FEATURES

- **1-of-4 Bidirectional Translating Switches**
- **I²C Bus and SMBus Compatible**
- **Active-Low Reset Input**
- **Three Address Pins, Allowing up to Eight Devices on the I²C Bus**
- **Channel Selection Via I²C Bus**
- **Power Up With All Switch Channels Deselected**
- **Low R_{ON} Switches**
- **Allows Voltage-Level Translation Between 1.8-V, 2.5-V, 3.3-V, and 5-V Buses**
- **No Glitch on Power Up**
- **Supports Hot Insertion**
- **Low Standby Current**
- **Operating Power-Supply Voltage Range of 2.3 V to 5.5 V**
- **5.5-V Tolerant Inputs**
- **0 to 400-kHz Clock Frequency**
- **Latch-Up Performance Exceeds 100 mA Per JESD 78**
- **ESD Protection Exceeds JESD 22**
  - **2000-V Human-Body Model (A114-A)**
  - **200-V Machine Model (A115-A)**
  - **1000-V Charged-Device Model (C101)**

DESCRIPTION/ORDERING INFORMATION

The PCA9546A is a quad bidirectional translating switch controlled via the I²C bus. The SCL/SDA upstream pair fans out to four downstream pairs, or channels. Any individual SCn/SDn channel or combination of channels can be selected, determined by the contents of the programmable control register.

An active-low reset ($\overline{\text{RESET}}$) input allows the PCA9546A to recover from a situation in which one of the downstream I²C buses is stuck in a low state. Pulling $\overline{\text{RESET}}$ low resets the I²C state machine and causes all the channels to be deselected, as does the internal power-on reset function.

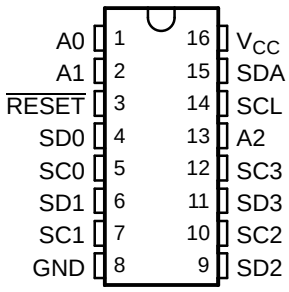
The pass gates of the switches are constructed such that the V_{CC} pin can be used to limit the maximum high voltage, which will be passed by the PCA9546A. This allows the use of different bus voltages on each pair, so that 1.8-V, 2.5-V, or 3.3-V parts can communicate with 5-V parts without any additional protection. External pullup resistors pull the bus up to the desired voltage level for each channel. All I/O pins are 5.5-V tolerant.

ORDERING INFORMATION

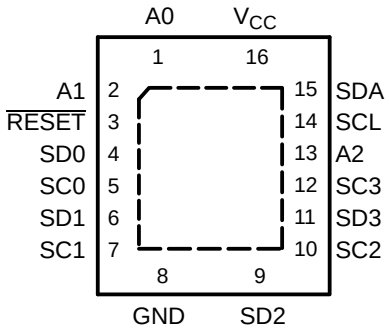
T_A	PACKAGE(1)		ORDERABLE PART NUMBER	TOP-SIDE MARKING
–40°C to 85°C	QFN – RGV	Reel of 3000	PCA9546ARVR	PREVIEW
	QFN – RGY	Reel of 1000	PCA9546ARGYR	PD546A
	SOIC – DW	Tube of 40	PCA9546ADW	PCA9546A
		Reel of 2000	PCA9546ADWR	
		Reel of 250	PCA9546ADWT	PREVIEW
	TSSOP – PW	Tube of 90	PCA9546APW	PD546A
		Reel of 2000	PCA9546APWR	
		Reel of 250	PCA9546APWT	
	TVSOP – DGV	Reel of 2000	PCA9546ADGVR	PD546A
		Reel of 250	PCA9546ADGVT	PREVIEW

(1) Package drawings, standard packing quantities, thermal data, symbolization, and PCB design guidelines are available at www.ti.com/sc/package.

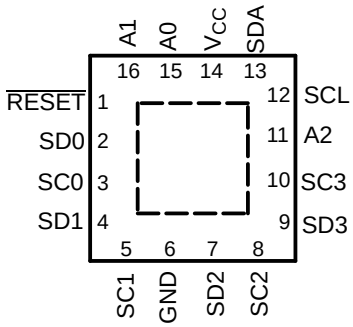
DGV, DW, OR PW PACKAGE
(TOP VIEW)



RGY PACKAGE
(TOP VIEW)



