R/W	R/W	R	R	R	R
RESET VALUE	1	0	0	0	0	0	0	0

FIELD NAME	BIT DEFINITION				
not used	N/A				
	Pushbutton status change interrupt mask				
PBM	0 – interrupt is issued when PB status changes				
	1 – no interrupt is issued when PB status changes				
	AC interrupt mask				
ACM	0 - interrupt is issued when power to AC input is applied or removed				
	1 - no interrupt is issued when power to AC input is applied or removed				
	USB power status change interrupt mask				
USBM	0 – interrupt is issued when power to USB input is applied or removed				
	1 – no interrupt is issued when power to USB input is applied or removed				
not used	N/A				
	Push-button status change interrupt				
PBI	0 – no change in status				
	1 – pushbutton status change (PB_IN changed high to low or low to high)				
	NOTE: Status information is available in STATUS register				
	AC power status change interrupt				
ACI	0 – no change in status				
	1 – AC power status change (power to AC pin has either been applied or removed)				
	NOTE: Status information is available in STATUS register				
	USB power status change interrupt				
USBI	0 – no change in status				
035	1 – USB power status change (power to USB pin has either been applied or removed)				
	NOTE: Status information is available in STATUS register				



CHARGER CONFIGURATION REGISTER 0 (CHGCONFIG0)

Address – 0x03h

www.ti.com

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	TREG	DPPM	TSUSP	TERMI	ACTIVE	CHGTOUT	PCHGTOUT	BATTEMP
READ/WRITE	R	R	R	R	R	R	R	R
RESET VALUE	0	0	0	0	0	0	0	0

FIELD NAME	BIT DEFINITION				
	Thermal regulation				
TREG	0 – charger is in normal operation				
	1 - charge current is reduced due to high chip temperature				
	DPPM active				
DPPM	0 – DPPM loop is not active				
	1 - DPPM loop is active; charge current is reduced to support the load with the current required				
	Thermal suspend				
TSUSP	0 – charging is allowed				
	1 - charging is momentarily suspended because battery temperature is out of range				
	Termination current detect				
TERMI	0 - charging, charge termination current threshold has not been crossed				
	1 – charge termination current threshold has been crossed and charging has been stopped. This can be due to a battery reaching full capacity or to a battery removal condition.				
	Charger active bit				
ACTIVE	0 – charger is not charging				
	1 – charger is charging (DPPM or thermal regulation may be active)				
	Charge timer time-out				
CHGTOUT	0 - charging, timers did not time out				
	1 - one of the timers has timed out and charging has been terminated				
	Pre-charge timer time-out				
PCHGTOUT	0 – charging, pre-charge timer did not time out				
	1 - pre-charge timer has timed out and charging has been terminated				
	BAT TEMP/NTC ERROR				
BATTEMP	0 - battery temperature is in the allowed range for charging				
	1 - no temperature sensor detected or battery temperature outside valid charging range				

www.ti.com

CHARGER CONFIGURATION REGISTER 1 (CHGCONFIG1)

Address – 0x04h

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	TIME	TIMER[1:0]		NTC_TYPE	RESET	TERM	SUSP	CHG_EN
READ/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	1	0	1	1	0	0	0	1

FIELD NAME	BIT DEFINITION				
	Charge safety timer setting (fast charge timer)				
	00 – 4h				
TIMER[1:0]	01 – 5h				
	10 – 6h				
	11 – 8h				
	Safety timer enable				
TMR_EN	0 – pre-charge timer and fast charge timer are disabled				
	1 – pre-charge timer and fast charge time are enabled				
	NTC TYPE (for battery temperature measurement)				
NTC_TYPE	0 – 100k (curve 1, B = 3960)				
	1 – 10k (curve 2, B = 3480)				
	Charger reset				
RESET	0 – inactive				
	1 – Reset active. This Bit must be set and then reset via the serial interface to restart the charge algorithm.				
	Charge termination on/off				
TERM	0 - charge termination enabled, based on timers and termination current				
	1 - current-based charge termination will not occur and the charger will always be on				
	Suspend charge				
SUSP	0 – Safety Timer and Pre-Charge timers are not suspended				
	1 – Safety Timer and Pre-Charge timers are suspended				
	Charger enable				
CHG_EN	0 – charger is disabled				
	1 – charger is enabled				



CHARGER CONFIGURATION REGISTER 2 (CHGCONFIG2)

Address – 0x05h

www.ti.com

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	DYNTMR	VPRECHG	VORE	G[1:0]	reserved	reserved	reserved	reserved
READ/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	1	0	0	0	0	0	0	0

FIELD NAME	BIT DEFINITION
	Dynamic timer function
DYNTMR	0 - safety timers run with their nominal clock speed
	1 - clock speed is divided by 2 if thermal loop or DPPM loop is active
	Precharge voltage
VPRECHG	0 – pre-charge to fast charge transition voltage is 2.9 V
	1 – pre-charge to fast charge transition voltage is 2.5 V
	Charge voltage selection
	00 – 4.10 V
VOREG[1:0]	01 – 4.15 V
	10 – 4.20 V
	11 – 4.25 V
reserved	This bit should always be set to 0.
reserved	This bit should always be set to 0.
reserved	This bit should always be set to 0.
reserved	This bit should always be set to 0.

www.ti.com

CHARGER CONFIGURATION REGISTER 3 (CHGCONFIG3)

Address – 0x06h

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	ICHRG[1:0]		DPPMTH[1:0]		PCHRGT	TERMIF[1:0]		TRANGE
READ/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	1	0	1	1	0	0	1	0

FIELD NAME	BIT DEFINITION						
	Charge current setting						
	00 – 300 mA						
ICHRG[1:0]	01 – 400 mA						
	10 – 500 mA						
	11 – 700 mA						
	Power path DPPM threshold						
	00 – 3.5 V						
DPPMTH[1:0]	01 – 3.75 V						
	10 – 4.0 V						
	11 – 4.25 V						
	Pre-charge time						
PCHRGT	0 – 30 min						
	1 – 60 min						
	Termination current factor						
	00 – 2.5%						
TERMIF[1:0]	01 – 7.5%						
[]	10 – 15%						
	11 – 18%						
	NOTE: Termination current = TERMIF x ICHRG						
	Temperature range for charging						
TRANGE	0 – 0°C-45°C						
	1 – 0°C-60°C						



TPS65217A, TPS65217B, TPS65217C

SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

www.ti.com

WLED CONTROL REGISTER 1 (WLEDCTRL1)

Address – 0x07h

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	not used	not used	not used	not used	ISINK_EN	ISEL	FDI	V[1:0]
READ/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	0	0	0	0	0	0	0	1

FIELD NAME	BIT DEFINITION				
not used	N/A				
not used	N/A				
not used	N/A				
not used	N/A				
	Current sink enable				
ISINK_EN	0 – current sink is disabled (OFF)				
ISINK_EN	1 – current sink is enabled (ON)				
	NOTE: This bit enables both current sinks				
	ISET selection bit				
ISEL	0 – low-level (define by ISET1 pin)				
	1 – high-level (defined by ISET2 pin)				
	PWM dimming frequency				
	00 – 100 Hz				
FDIM[1:0]	01 – 200 Hz				
	10 – 500 Hz				
	11 – 1000 Hz				

WLED CONTROL REGISTER 2 (WLEDCTRL2)

Address – 0x08h

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	not used		DUTY[6:0]					
READ/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	0	0	0	0	0	0	0	0

FIELD NAME	BIT DEFINITION						
not used	N/A						
	000 0000 – 1%						
	000 0001 – 2%						
	110 0010 – 99%						
DUTY[6:0]	110 0011 – 100%						
	110 0100 – 0%						
	111 1110 – 0%						
	111 1111 – 0%						

NSTRUMENTS

Texas



TPS65217A, TPS65217B, TPS65217C

SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

MUX CONTROL REGISTER (MUXCTRL)

Address – 0x09h

www.ti.com

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	not used		MUX[2:0]					
READ/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	0	0	0	0	0	0	0	0