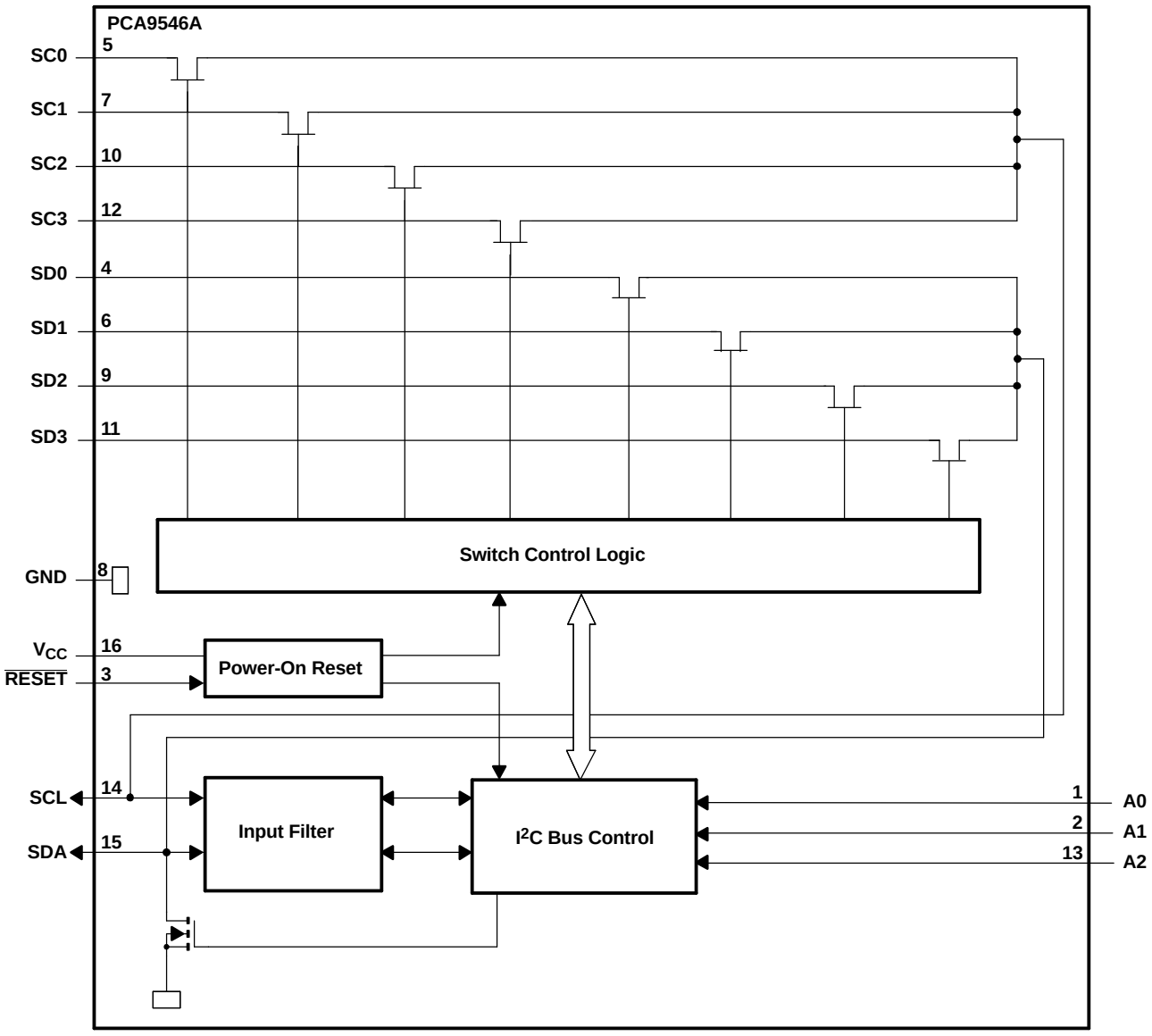
RGV PACKAGE
(TOP VIEW)



TERMINAL FUNCTIONS

NO.		NAME	DESCRIPTION
DGV, DW, PW, AND RGY	RGV		
1	15	A0	Address input 0
2	16	A1	Address input 1
3	1	$\overline{\text{RESET}}$	Active low reset input
4	2	SD0	Serial data 0
5	3	SC0	Serial clock 0
6	4	SD1	Serial data 1
7	5	SC1	Serial clock 1
8	6	GND	Ground
9	7	SD2	Serial data 2
10	8	SC2	Serial clock 2
11	9	SD3	Serial data 3
12	10	SC3	Serial clock 3
13	11	A2	Address input 2
14	12	SCL	Serial clock line
15	13	SDA	Serial data line
16	14	V_{CC}	Supply power

BLOCK DIAGRAM



Pin numbers shown are for the DGV, DW, PW, and RGY packages.

Device Address

Following a start condition, the bus master must output the address of the slave it is accessing. The address of the PCA9546A is shown in Figure 1. To conserve power, no internal pullup resistors are incorporated on the hardware-selectable address pins, and they must be pulled high or low.

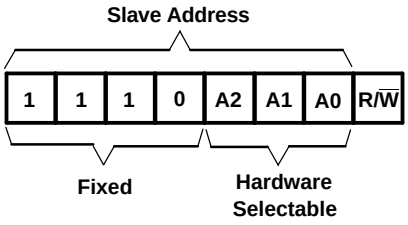


Figure 1. PCA9545A Address

The last bit of the slave address defines the operation to be performed. When set to a logic 1, a read is selected, while a logic 0 selects a write operation.

Control Register

Following the successful acknowledgment of the slave address, the bus master sends a byte to the PCA9546A, which is stored in the control register (see Figure 2). If multiple bytes are received by the PCA9546A, it will save the last byte received. This register can be written and read via the I²C bus.