FIELD NAME	BIT DEFINITION
not used	N/A
MUX[2:0]	Analog multiplexer selection 000 – MUX is disabled, output is HiZ 001 – VBAT 010 – VSYS 011 – VTS 100 – VICHARGE 101 – MUX_IN (external input) 110 – MUX is disabled, output is HiZ 111 – MUX is disabled, output is HiZ



www.ti.com

STATUS REGISTER (STATUS)

Address – 0x0Ah

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	OFF	not used	not used	not used	ACPWR	USBPWR	not used	PB
READ/WRITE	R/W	R/W	R/W	R/W	R	R	R	R
RESET VALUE	0	0	0	0	0	0	0	0

FIELD NAME	BIT DEFINITION
OFF	OFF bit. Set this bit to 1 to enter OFF state when PWR_EN pin is pulled low. Bit is automatically reset to 0.
not used	N/A
not used	N/A
not used	N/A
	AC power status bit
ACPWR	0 - AC power is not present and/or not in the range valid for charging
	1 – AC source is present and in the range valid for charging
	USB power
USBPWR	0 - USB power is not present and/or not in the range valid for charging
	1 – USB source is present and in the range valid for charging
not used	N/A
	Push Button status bit
PB	0 – Push Button is inactive (PB_IN is pulled high)
	1 – Push Button is active (PB_IN is pulled low)



PASSWORD REGISTER (PASSWORD)

Address – 0x0Bh

www.ti.com

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME				PWR	D[7:0]			
READ/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	0	0	0	0	0	0	0	0

FIELD NAME	BIT DEFINITION
	0000 0000 – Password protected registers are locked for write access
	0111 1100 – Password protected registers are locked for write access
	0111 1101 - Allows writing to a password protected register in the next write cycle
PWRD[7:0]	0111 1110 – Password protected registers are locked for write access
	1111 1111 – Password protected registers are locked for write access
	NOTE: Register is automatically reset to 0x00h after following I ² C transaction. See PASSWORD PROTECTION section for details.



www.ti.com

SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

POWER GOOD REGISTER (PGOOD)

Address – 0x0Ch

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	not used	LDO3_PG	LDO4_PG	DC1_PG	DC2_PG	DC3_PG	LDO1_PG	LDO2_PG
READ/WRITE	R/W	R	R	R	R	R	R	R
RESET VALUE	0	0	0	0	0	0	0	0

FIELD NAME	BIT DEFINITION
not used	N/A
	LDO3 power-good
LDO3_PG	0 – LDO is either disabled or not in regulation
	1 – LDO is in regulation or LS1/LDO3 is configured as switch
	LDO4 power-good
LDO4_PG	0 – LDO is either disabled or not in regulation
	1 – LDO is in regulation or LS2/LDO4 is configured as switch
	DCDC1 power-good
DC1_PG	0 – DCDC is either disabled or not in regulation
	1 – DCDC is in regulation
	DCDC2 power-good
DC2_PG	0 – DCDC is either disabled or not in regulation
	1 – DCDC is in regulation
	DCDC3 power-good
DC3_PG	0 – DCDC is either disabled or not in regulation
	1 – DCDC is in regulation
	LDO1 power-good
LDO1_PG	0 – LDO is either disabled or not in regulation
	1 – LDO is in regulation
	LDO2 power-good
LDO2_PG	0 – LDO is either disabled or not in regulation
	1 – LDO is in regulation



TPS65217A, TPS65217B, TPS65217C

SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

www.ti.com

POWER GOOD CONTROL REGISTER (DEFPG)

Address – 0x0Dh (Password Protected)

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	not used	not used	not used	not used	LDO1PGM	LDO2PGM	PGD	LY[1:0]
READ/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	0	0	0	0	1	1	0	0

FIELD NAME	BIT DEFINITION
not used	N/A
	LDO1 power-good masking bit
LDO1PGM	0 – PGOOD pin is pulled low if LDO1_PG is low
	1 - LDO1_PG status does not affect the status of the PGOOD output pin
	LDO2 power-good masking bit
LDO2PGM	0 – PGOOD pin is pulled low if LDO2_PG is low
	1 - LDO2_PG status does not affect the status of the PGOOD output pin
	Power Good delay
	00 – 20 ms
	01 – 100 ms
PGDLY[1:0]	10 – 200 ms
	11 – 400 ms
	Note: PGDLY applies to PGOOD pin.

www.ti.com

DCDC1 CONTROL REGISTER (DEFDCDC1)

Address – 0x0Eh (Password Protected)

DAT	A BIT	D7	D6	D5 D4 D3 D2 D1				D0	
FIELD	NAME	XADJ1	not used	DCDC1[5:0]					
READ	/WRITE	R/W	R/W	R/W R/W R/W R/W R/W R/W				R/W	
	TPS65217A	0	0	0	1	1	1	1	0
RESET TPS65217B 0 0 0 1				1	1	1	1	0	
TALUL	TPS65217BC	0	0	0	1	1	0	0	0

FIELD NAME		BIT DEFINITION (TPS65217A, TPS65217B)						
	DCDC1 voltage adjust	ment option						
XADJ1	0 – Output voltage is a	0 - Output voltage is adjusted through register setting						
	1 – Output voltage is e							
not used	N/A							
	DCDC1 output voltage	DCDC1 output voltage setting						
	00 0000 – 0.900 V	01 0000 – 1.300 V	10 0000 – 1.900 V	11 0000 – 2.700 V				
	00 0001 – 0.925 V	01 0001 – 1.325 V	10 0001 – 1.950 V	11 0001 – 2.750 V				
	00 0010 – 0.950 V	01 0010 – 1.350 V	10 0010 – 2.000 V	11 0010 – 2.800 V				
	00 0011 – 0.975 V	00 0011 – 0.975 V 01 0011 – 1.375 V		11 0011 – 2.850 V				
	00 0100 – 1.000 V	00 0100 – 1.000 V 01 0100 – 1.400 V 10 0100 – 2.100 V 11 01						
	00 0101 – 1.025 V	00 0101 – 1.025 V 01 0101 – 1.425 V 10 0101 – 2.150 V 11 0						
	00 0110 – 1.050 V	01 0110 – 1.450 V	10 0110 – 2.200 V	11 0110 – 3.100 V				
DCDC1[5:0]	00 0111 – 1.075 V	01 0111 – 1.475 V	10 0111 – 2.250 V	11 0111 – 3.200 V				
	00 1000 – 1.100 V	01 1000 – 1.500 V	10 1000 – 2.300 V	11 1000 – 3.300 V				
	00 1001 – 1.125 V	01 1001 – 1.550 V	10 1001 – 2.350 V	11 1001 – 3.300 V				
	00 1010 – 1.150 V	01 1010 – 1.600 V	10 1010 – 2.400 V	11 1010 – 3.300 V				
	00 1011 – 1.175 V	01 1011 – 1.650 V	10 1011 – 2.450 V	11 1011 – 3.300 V				
	00 1100 – 1.200 V	01 1100 – 1.700 V	10 1100 – 2.500 V	11 1100 – 3.300 V				
	00 1101 – 1.225 V	01 1101 – 1.750 V	10 1101 – 2.550 V	11 1101 – 3.300 V				
	00 1110 – 1.250 V	01 1110 – 1.800 V	10 1110 – 2.600 V	11 1110 – 3.300 V				
	00 1111 – 1.275 V	01 1111 – 1.850 V	10 1111 – 2.650 V	11 1111 – 3.300 V				