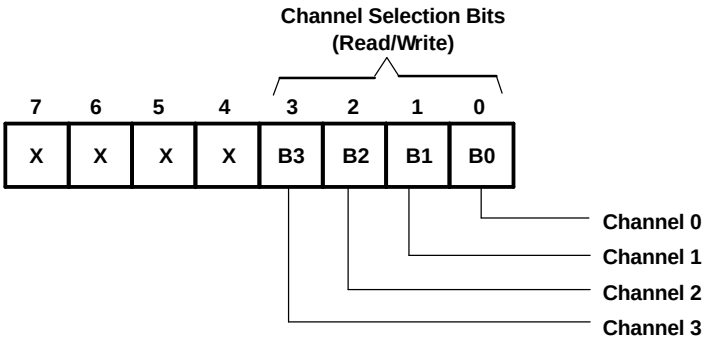


Figure 2. Control Register

Control Register Definition

One or several SCn/SDn downstream pairs, or channels, are selected by the contents of the control register (see Table 1). This register is written after the PCA9546A has been addressed. The four LSBs of the control byte are used to determine which channel or channels are to be selected. When a channel is selected, the channel becomes active after a stop condition has been placed on the I²C bus. This ensures that all SCn/SDn lines are in a high state when the channel is made active, so that no false conditions are generated at the time of connection. A stop condition always must occur right after the acknowledge cycle.

Table 1. Control Register Write (Channel Selection), Control Register Read (Channel Status)(1)

B7	B6	B5	B4	B3	B2	B1	B0	COMMAND
X	X	X	X	X	X	X	0	Channel 0 disabled
							1	Channel 0 enabled
X	X	X	X	X	X	0	X	Channel 1 disabled
						1		Channel 1 enabled
X	X	X	X	X	0	X	X	Channel 2 disabled
					1			Channel 2 enabled
X	X	X	X	0	X	X	X	Channel 3 disabled
				1				Channel 3 enabled
0	0	0	0	0	0	0	0	No channel selected, power-up/reset default state

(1) Several channels can be enabled at the same time. For example, B3 =0, B2 = 1, B1 = 1, B0 = 0 means that channels 0 and 3 are disabled, and channels 1 and 2 are enabled. Care should be taken not to exceed the maximum bus capacity.

$\overline{\text{RESET}}$ Input

The $\overline{\text{RESET}}$ input is an active-low signal that may be used to recover from a bus-fault condition. When this signal is asserted low for a minimum of t_{WL}, the PCA9446A resets its registers and I²C state machine and deselects all channels. The $\overline{\text{RESET}}$ input must be connected to V_{CC} through a pullup resistor.

Power-On Reset

When power is applied to V_{CC}, an internal power-on reset holds the PCA9546A in a reset condition until V_{CC} has reached V_{POR}. At this point, the reset condition is released, and the PCA9546A registers and I²C state machine are initialized to their default states, all zeroes, causing all the channels to be deselected. Thereafter, V_{CC} must be lowered below 0.2 V to reset the device.

Voltage Translation

The pass-gate transistors of the PCA9546A are constructed such that the V_{CC} voltage can be used to limit the maximum voltage that will be passed from one I²C bus to another.

Figure 3 shows the voltage characteristics of the pass-gate transistors (note that the graph was generated using the data specified in the electrical characteristics section of this data sheet). In order for the PCA9546A to act as a voltage translator, the V_{pass} voltage must be equal to or lower than the lowest bus voltage. For example, if the main bus is running at 5 V, and the downstream buses are 3.3 V and 2.7 V, then V_{pass} must be equal to or below 2.7 V to effectively clamp the downstream bus voltages. As shown in Figure 3, V_{pass} (max) is at 2.7 V when the PCA9546A supply voltage is 3.5 V or lower, so the PCA9546A supply voltage could be set to 3.3 V. Pullup resistors then can be used to bring the bus voltages to their appropriate levels (see Figure 12).

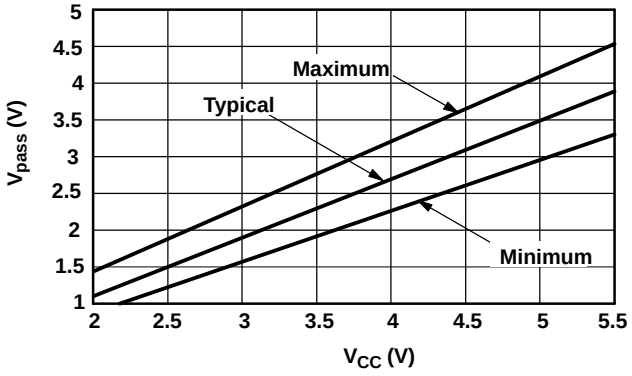


Figure 3. V_{pass} Voltage vs V_{CC}

I²C Interface

The I²C bus is for two-way two-line communication between different ICs or modules. The two lines are a serial data line (SDA) and a serial clock line (SCL). Both lines must be connected to a positive supply via a pullup resistor when connected to the output stages of a device. Data transfer can be initiated only when the bus is not busy.

One data bit is transferred during each clock pulse. The data on the SDA line must remain stable during the high period of the clock pulse, as changes in the data line at this time are interpreted as control signals (see Figure 4).

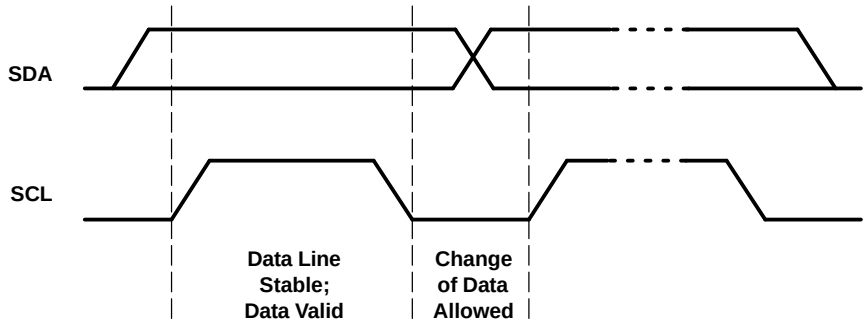


Figure 4. Bit Transfer

Both data and clock lines remain high when the bus is not busy. A high-to-low transition of the data line while the clock is high is defined as the start condition (S). A low-to-high transition of the data line while the clock is high is defined as the stop condition (P) (see Figure 5).

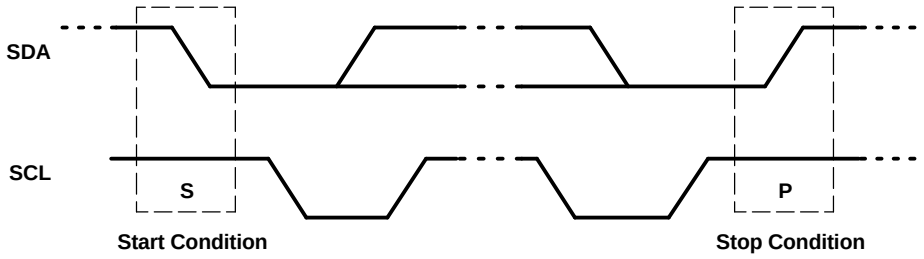


Figure 5. Definition of Start and Stop Conditions

A device generating a message is a transmitter; a device receiving is the receiver. The device that controls the message is the master, and the devices that are controlled by the master are the slaves (see Figure 6).

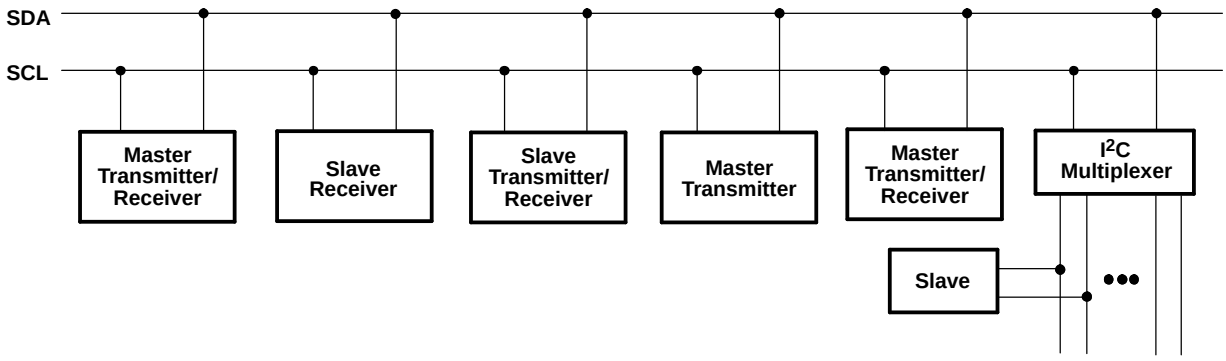


Figure 6. System Configuration

The number of data bytes transferred between the start and the stop conditions from transmitter to receiver is not limited. Each byte of eight bits is followed by one acknowledge (ACK) bit. The transmitter must release the SDA line before the receiver can send an ACK bit.

When a slave receiver is addressed, it must generate an ACK after the reception of each byte. Also, a master must generate an ACK after the reception of each byte that has been clocked out of the slave transmitter. The device that acknowledges must pull down the SDA line during the ACK clock pulse so that the SDA line is stable low during the high pulse of the ACK-related clock period (see Figure 7). Setup and hold times must be taken into account.