www.ti.com

TPS65217A, TPS65217B, TPS65217C

SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

FIELD NAME		BIT DEFINITION (TPS65217C)						
	DCDC1 voltage adjust	DCDC1 voltage adjustment option 0 – Output voltage is adjusted through register setting						
XADJ1	0 – Output voltage is a							
	1 – Output voltage is e	externally adjusted						
not used	N/A							
	DCDC1 output voltage	setting						
	00 0000 – 0.900 V	01 0000 – 1.300 V	10 0000 – 1.900 V	11 0000 – 2.700 V				
	00 0001 – 0.925 V	01 0001 – 1.325 V	10 0001 – 1.950 V	11 0001 – 2.750 V				
	00 0010 – 0.950 V	01 0010 – 1.350 V	10 0010 – 2.000 V	11 0010 – 2.800 V				
	00 0011 – 0.975 V	00 0011 – 0.975 V 01 0011 – 1.375 V		11 0011 – 2.850 V				
	00 0100 – 1.000 V	01 0100 – 1.400 V	10 0100 – 2.100 V	11 0100 – 2.900 V				
	00 0101 – 1.025 V	01 0101 – 1.425 V	10 0101 – 2.150 V	11 0101 – 3.000 V				
	00 0110 – 1.050 V	01 0110 – 1.450 V	10 0110 – 2.200 V	11 0110 – 3.100 V				
DCDC1[5:0]	00 0111 – 1.075 V	01 0111 – 1.475 V	10 0111 – 2.250 V	11 0111 – 3.200 V				
	00 1000 – 1.100 V	01 1000 – 1.500 V	10 1000 – 2.300 V	11 1000 – 3.300 V				
	00 1001 – 1.125 V	01 1001 – 1.550 V	10 1001 – 2.350 V	11 1001 – 3.300 V				
	00 1010 – 1.150 V	01 1010 – 1.600 V	10 1010 – 2.400 V	11 1010 – 3.300 V				
	00 1011 – 1.175 V	01 1011 – 1.650 V	10 1011 – 2.450 V	11 1011 – 3.300 V				
	00 1100 – 1.200 V	01 1100 – 1.700 V	10 1100 – 2.500 V	11 1100 – 3.300 V				
	00 1101 – 1.225 V	01 1101 – 1.750 V	10 1101 – 2.550 V	11 1101 – 3.300 V				
	00 1110 – 1.250 V	01 1110 – 1.800 V	10 1110 – 2.600 V	11 1110 – 3.300 V				
	00 1111 – 1.275 V	01 1111 – 1.850 V	10 1111 – 2.650 V	11 1111 – 3.300 V				



www.ti.com

DCDC2 CONTROL REGISTER (DEFDCDC2)

Address – 0x0Fh (Password Protected)

DAT	A BIT	D7	D6	D5 D4 D3 D2 D1				D0	
FIELD	NAME	XADJ2	not used	DCDC2[5:0]					
READ	/WRITE	R/W	R/W	R/W R/W R/W R/W R/W R/W				R/W	
	TPS65217A	0	0	1	1	1	0	0	0
RESET VALUE TPS65217B		0	0	0	0	1	0	0	0
VALUE	TPS65217C	0	0	0	0	1	0	0	0

FIELD NAME		BIT DEFINITION (TPS65217A)						
	DCDC2 voltage adjust	ment option						
XADJ2	0 – Output voltage is a	0 - Output voltage is adjusted through register setting						
	1 – Output voltage is e	externally adjusted						
not used	N/A							
	DCDC2 output voltage	setting						
	00 0000 – 0.900 V	01 0000 – 1.300 V	10 0000 – 1.900 V	11 0000 – 2.700 V				
	00 0001 – 0.925 V	01 0001 – 1.325 V	10 0001 – 1.950 V	11 0001 – 2.750 V				
	00 0010 – 0.950 V	01 0010 – 1.350 V	10 0010 – 2.000 V	11 0010 – 2.800 V				
	00 0011 – 0.975 V	01 0011 – 1.375 V	10 0011 – 2.050 V	11 0011 – 2.850 V				
	00 0100 – 1.000 V 01 0100 – 1.400 V		10 0100 – 2.100 V	11 0100 – 2.900 V				
	00 0101 – 1.025 V	01 0101 – 1.425 V	10 0101 – 2.150 V	11 0101 – 3.000 V				
	00 0110 – 1.050 V	01 0110 – 1.450 V	10 0110 – 2.200 V	11 0110 – 3.100 V				
DCDC2[5:0]	00 0111 – 1.075 V	01 0111 – 1.475 V	10 0111 – 2.250 V	11 0111 – 3.200 V				
	00 1000 – 1.100 V	01 1000 – 1.500 V	10 1000 – 2.300 V	11 1000 – 3.300 V				
	00 1001 – 1.125 V	01 1001 – 1.550 V	10 1001 – 2.350 V	11 1001 – 3.300 V				
	00 1010 – 1.150 V	01 1010 – 1.600 V	10 1010 – 2.400 V	11 1010 – 3.300 V				
	00 1011 – 1.175 V	01 1011 – 1.650 V	10 1011 – 2.450 V	11 1011 – 3.300 V				
	00 1100 – 1.200 V	01 1100 – 1.700 V	10 1100 – 2.500 V	11 1100 – 3.300 V				
	00 1101 – 1.225 V	01 1101 – 1.750 V	10 1101 – 2.550 V	11 1101 – 3.300 V				
	00 1110 – 1.250 V	01 1110 – 1.800 V	10 1110 – 2.600 V	11 1110 – 3.300 V				
	00 1111 – 1.275 V	01 1111 – 1.850 V	10 1111 – 2.650 V	11 1111 – 3.300 V				



www.ti.com

TPS65217A, TPS65217B, TPS65217C

SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

FIELD NAME		BIT DEFINITION (TPS65217B, TPS65217C)						
	DCDC2 voltage adjust	DCDC2 voltage adjustment option 0 – Output voltage is adjusted through register setting						
XADJ2	0 – Output voltage is a							
	1 – Output voltage is e	1 – Output voltage is externally adjusted						
not used	N/A							
	DCDC2 output voltage	setting						
	00 0000 – 0.900 V	01 0000 – 1.300 V	10 0000 – 1.900 V	11 0000 – 2.700 V				
	00 0001 – 0.925 V	01 0001 – 1.325 V	10 0001 – 1.950 V	11 0001 – 2.750 V				
	00 0010 – 0.950 V	01 0010 – 1.350 V	10 0010 – 2.000 V	11 0010 – 2.800 V				
	00 0011 – 0.975 V	00 0011 – 0.975 V 01 0011 – 1.375 V		11 0011 – 2.850 V				
	00 0100 – 1.000 V	00 0100 – 1.000 V 01 0100 – 1.400 V 10 0100 – 2.100 V 1						
	00 0101 – 1.025 V	01 0101 – 1.425 V	10 0101 – 2.150 V	11 0101 – 3.000 V				
	00 0110 – 1.050 V	01 0110 – 1.450 V	10 0110 – 2.200 V	11 0110 – 3.100 V				
DCDC2[5:0]	00 0111 – 1.075 V	01 0111 – 1.475 V	10 0111 – 2.250 V	11 0111 – 3.200 V				
	00 1000 – 1.100 V	01 1000 – 1.500 V	10 1000 – 2.300 V	11 1000 – 3.300 V				
	00 1001 – 1.125 V	01 1001 – 1.550 V	10 1001 – 2.350 V	11 1001 – 3.300 V				
	00 1010 – 1.150 V	01 1010 – 1.600 V	10 1010 – 2.400 V	11 1010 – 3.300 V				
	00 1011 – 1.175 V	01 1011 – 1.650 V	10 1011 – 2.450 V	11 1011 – 3.300 V				
	00 1100 – 1.200 V	01 1100 – 1.700 V	10 1100 – 2.500 V	11 1100 – 3.300 V				
	00 1101 – 1.225 V	01 1101 – 1.750 V	10 1101 – 2.550 V	11 1101 – 3.300 V				
	00 1110 – 1.250 V	01 1110 – 1.800 V	10 1110 – 2.600 V	11 1110 – 3.300 V				
	00 1111 – 1.275 V	01 1111 – 1.850 V	10 1111 – 2.650 V	11 1111 – 3.300 V				

Copyright © 2011–2012, Texas Instruments Incorporated



www.ti.com

DCDC3 CONTROL REGISTER (DEFDCDC3)

Address - 0x10h (Password Protected)

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	XADJ3	not used	DCDC3[5:0]					
READ/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	0	0	0	0	1	0	0	0