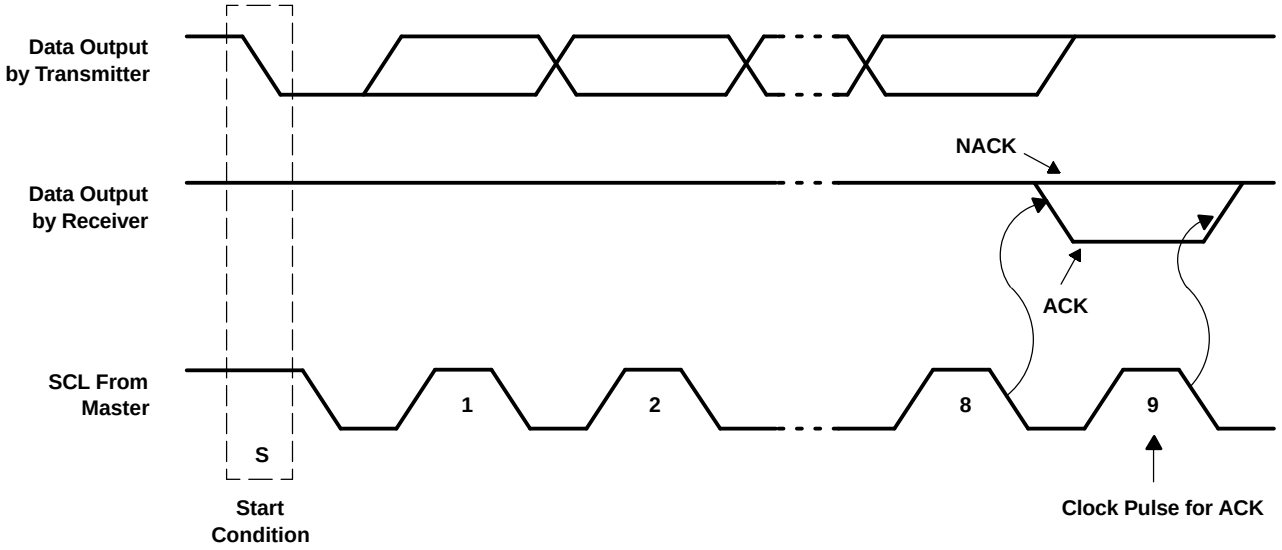


Figure 7. Acknowledgment on the I²C Bus

Data is transmitted to the PCA9546A control register using the write mode shown in Figure 8.

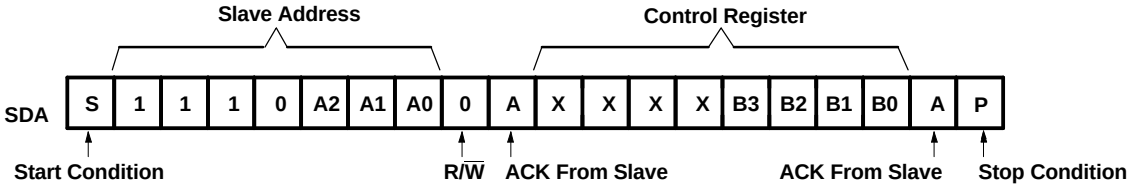


Figure 8. Write Control Register

Data is read from the PCA9546A control register using the read mode shown in Figure 9.

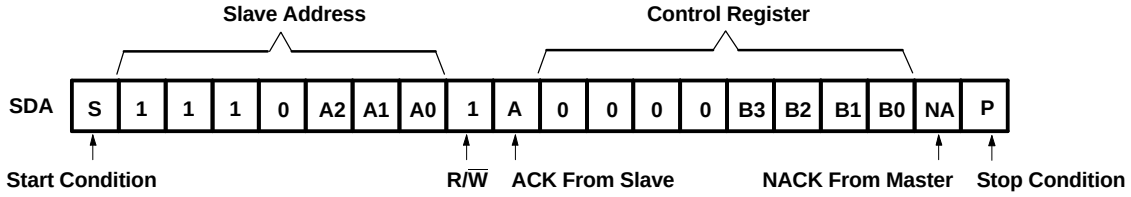


Figure 9. Read Control Register

Absolute Maximum Ratings(1)

over operating free-air temperature range (unless otherwise noted)

			MIN	MAX	UNIT
V_{CC}	Supply voltage range		–0.5	7	V
V_I	Input voltage range(2)		–0.5	7	V
I_I	Input current			±20	mA
I_O	Output current			±25	mA
	Continuous current through V_{CC}			±100	mA
	Continuous current through GND			±100	mA
θ_{JA}	Package thermal impedance(3)	DGV package		120	°C/W
		DW package		57	
		PW package		108	
		RGV package		TBD	
		RGY package		50	
P_{tot}	Total power dissipation			400	mW
T_{stg}	Storage temperature range		–65	150	°C
T_A	Operating free-air temperature range		–40	85	°C

(1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
(2) The input negative-voltage and output voltage ratings may be exceeded if the input and output current ratings are observed.
(3) The package thermal impedance is calculated in accordance with JESD 51-7.

Recommended Operating Conditions(1)

			MIN	MAX	UNIT
V_{CC}	Supply voltage		2.3	5.5	V
V_{IH}	High-level input voltage	SCL, SDA	$0.7 \times V_{CC}$	6	V
		A2–A0, $\overline{\text{RESET}}$	$0.7 \times V_{CC}$	V_{CC} + 0.5	
V_{IL}	Low-level input voltage	SCL, SDA	–0.5	$0.3 \times V_{CC}$	V
		A2–A0, $\overline{\text{RESET}}$	–0.5	$0.3 \times V_{CC}$	
T_A	Operating free-air temperature		–40	85	°C

(1) All unused inputs of the device must be held at V_{CC} or GND to ensure proper device operation. Refer to the TI application report, *Implications of Slow or Floating CMOS Inputs*, literature number SCBA004.