FIELD NAME		BIT DEFINITION							
	DCDC3 voltage adjust	DCDC3 voltage adjustment option							
XADJ3	0 – Output voltage is a	0 - Output voltage is adjusted through register setting							
	1 – Output voltage is e	externally adjusted							
not used	N/A								
	DCDC3 output voltage	setting							
	00 0000 – 0.900 V	01 0000 – 1.300 V	10 0000 – 1.900 V	11 0000 – 2.700 V					
	00 0001 – 0.925 V	01 0001 – 1.325 V	10 0001 – 1.950 V	11 0001 – 2.750 V					
	00 0010 – 0.950 V	01 0010 – 1.350 V	10 0010 – 2.000 V	11 0010 – 2.800 V					
	00 0011 – 0.975 V	01 0011 – 1.375 V	10 0011 – 2.050 V	11 0011 – 2.850 V					
	00 0100 – 1.000 V	01 0100 – 1.400 V	10 0100 – 2.100 V	11 0100 – 2.900 V					
	00 0101 – 1.025 V	01 0101 – 1.425 V	10 0101 – 2.150 V	11 0101 – 3.000 V					
	00 0110 – 1.050 V	01 0110 – 1.450 V	10 0110 – 2.200 V	11 0110 – 3.100 V					
DCDC3[5:0]	00 0111 – 1.075 V	01 0111 – 1.475 V	10 0111 – 2.250 V	11 0111 – 3.200 V					
	00 1000 – 1.100 V	01 1000 – 1.500 V	10 1000 – 2.300 V	11 1000 – 3.300 V					
	00 1001 – 1.125 V	01 1001 – 1.550 V	10 1001 – 2.350 V	11 1001 – 3.300 V					
	00 1010 – 1.150 V	01 1010 – 1.600 V	10 1010 – 2.400 V	11 1010 – 3.300 V					
	00 1011 – 1.175 V	01 1011 – 1.650 V	10 1011 – 2.450 V	11 1011 – 3.300 V					
	00 1100 – 1.200 V	01 1100 – 1.700 V	10 1100 – 2.500 V	11 1100 – 3.300 V					
	00 1101 – 1.225 V	01 1101 – 1.750 V	10 1101 – 2.550 V	11 1101 – 3.300 V					
	00 1110 – 1.250 V	01 1110 – 1.800 V	10 1110 – 2.600 V	11 1110 – 3.300 V					
	00 1111 – 1.275 V	01 1111 – 1.850 V	10 1111 – 2.650 V	11 1111 – 3.300 V					



www.ti.com

SLEW RATE CONTROL REGISTER (DEFSLEW)

Address – 0x11h (Password Protected)

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	GO	GODSBL	PFM_EN1	PFM_EN2	PFM_EN3		SLEW[2:0]	
READ/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	0	0	0	0	0	1	1	0

FIELD NAME	BIT DEFINITION ⁽¹⁾				
	Go bit				
	0 – no change				
GO	1 – Initiates the transition from present state to the output voltage setting currently stored in DEFDCDCx register				
	NOTE: Bit is automatically reset at the end of the voltage transition.				
	Go disable bit				
GODSBL	0 – enabled				
	1 – disabled; DCDCx output voltage changes whenever set-point is updated in DEFDCDCx register without having to write to the GO bit. SLEW[2:0] setting does apply.				
	PFM enable bit, DCDC1				
PFM_EN1	0 – DCDC converter operates in PWM / PFM mode, depending on load				
	1 – DCDC converter is forced into fixed frequency PWM mode				
	PFM enable bit, DCDC2				
PFM_EN2	0 – DCDC converter operates in PWM / PFM mode, depending on load				
	1 – DCDC converter is forced into fixed frequency PWM mode				
	PFM enable bit, DCDC3				
PFM_EN3	0 – DCDC converter operates in PWM / PFM mode, depending on load				
	1 – DCDC converter is forced into fixed frequency PWM mode				
	Output slew rate setting				
	000 – 224 μs/step (0.11 mV/μs at 25 mV per step)				
	001 – 112 μs/step (0.22 mV/μs at 25 mV per step)				
	010 – 56 μs/step (0.45 mV/μs at 25 mV per step)				
	011 – 28 μs/step (0.90 mV/μs at 25 mV per step)				
SLEW[2:0]	100 – 14 µs/step (1.80 mV/µs at 25 mV per step)				
	101 – 7 μs/step (3.60 mV/μs at 25 mV per step)				
	110 – 3.5 μs/step (7.2 mV/μs at 25 mV per step)				
	111 - Immediate; Slew rate is only limited by control loop response time				
	Note: The actual slew rate depends on the voltage step per code. Please refer to DCDC1 and DCDC2 register for details.				

(1) Slew-rate control applies to all three DCDC converters.



www.ti.com

LDO1 CONTROL REGISTER (DEFLDO1)

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	not used	not used	not used	not used	LDO1[3:0]			
READ/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	0	0	0	0	1	0	0	1

FIELD NAME		BIT DEFINITION						
not used	N/A							
not used	N/A							
not used	N/A							
not used	N/A							
	LDO1 output voltage	e setting						
	0000 – 1.00 V	0100 – 1.30 V	1000 – 1.60 V	1100 – 2.80 V				
LDO1[3:0]	0001 – 1.10 V	0101 – 1.35 V	1001 – 1.80 V	1101 – 3.00 V				
	0010 – 1.20 V	0110 – 1.40 V	1010 – 2.50 V	1110 – 3.10 V				
	0011 – 1.25 V	0111 – 1.50 V	1011 – 2.75 V	1111 – 3.30 V				



www.ti.com

LDO2 CONTROL REGISTER (DEFLDO2)

Address – 0x13h (Password Protected)

	····/							
DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	not used	TRACK	LDO2[5:0]					
READ/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	0	0	1	1	1	0	0	0

FIELD NAME		BIT DEFINITION							
not used	N/A	N/A							
	LDO2 tracking bit	LDO2 tracking bit							
TRACK	0 – Output voltage is d	0 – Output voltage is defined by LDO2[5:0] bits							
	1 – Output voltage follo	ows DCDC3 voltage setting	(DEFDCDC3 register)						
	LDO2 output voltage s	etting							
	00 0000 – 0.900 V	01 0000 – 1.300 V	10 0000 – 1.900 V	11 0000 – 2.700 V					
	00 0001 – 0.925 V	01 0001 – 1.325 V	10 0001 – 1.950 V	11 0001 – 2.750 V					
	00 0010 – 0.950 V	01 0010 – 1.350 V	10 0010 – 2.000 V	11 0010 – 2.800 V					
	00 0011 – 0.975 V	01 0011 – 1.375 V	10 0011 – 2.050 V	11 0011 – 2.850 V					
	00 0100 – 1.000 V	01 0100 – 1.400 V	10 0100 – 2.100 V	11 0100 – 2.900 V					
	00 0101 – 1.025 V	01 0101 – 1.425 V	10 0101 – 2.150 V	11 0101 – 3.000 V					
	00 0110 – 1.050 V	01 0110 – 1.450 V	10 0110 – 2.200 V	11 0110 – 3.100 V					
LDO2[5:0]	00 0111 – 1.075 V	01 0111 – 1.475 V	10 0111 – 2.250 V	11 0111 – 3.200 V					
	00 1000 – 1.100 V	01 1000 – 1.500 V	10 1000 – 2.300 V	11 1000 – 3.300 V					
	00 1001 – 1.125 V	01 1001 – 1.550 V	10 1001 – 2.350 V	11 1001 – 3.300 V					
	00 1010 – 1.150 V	01 1010 – 1.600 V	10 1010 – 2.400 V	11 1010 – 3.300 V					
	00 1011 – 1.175 V	01 1011 – 1.650 V	10 1011 – 2.450 V	11 1011 – 3.300 V					
	00 1100 – 1.200 V	01 1100 – 1.700 V	10 1100 – 2.500 V	11 1100 – 3.300 V					
	00 1101 – 1.225 V	01 1101 – 1.750 V	10 1101 – 2.550 V	11 1101 – 3.300 V					
	00 1110 – 1.250 V	01 1110 – 1.800 V	10 1110 – 2.600 V	11 1110 – 3.300 V					
	00 1111 – 1.275 V	01 1111 – 1.850 V	10 1111 – 2.650 V	11 1111 – 3.300 V					

www.ti.com

LOAD SWITCH1 / LDO3 CONTROL REGISTER (DEFLS1)

DAT	A BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD	NAME	not used	not used	LS1LDO3	LDO3[4:0]				
READ	/WRITE	R/W	R/W	R/W	R/W R/W R/W R				R/W
	TPS65217A	0	0	0	0	0	1	1	0
RESET VALUE	TPS65217B	0	0	1	1	1	1	1	1
TALUL	TPS65217B	0	0	1	0	0	1	1	0

FIELD NAME		BIT DEFINITION (TPS65217A)						
not used	N/A							
not used	N/A							
	LS / LDO configuration	n bit						
LS1LDO3	0 – FET functions as	load switch (LS1)						
	1 – FET is configured	as LDO3						
	LDO3 output voltage	setting (LS1LDO3 = 1)						
	0 0000 – 1.50 V	0 1000 – 1.90 V	1 0000 – 2.55 V	1 1000 – 2.95 V				
	0 0001 – 1.55 V	0 1001 – 2.00 V	1 0001 – 2.60 V	1 1001 – 3.00 V				
	0 0010 – 1.60 V	0 1010 – 2.10 V	1 0010 – 2.65 V	1 1010 – 3.05 V				
LDO3[4:0]	0 0011 – 1.65 V	0 1011 – 2.20 V	1 0011 – 2.70 V	1 1011 – 3.10 V				
	0 0100 – 1.70 V	0 1100 – 2.30 V	1 0100 – 2.75 V	1 1100 – 3.15 V				
	0 0101 – 1.75 V	0 1101 – 2.40 V	1 0101 – 2.80 V	1 1101 – 3.20 V				
	0 0110 – 1.80 V	0 1110 – 2.45 V	1 0110 – 2.85 V	1 1110 – 3.25 V				
	0 0111 – 1.85 V	0 1111 – 2.50 V	1 0111 – 2.90 V	1 1111 – 3.30 V				

FIELD NAME		BIT DEFINITION (TPS65217B)						
not used	N/A							
not used	N/A							
	LS / LDO configuration	on bit						
LS1LDO3	0 – FET functions as	load switch (LS1)						
	1 – FET is configured	as LDO3						
	LDO3 output voltage	setting (LS1LDO3 = 1)						
	0 0000 – 1.50 V	0 1000 – 1.90 V	1 0000 – 2.55 V	1 1000 – 2.95 V				
	0 0001 – 1.55 V	0 1001 – 2.00 V	1 0001 – 2.60 V	1 1001 – 3.00 V				
	0 0010 – 1.60 V	0 1010 – 2.10 V	1 0010 – 2.65 V	1 1010 – 3.05 V				
LDO3[4:0]	0 0011 – 1.65 V	0 1011 – 2.20 V	1 0011 – 2.70 V	1 1011 – 3.10 V				
	0 0100 – 1.70 V	0 1100 – 2.30 V	1 0100 – 2.75 V	1 1100 – 3.15 V				
	0 0101 – 1.75 V	0 1101 – 2.40 V	1 0101 – 2.80 V	1 1101 – 3.20 V				
	0 0110 – 1.80 V	0 1110 – 2.45 V	1 0110 – 2.85 V	1 1110 – 3.25 V				
	0 0111 – 1.85 V	0 1111 – 2.50 V	1 0111 – 2.90 V	1 1111 – 3.30 V				



www.ti.com

TPS65217A, TPS65217B, TPS65217C

SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

FIELD NAME		BIT DEFINITION (TPS65217C)					
not used	N/A						
not used	N/A						
	LS / LDO configuration	on bit					
LS1LDO3	0 – FET functions as	load switch (LS1)					
	1 – FET is configured	l as LDO3					
	LDO3 output voltage setting (LS1LDO3 = 1)						
	0 0000 – 1.50 V	0 1000 – 1.90 V	1 0000 – 2.55 V	1 1000 – 2.95 V			
	0 0001 – 1.55 V	0 1001 – 2.00 V	1 0001 – 2.60 V	1 1001 – 3.00 V			
	0 0010 – 1.60 V	0 1010 – 2.10 V	1 0010 – 2.65 V	1 1010 – 3.05 V			
LDO3[4:0]	0 0011 – 1.65 V	0 1011 – 2.20 V	1 0011 – 2.70 V	1 1011 – 3.10 V			
	0 0100 – 1.70 V	0 1100 – 2.30 V	1 0100 – 2.75 V	1 1100 – 3.15 V			
	0 0101 – 1.75 V	0 1101 – 2.40 V	1 0101 – 2.80 V	1 1101 – 3.20 V			
	0 0110 – 1.80 V	0 1110 – 2.45 V	1 0110 – 2.85 V	1 1110 – 3.25 V			
	0 0111 – 1.85 V	0 1111 – 2.50 V	1 0111 – 2.90 V	1 1111 – 3.30 V			

www.ti.com

LOAD SWITCH2 / LDO4 CONTROL REGISTER (DEFLS2)

Address – 0x15h (Password Protected)

DAT	A BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD	NAME	not used	not used	LS2LDO4	LDO4[4:0]				
READ	/WRITE	R/W	R/W	R/W	R/W R/W R/W R/W				R/W
	TPS65217A	0	0	0	1	0	1	0	1
RESET VALUE	TPS65217B	0	0	1	1	1	1	1	1
TALUL	TPS65217C	0	0	1	1	1	1	1	1

FIELD NAME		BIT DEFINITION (TPS65217A)					
not used	N/A						
not used	N/A						
	LS / LDO configuration	n bit					
LS2LDO4	0 – FET functions as	load switch (LS2)					
	1 – FET is configured	as LDO4					
	LDO4 output voltage	setting (LS2LDO4 = 1)					
	0 0000 – 1.50 V	0 1000 – 1.90 V	1 0000 – 2.55 V	1 1000 – 2.95 V			
	0 0001 – 1.55 V	0 1001 – 2.00 V	1 0001 – 2.60 V	1 1001 – 3.00 V			
	0 0010 – 1.60 V	0 1010 – 2.10 V	1 0010 – 2.65 V	1 1010 – 3.05 V			
LDO4[4:0]	0 0011 – 1.65 V	0 1011 – 2.20 V	1 0011 – 2.70 V	1 1011 – 3.10 V			
	0 0100 – 1.70 V	0 1100 – 2.30 V	1 0100 – 2.75 V	1 1100 – 3.15 V			
	0 0101 – 1.75 V	0 1101 – 2.40 V	1 0101 – 2.80 V	1 1101 – 3.20 V			
	0 0110 – 1.80 V	0 1110 – 2.45 V	1 0110 – 2.85 V	1 1110 – 3.25 V			
	0 0111 – 1.85 V	0 1111 – 2.50 V	1 0111 – 2.90 V	1 1111 – 3.30 V			

FIELD NAME		BIT DEFINITION (TPS65217B, TPS65217C)						
not used	N/A							
not used	N/A							
	LS / LDO configuration	on bit						
LS2LDO4	0 – FET functions as	load switch (LS2)						
	1 – FET is configured	l as LDO4						
	LDO4 output voltage	setting (LS2LDO4 = 1)						
	0 0000 – 1.50 V	0 1000 – 1.90 V	1 0000 – 2.55 V	1 1000 – 2.95 V				
	0 0001 – 1.55 V	0 1001 – 2.00 V	1 0001 – 2.60 V	1 1001 – 3.00 V				
	0 0010 – 1.60 V	0 1010 – 2.10 V	1 0010 – 2.65 V	1 1010 – 3.05 V				
LDO4[4:0]	0 0011 – 1.65 V	0 1011 – 2.20 V	1 0011 – 2.70 V	1 1011 – 3.10 V				
	0 0100 – 1.70 V	0 1100 – 2.30 V	1 0100 – 2.75 V	1 1100 – 3.15 V				
	0 0101 – 1.75 V	0 1101 – 2.40 V	1 0101 – 2.80 V	1 1101 – 3.20 V				
	0 0110 – 1.80 V	0 1110 – 2.45 V	1 0110 – 2.85 V	1 1110 – 3.25 V				
	0 0111 – 1.85 V	0 1111 – 2.50 V	1 0111 – 2.90 V	1 1111 – 3.30 V				



www.ti.com

ENABLE REGISTER (ENABLE)

Address – 0x16h (Password Protected)

	0.000.00,							
DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	not used	LS1_EN	LS2_EN	DC1_EN	DC2_EN	DC3_EN	LDO1_EN	LDO2_EN
READ/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	0	0	0	0	0	0	0	0