Electrical Characteristics

over recommended operating free-air temperature range (unless otherwise noted)

PARAMETER			TEST CONDITIONS		V_{CC}	MIN	TYP(1)	MAX	UNIT
V_{POR}	Power-on reset voltage(2)		No load,	$V_I = V_{CC}$ or GND	V_{POR}		1.6	2.1	V
V_{pass}	Switch output voltage		$V_{SWin} = V_{CC}$,	$I_{SWout} = -100\ \mu A$	5 V		3.6		V
					4.5 V to 5.5 V	2.6		4.5	
					3.3 V		1.9		
					3 V to 3.6 V	1.6		2.8	
					2.5 V		1.5		
					2.3 V to 2.7 V	1.1		2	
I_{OL}	SCL, SDA		V_{OL} = 0.4 V		2.3 V to 5.5 V	3	7		mA
			V_{OL} = 0.6 V			6	10		
I_I	SCL, SDA		$V_I = V_{CC}$ or GND		2.3 V to 5.5 V			±1	µA
	SC3–SC0, SD3–SD0							±1	
	A2–A0							±1	
	$\overline{RESET}$							±1	
I_{CC}	Operating mode	f_{SCL} = 100 kHz	$V_I = V_{CC}$ or GND,	$I_O = 0$	5.5 V		3	12	µA
					3.6 V		3	11	
					2.7 V		3	10	
	Standby mode	Low inputs	V_I = GND,	$I_O = 0$	5.5 V		0.3	1	
					3.6 V		0.1	1	
					2.7 V		0.1	1	
		High inputs	$V_I = V_{CC}$,	$I_O = 0$	5.5 V		0.3	1	
					3.6 V		0.1	1	
					2.7 V		0.1	1	
ΔI_{CC}	Supply-current change	SCL, SDA	SCL or SDA input at 0.6 V, Other inputs at V_{CC} or GND				8	15	µA
			SCL or SDA input at V_{CC} – 0.6 V, Other inputs at V_{CC} or GND		2.3 V to 5.5 V		8	15	
C_i	A2–A0		$V_I = V_{CC}$ or GND		2.3 V to 5.5 V		4.5	6	pF
	$\overline{RESET}$						4.5	5.5	
$C_{io(OFF)}$(3)	SCL, SDA		$V_I = V_{CC}$ or GND,	Switch OFF	2.3 V to 5.5 V		15	19	pF
	SC3–SC0, SD3–SD0						6	8	
R_{ON}	Switch on-state resistance		V_O = 0.4 V,	I_O = 15 mA	4.5 V to 5.5 V	4	9	16	Ω
					3 V to 3.6 V	5	11	20	
			V_O = 0.4 V,	I_O = 10 mA	2.3 V to 2.7 V	7	16	45	

(1) All typical values are at nominal supply voltage (2.5-V, 3.3-V, or 5-V V_{CC}), T_A = 25°C.
(2) The power-on reset circuit resets the I²C bus logic with $V_{CC} < V_{POR}$. V_{CC} must be lowered to 0.2 V to reset the device.
(3) $C_{io(ON)}$ depends on internal capacitance and external capacitance added to the SCn lines when channels(s) are ON.

I²C Interface Timing Requirements

over recommended operating free-air temperature range (unless otherwise noted) (see Figure 10)

			STANDARD MODE I²C BUS		FAST MODE I²C BUS		UNIT
			MIN	MAX	MIN	MAX	
f_{scl}	I²C clock frequency		0	100	0	400	kHz
t_{sch}	I²C clock high time		4		0.6		µs
t_{scl}	I²C clock low time		4.7		1.3		µs
t_{sp}	I²C spike time			50		50	ns
t_{sds}	I²C serial-data setup time		250		100		ns
t_{sdh}	I²C serial-data hold time		0(1)		0(1)		µs
t_{icr}	I²C input rise time			1000	20 + 0.1C_b(2)	300	ns
t_{icf}	I²C input fall time			300	20 + 0.1C_b(2)	300	ns
t_{ocf}	I²C output fall time	10-pF to 400-pF bus		300	20 + 0.1C_b(2)	300	ns
t_{buf}	I²C bus free time between stop and start		4.7		1.3		µs
t_{sts}	I²C start or repeated start condition setup		4.7		0.6		µs
t_{sth}	I²C start or repeated start condition hold		4		0.6		µs
t_{sps}	I²C stop condition setup		4		0.6		µs
$t_{vdL(Data)}$	Valid-data time (high to low)(3)	SCL low to SDA output low valid		1		1	µs
$t_{vdH(Data)}$	Valid-data time (low to high)(3)	SCL low to SDA output high valid		0.6		0.6	µs
$t_{vd(ack)}$	Valid-data time of ACK condition	ACK signal from SCL low to SDA output low		1		1	µs
C_b	I²C bus capacitive load			400		400	pF

(1) A device internally must provide a hold time of at least 300 ns for the SDA signal (referred to the V_{IH} min of the SCL signal), in order to bridge the undefined region of the falling edge of SCL.
(2) C_b = total bus capacitance of one bus line in pF
(3) Data taken using a 1-kΩ pullup resistor and 50-pF load (see Figure 10)

Switching Characteristics

over recommended operating free-air temperature range, $C_L \leq 100$ pF (unless otherwise noted) (see Figure 10)

PARAMETER			FROM (INPUT)	TO (OUTPUT)	MIN	MAX	UNIT
t_{pd}(1)	Propagation delay time	R_{ON} = 20 Ω, C_L = 15 pF	SDA or SCL	SDn or SCn		0.3	ns
		R_{ON} = 20 Ω, C_L = 50 pF				1	

(1) The propagation delay is the calculated RC time constant of the typical ON-state resistance of the switch and the specified load capacitance, when driven by an ideal voltage source (zero output impedance).