FIELD NAME	BIT DEFINITION					
not used	N/A					
	Load Switch1/LDO3 enable bit					
	0 – disabled					
LS1_EN	1 – enabled					
	NOTE: PWR_EN pin must be high to enable LS1/LDO3					
	Load Switch2/LDO4 enable bit					
	0 – disabled					
LS2_EN	1 – enabled					
	NOTE: PWR_EN pin must be high to enable LS2/LDO4					
	DCDC1 enable bit					
	0 – DCDC1 is disabled					
DC1_EN	1 – DCDC1 is enabled					
	NOTE: PWR_EN pin must be high to enable DCDC					
	DCDC2 enable bit					
	0 – DCDC2 is disabled					
DC2_EN	1 – DCDC2 is enabled					
	NOTE: PWR_EN pin must be high to enable DCDC					
	DCDC3 enable bit					
DC3_EN	0 – DCDC3 is disabled					
DC3_EN	1 – DCDC3 is enabled					
	NOTE: PWR_EN pin must be high to enable DCDC					
	LDO1 enable bit					
LDO1_EN	0 – disabled					
	1 – enabled					
	LDO2 enable bit					
LDO2_EN	0 – disabled					
	1 – enabled					

TEXAS INSTRUMENTS

SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

www.ti.com

UVLO CONTROL REGISTER (DEFUVLO)

Address – 0x18h (Password Protected)

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	not used	UVL	O[1:0]					
READ/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	0	0	0	0	0	0	1	1

FIELD NAME	BIT DEFINITION
not used	N/A
	Under Voltage Lock Out setting
	00 – 2.73 V
UVLO[1:0]	01 – 2.89 V
	10 – 3.18 V
	11 – 3.30 V



www.ti.com

SEQUENCER REGISTER 1 (SEQ1)

Address – 0x19h (Password Protected)

DAT	A BIT	D7	D7 D6 D5 D4			D3	D2	D1	D0
FIELD	NAME		DC1_	SEQ[3:0]		DC2_SEQ[3:0]			
READ	/WRITE	R R/W R/W R/W R R/W				R/W	R/W	R/W	
	TPS65217A	0	0	0	1	0	0	1	0
RESET VALUE	TPS65217B	0	0	0	1	0	1	0	1
T.LOL	TPS65217C	0	0	0	1	0	1	0	1

FIELD NAME	BIT DEFINITION (TPS65217A)
	DCDC1 enable STROBE
	0000 - rail is not controlled by sequencer
	0001 – enable at STROBE1
	0010 – enable at STROBE2
DC1_SEQ[3:0]	0011 – enable at STROBE3
	0100 – enable at STROBE4
	0101 – enable at STROBE5
	0110 – enable at STROBE6
	0111 – enable at STROBE7
	DCDC2 enable state
	0000 - rail is not controlled by sequencer
	0001 – enable at STROBE1
	0010 – enable at STROBE2
DC2_SEQ[3:0]	0011 – enable at STROBE3
	0100 – enable at STROBE4
	0101 – enable at STROBE5
	0110 – enable at STROBE6
	0111 – enable at STROBE7

FIELD NAME	BIT DEFINITION (TPS65217B, TPS65217C)
	DCDC1 enable STROBE
	0000 - rail is not controlled by sequencer
	0001 – enable at STROBE1
	0010 – enable at STROBE2
DC1_SEQ[3:0]	0011 – enable at STROBE3
	0100 – enable at STROBE4
	0101 – enable at STROBE5
	0110 – enable at STROBE6
	0111 – enable at STROBE7
	DCDC2 enable state
	0000 - rail is not controlled by sequencer
	0001 – enable at STROBE1
	0010 – enable at STROBE2
DC2_SEQ[3:0]	0011 – enable at STROBE3
	0100 – enable at STROBE4
	0101 – enable at STROBE5
	0110 – enable at STROBE6
	0111 – enable at STROBE7

Copyright © 2011–2012, Texas Instruments Incorporated

Submit Documentation Feedback 69

TEXAS INSTRUMENTS

SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

www.ti.com

SEQUENCER REGISTER 2 (SEQ2)

Address – 0x1Ah (Password Protected)

DATA BIT		D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME		DC3_SEQ[3:0]				LDO1_SEQ[3:0]			
READ/WRITE		R	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	TPS65217A	0	0	1	1	1	0	1	1
	TPS65217B	0	1	0	1	1	1	1	1
	TPS65217C	0	1	0	1	1	1	1	1

FIELD NAME	BIT DEFINITION (TPS65217A)					
	DCDC3 enable STROBE					
	0000 - rail is not controlled by sequencer					
	0001 – enable at STROBE1					
	0010 – enable at STROBE2					
DC3_SEQ[3:0]	0011 – enable at STROBE3					
	0100 – enable at STROBE4					
	0101 – enable at STROBE5					
	0110 – enable at STROBE6					
	0111 – enable at STROBE7					
	LDO1 enable state					
	0000 – rail is not controlled by sequencer					
	0001 – enable at STROBE1					
	0010 – enable at STROBE2					
	0011 – enable at STROBE3					
	0100 – enable at STROBE4					
LDO1_SEQ[3:0]	0101 – enable at STROBE5					
	0110 – enable at STROBE6					
	0111 – enable at STROBE7					
	1000 - rail is not controlled by sequencer					
	1001 - rail is not controlled by sequencer					
	1110 – enable at STROBE14					
	1111 – enabled at STROBE15 (with SYS)					

Copyright © 2011–2012, Texas Instruments Incorporated



TPS65217A, TPS65217B, TPS65217C

www.ti.com

SLVSB64E-NOVEMBER 2011-REVISED JULY 2012

FIELD NAME	BIT DEFINITION (TPS65217B, TPS65217C)					
	DCDC3 enable STROBE					
	0000 - rail is not controlled by sequencer					
	0001 – enable at STROBE1					
	0010 – enable at STROBE2					
DC3_SEQ[3:0]	0011 – enable at STROBE3					
	0100 – enable at STROBE4					
	0101 – enable at STROBE5					
	0110 – enable at STROBE6					
	0111 – enable at STROBE7					
	LDO1 enable state					
	0000 - rail is not controlled by sequencer					
	0001 – enable at STROBE1					
	0010 – enable at STROBE2					
	0011 – enable at STROBE3					
	0100 – enable at STROBE4					
LDO1_SEQ[3:0]	0101 – enable at STROBE5					
	0110 – enable at STROBE6					
	0111 – enable at STROBE7					
	1000 - rail is not controlled by sequencer					
	1001 - rail is not controlled by sequencer					
	1110 – enable at STROBE14					
	1111 – enabled at STROBE15 (with SYS)					

TEXAS INSTRUMENTS

SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

www.ti.com

SEQUENCER REGISTER 3 (SEQ3)

Address – 0x1Bh (Password Protected)

DATA BIT		D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME		LDO2_SEQ[3:0]				LDO3_SEQ[3:0]			
READ/WRITE		R/WR	R/W	R/W	R/W	R	R/W	R/W	R/W
RESET VALUE	TPS65217A	0	0	1	0	0	0	0	1
	TPS65217B	0	0	1	0	0	0	1	1
	TPS65217C	0	0	1	1	0	0	1	0

FIELD NAME	BIT DEFINITION (TPS65217A)					
	LDO2 enable STROBE					
	0000 - rail is not controlled by sequencer					
	0001 – enable at STROBE1					
	0010 – enable at STROBE2					
	0011 – enable at STROBE3					
	0100 – enable at STROBE4					
LDO2_SEQ[3:0]	0101 – enable at STROBE5					
LD02_3LQ[3.0]	0110 – enable at STROBE6					
	0111 – enable at STROBE7					
	1000 - rail is not controlled by sequencer					
	1001 - rail is not controlled by sequencer					
	1110 – enable at STROBE14					
	1111 – enabled at STROBE15 (with SYS)					
	LS1/LDO3 enable state					
	0000 - rail is not controlled by sequencer					
	0001 – enable at STROBE1					
	0010 – enable at STROBE2					
LDO3_SEQ[3:0]	0011 – enable at STROBE3					
	0100 – enable at STROBE4					
	0101 – enable at STROBE5					
	0110 – enable at STROBE6					
	0111 – enable at STROBE7					



www.ti.com

TPS65217A, TPS65217B, TPS65217C

SLVSB64E-NOVEMBER 2011-REVISED JULY 2012

FIELD NAME	BIT DEFINITION (TPS65217B)				
	LDO2 enable STROBE				
	0000 – rail is not controlled by sequencer				
	0001 – enable at STROBE1				
	0010 – enable at STROBE2				
	0011 – enable at STROBE3				
	0100 – enable at STROBE4				
LDO2_SEQ[3:0]	0101 – enable at STROBE5				
	0110 – enable at STROBE6				
	0111 – enable at STROBE7				
	1000 – rail is not controlled by sequencer				
	1001 – rail is not controlled by sequencer				
	1110 – enable at STROBE14				
	1111 – enabled at STROBE15 (with SYS)				
	LS1/LDO3 enable state				
	0000 – rail is not controlled by sequencer				
	0001 – enable at STROBE1				
	0010 – enable at STROBE2				
LDO3_SEQ[3:0]	0011 – enable at STROBE3				
	0100 – enable at STROBE4				
	0101 – enable at STROBE5				
	0110 – enable at STROBE6				
	0111 – enable at STROBE7				

2170, 183032176

SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

FIELD NAME

LDO3_SEQ[3:0]

LDO2 enable STROBE
0000 - rail is not controlled by sequencer
0001 – enable at STROBE1
0010 – enable at STROBE2
0011 – enable at STROBE3
0100 – enable at STROBE4
0101 – enable at STROBE5
0110 – enable at STROBE6
0111 – enable at STROBE7
1000 – rail is not controlled by sequencer
1001 – rail is not controlled by sequencer
1110 – enable at STROBE14

BIT DEFINITION (TPS65217C)

	0001 – enable at STROBE1
	0010 – enable at STROBE2
	0011 – enable at STROBE3
	0100 – enable at STROBE4
LDO2 SEQ[3:0]	0101 – enable at STROBE5
LDO2_3EQ[3.0]	0110 – enable at STROBE6

1111 - enabled at STROBE15 (with SYS)

0000 - rail is not controlled by sequencer

LS1/LDO3 enable state

0001 - enable at STROBE1 0010 - enable at STROBE2 0011 - enable at STROBE3

0100 - enable at STROBE4 0101 - enable at STROBE5 0110 - enable at STROBE6 0111 - enable at STROBE7

TDS65217A	TPS65217B,	TDS65217C
1F30321/A.	IF 30321/D.	15002176

www.ti.com

ISTRUMENTS

EXAS



TPS65217A, TPS65217B, TPS65217C

SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

www.ti.com

SEQUENCER REGISTER 4 (SEQ4)

Address – 0x1Ch (Password Protected)

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME		LDO4_SEQ[3:0]				not used	not used	not used
READ/WRITE	R	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	0	1	0	0	0	0	0	0

FIELD NAME	BIT DEFINITION
	LS2/LDO4 enable STROBE
	0000 - rail is not controlled by sequencer
	0001 – enable at STROBE1
	0010 – enable at STROBE2
LDO4_SEQ[3:0]	0011 – enable at STROBE3
	0100 – enable at STROBE4
	0101 – enable at STROBE5
	0110 – enable at STROBE6
	0111 – enable at STROBE7
not used	N/A

TEXAS INSTRUMENTS

SLVSB64E - NOVEMBER 2011-REVISED JULY 2012

www.ti.com

SEQUENCER REGISTER 5 (SEQ5)

Address – 0x1Dh (Password Protected)

DATA BIT		D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME		DLY	1[1:0]	DLY2[1:0]		DLY3[1:0]		DLY4[1:0]	
READ	/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
	TPS65217A	1	0	0	0	0	0	0	0
RESET VALUE	TPS65217B	1	0	0	0	0	0	0	0
EOE	TPS65217C	0	0	1	0	0	0	0	0

FIELD NAME	BIT DEFINITION (TPS65217A, TPS65217B)
	Delay1 time
	00 – 1 ms
DLY1[1:0]	01 – 2 ms
	10 – 5 ms
	11 – 10 ms
	Delay2 time
	00 – 1 ms
DLY2[1:0]	01 – 2 ms
	10 – 5 ms
	11 – 10 ms
	Delay3 time
	00 – 1 ms
DLY3[1:0]	01 – 2 ms
	10 – 5 ms
	11 – 10 ms
	Delay4 time
	00 – 1 ms
DLY4[1:0]	01 – 2 ms
	10 – 5 ms
	11 – 10 ms



TPS65217A, TPS65217B, TPS65217C

www.ti.com

SLVSB64E - NOVEMBER 2011 - REVISED JULY 2012

FIELD NAME	BIT DEFINITION (TPS65217C)
	Delay1 time
	00 – 1 ms
DLY1[1:0]	01 – 2 ms
	10 – 5 ms
	11 – 10 ms
	Delay2 time
	00 – 1 ms
DLY2[1:0]	01 – 2 ms
	10 – 5 ms
	11 – 10 ms
	Delay3 time
	00 – 1 ms
DLY3[1:0]	01 – 2 ms
	10 – 5 ms
	11 – 10 ms
	Delay4 time
	00 – 1 ms
DLY4[1:0]	01 – 2 ms
	10 – 5 ms
	11 – 10 ms

SLVSB64E - NOVEMBER 2011-REVISED JULY 2012



www.ti.com

SEQUENCER REGISTER 6 (SEQ6)

DATA BIT	D7	D6	D5	D4	D3	D2	D1	D0
FIELD NAME	FIELD NAME DLY5[1:0]		DLY6[1:0]		not used	SEQUP	SEQDWN	INSTDWN
READ/WRITE	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
RESET VALUE	0	0	0	0	0	0	0	0

FIELD NAME	BIT DEFINITION
	Delay5 time
	00 – 1 ms
DLY5[1:0]	01 – 2 ms
	10 – 5 ms
	11 – 10 ms
	Delay6 time
	00 – 1 ms
DLY6[1:0]	01 – 2 ms
	10 – 5 ms
	11 – 10 ms
not used	N/A
SEQUP	Set this bit to 1 to trigger a power-up sequence. Bit is automatically reset to 0.
SEQDWN	Set this bit to 1 to trigger a power-down sequence. Bit is automatically reset to 0.
	Instant shut-down bit
	0 – shut-down follows reverse power-up sequence
INSTDWN	1 - all delays are bypassed and all rails are shut-down simultaneously
	NOTE: Shut-down occurs when PWR_EN pin is pulled low or SEQDWN bit is set. Only those rails controlled by the sequencer will be shut down.



www.ti.com

PACKAGING INFORMATION

Orderable Device	Status ⁽¹⁾	Package Type	Package Drawing	Pins	Package Qty	Eco Plan ⁽²⁾	Lead/ Ball Finish	MSL Peak Temp ⁽³⁾	Samples (Requires Login)
TPS65217ARSLR	ACTIVE	VQFN	RSL	48	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	
TPS65217ARSLT	ACTIVE	VQFN	RSL	48	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	
TPS65217BRSLR	ACTIVE	VQFN	RSL	48	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	
TPS65217BRSLT	ACTIVE	VQFN	RSL	48	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	
TPS65217CRSLR	PREVIEW	VQFN	RSL	48	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	
TPS65217CRSLT	PREVIEW	VQFN	RSL	48	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

⁽³⁾ MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.