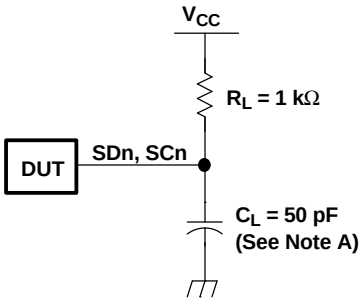
Interrupt and Reset Timing Requirements

over recommended operating free-air temperature range (unless otherwise noted)

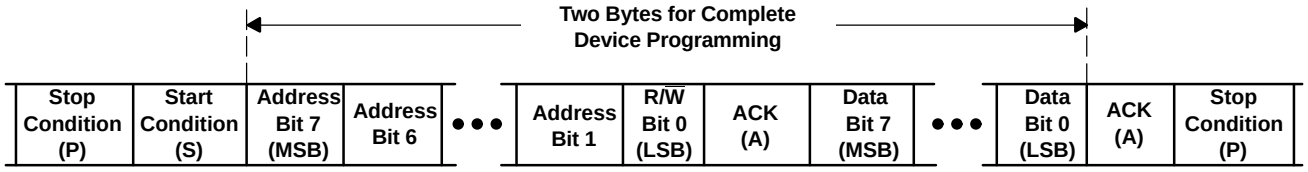
PARAMETER		MIN	MAX	UNIT
t_{WL}	Pulse duration, $\overline{\text{RESET}}$ low	6		ns
t_{rst}(1)	$\overline{\text{RESET}}$ time (SDA clear)		500	ns
$t_{REC(STA)}$	Recovery time from $\overline{\text{RESET}}$ to start	0		ns

(1) t_{rst} is the propagation delay measured from the time the $\overline{\text{RESET}}$ pin is first asserted low to the time the SDA pin is asserted high, signaling a stop condition. It must be a minimum of t_{WL}.

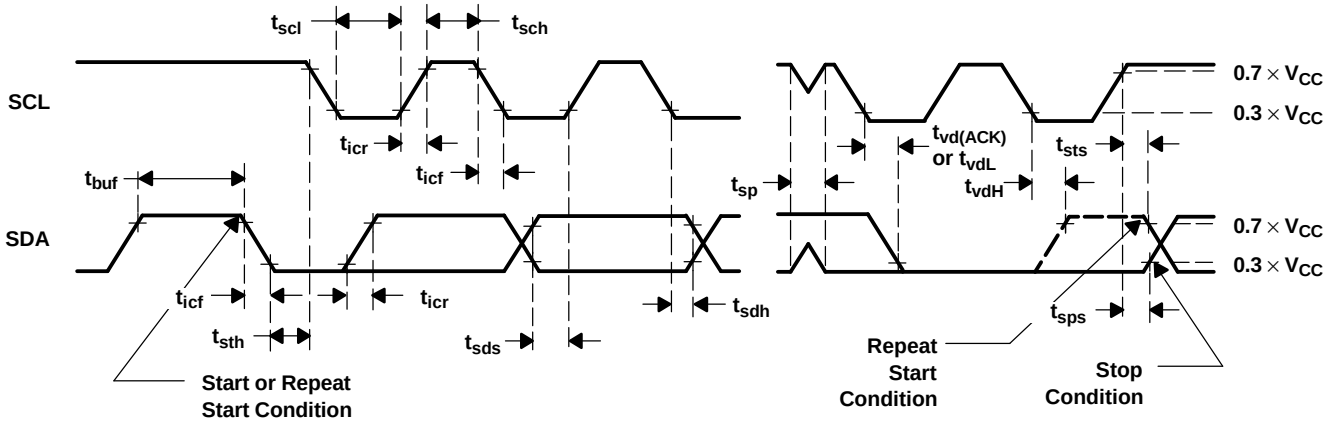
PARAMETER MEASUREMENT INFORMATION



I²C PORT LOAD CONFIGURATION



BYTE	DESCRIPTION
1	I²C address + R/W
2	Control register data



VOLTAGE WAVEFORMS

A. C_L includes probe and jig capacitance.

B. All input pulses are supplied by generators having the following characteristics: PRR ≤ 10 MHz, Z_O = 50 Ω, t_r/t_f ≤ 30 ns.

C. The outputs are measured one at a time, with one transition per measurement.

Figure 10. I²C Interface Load Circuit, Byte Descriptions, and Voltage Waveforms

PARAMETER MEASUREMENT INFORMATION (continued)