5-Jul-2012

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

PACKAGE MATERIALS INFORMATION

www.ti.com

TAPE AND REEL INFORMATION

REEL DIMENSIONS

TEXAS INSTRUMENTS





TAPE AND REEL INFORMATION

TAPE DIMENSIONS



A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

*All dimensions are nominal												
Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS65217ARSLR	VQFN	RSL	48	2500	330.0	16.4	6.3	6.3	1.5	12.0	16.0	Q2
TPS65217ARSLT	VQFN	RSL	48	250	180.0	16.4	6.3	6.3	1.5	12.0	16.0	Q2
TPS65217BRSLR	VQFN	RSL	48	2500	330.0	16.4	6.3	6.3	1.5	12.0	16.0	Q2
TPS65217BRSLT	VQFN	RSL	48	250	180.0	16.4	6.3	6.3	1.5	12.0	16.0	Q2

TEXAS INSTRUMENTS

www.ti.com

PACKAGE MATERIALS INFORMATION

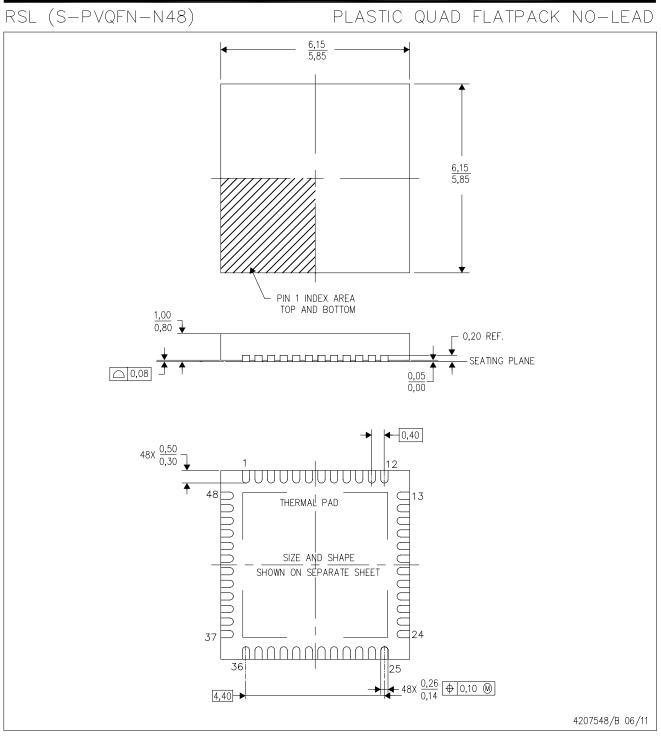
14-Jul-2012



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS65217ARSLR	VQFN	RSL	48	2500	367.0	367.0	38.0
TPS65217ARSLT	VQFN	RSL	48	250	210.0	185.0	35.0
TPS65217BRSLR	VQFN	RSL	48	2500	367.0	367.0	38.0
TPS65217BRSLT	VQFN	RSL	48	250	210.0	185.0	35.0

MECHANICAL DATA



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. Quad Flatpack, No-leads (QFN) package configuration.
- D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
- E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.



RSL (S-PVQFN-N48)

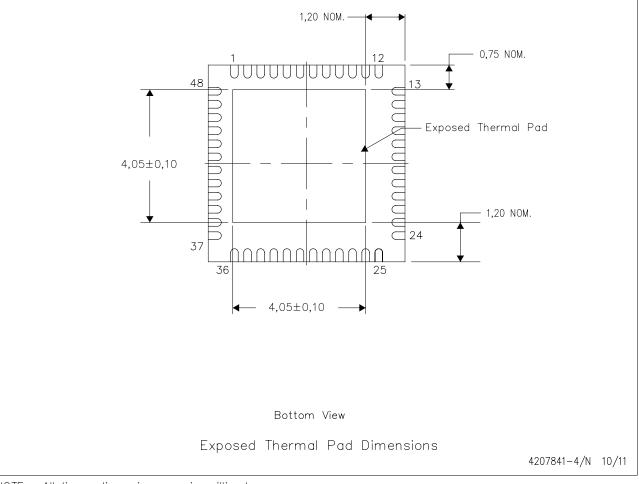
PLASTIC QUAD FLATPACK NO-LEAD

THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.

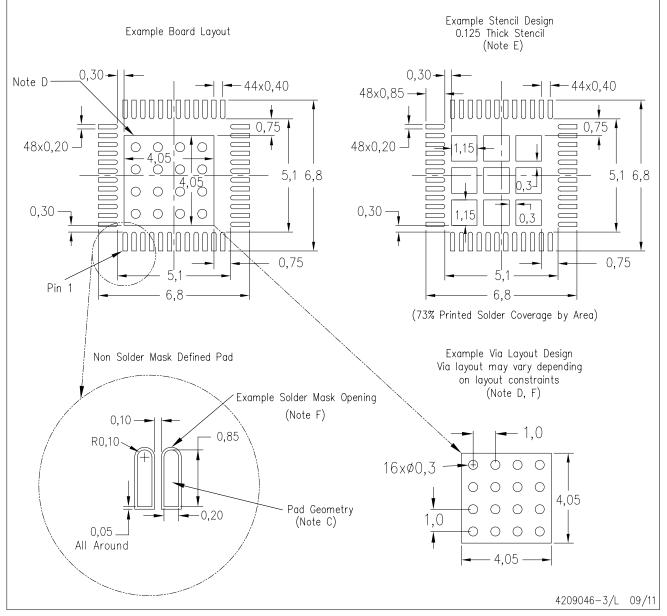


NOTE: All linear dimensions are in millimeters



RSL (S-PVQFN-N48)

PLASTIC QUAD FLATPACK NO-LEAD



- NOTES: A. All linear dimensions are in millimeters.
 - B. This drawing is subject to change without notice.
 - C. Publication IPC-7351 is recommended for alternate designs.
 - D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com http://www.ti.com.
 - E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
 - F. Customers should contact their board fabrication site for recommended solder mask tolerances and via tenting recommendations for vias placed in the thermal pad.



IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46C and to discontinue any product or service per JESD48B. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products (also referred to herein as "components") are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its components to the specifications applicable at the time of sale, in accordance with the warranty in TI's terms and conditions of sale of semiconductor products. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by applicable law, testing of all parameters of each component is not necessarily performed.

TI assumes no liability for applications assistance or the design of Buyers' products. Buyers are responsible for their products and applications using TI components. To minimize the risks associated with Buyers' products and applications, Buyers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI components or services are used. Information published by TI regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of significant portions of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI components or services with statements different from or beyond the parameters stated by TI for that component or service voids all express and any implied warranties for the associated TI component or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of TI components in its applications, notwithstanding any applications-related information or support that may be provided by TI. Buyer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Buyer will fully indemnify TI and its representatives against any damages arising out of the use of any TI components in safety-critical applications.

In some cases, TI components may be promoted specifically to facilitate safety-related applications. With such components, TI's goal is to help enable customers to design and create their own end-product solutions that meet applicable functional safety standards and requirements. Nonetheless, such components are subject to these terms.

No TI components are authorized for use in FDA Class III (or similar life-critical medical equipment) unless authorized officers of the parties have executed a special agreement specifically governing such use.

Only those TI components which TI has specifically designated as military grade or "enhanced plastic" are designed and intended for use in military/aerospace applications or environments. Buyer acknowledges and agrees that any military or aerospace use of TI components which have *not* been so designated is solely at the Buyer's risk, and that Buyer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI has specifically designated certain components which meet ISO/TS16949 requirements, mainly for automotive use. Components which have not been so designated are neither designed nor intended for automotive use; and TI will not be responsible for any failure of such components to meet such requirements.

Products		Applications	
Audio	www.ti.com/audio	Automotive and Transportation	www.ti.com/automotive
Amplifiers	amplifier.ti.com	Communications and Telecom	www.ti.com/communications
Data Converters	dataconverter.ti.com	Computers and Peripherals	www.ti.com/computers
DLP® Products	www.dlp.com	Consumer Electronics	www.ti.com/consumer-apps
DSP	dsp.ti.com	Energy and Lighting	www.ti.com/energy
Clocks and Timers	www.ti.com/clocks	Industrial	www.ti.com/industrial
Interface	interface.ti.com	Medical	www.ti.com/medical
Logic	logic.ti.com	Security	www.ti.com/security
Power Mgmt	power.ti.com	Space, Avionics and Defense	www.ti.com/space-avionics-defense
Microcontrollers	microcontroller.ti.com	Video and Imaging	www.ti.com/video
RFID	www.ti-rfid.com		
OMAP Mobile Processors	www.ti.com/omap	TI E2E Community	e2e.ti.com
Wireless Connectivity	www.ti.com/wirelessconnectivity		

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2012, Texas Instruments Incorporated