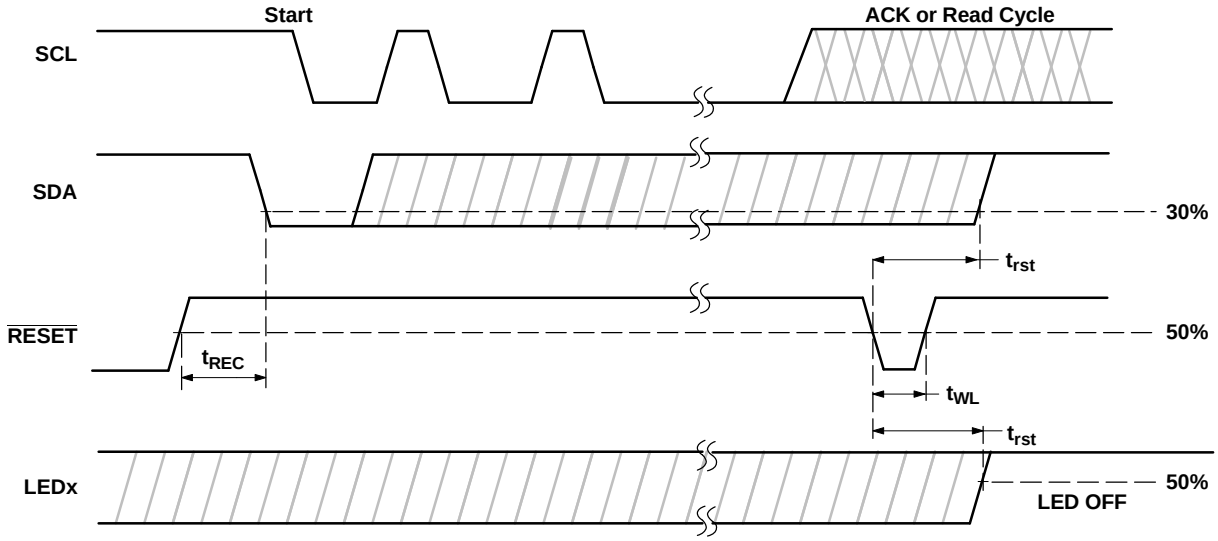
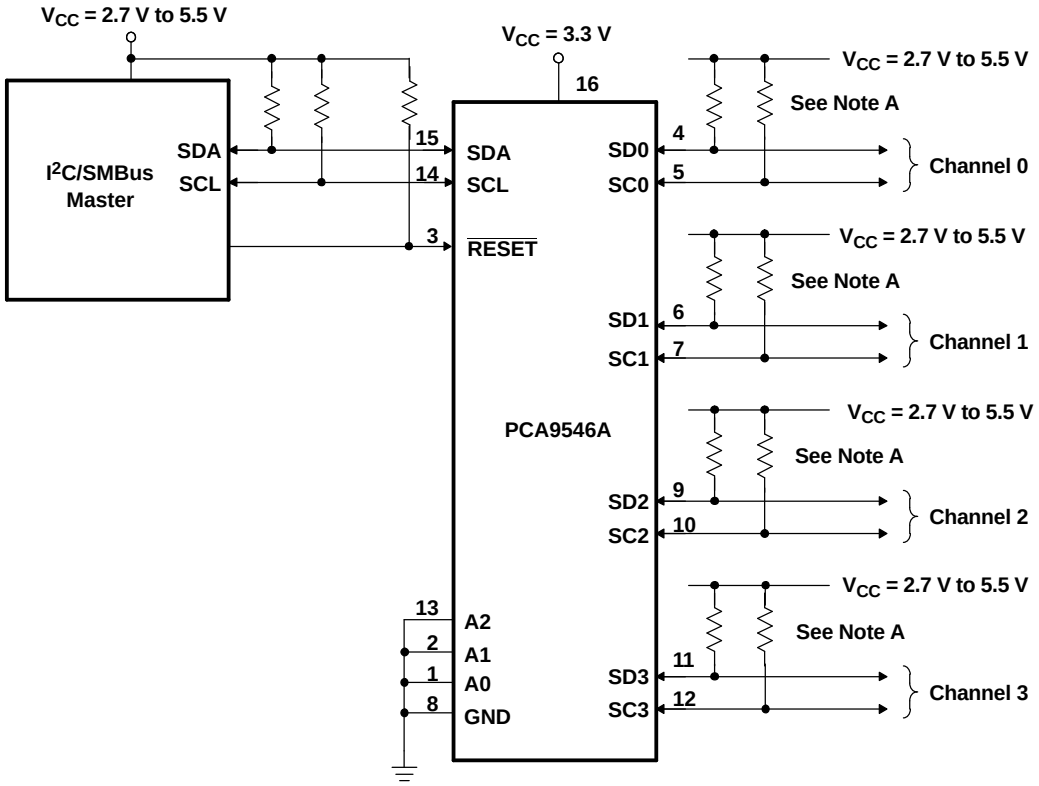


Figure 11. Reset Timing

APPLICATION INFORMATION

Figure 12 shows an application in which the PCA9546A can be used.



A. Pin numbers shown are for the DGV, DW, PW, and RGY packages.

Figure 12. Typical Application

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish	MSL Peak Temp (3)
PCA9546ADGVR	ACTIVE	TVSOP	DGV	16	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9546ADGVT	PREVIEW	TVSOP	DGV	20	250	TBD	Call TI	Call TI
PCA9546ADW	ACTIVE	SOIC	DW	16	40	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9546ADWR	ACTIVE	SOIC	DW	16	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9546ADWT	PREVIEW	SOIC	DW	16	250	TBD	Call TI	Call TI
PCA9546AGQNR	PREVIEW	BGA MICROSTAR JUNIOR	GQN	20	1000	TBD	Call TI	Call TI
PCA9546APW	ACTIVE	TSSOP	PW	16	90	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9546APWE4	ACTIVE	TSSOP	PW	16	90	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9546APWR	ACTIVE	TSSOP	PW	16	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9546APWRE4	ACTIVE	TSSOP	PW	16	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9546APWT	ACTIVE	TSSOP	PW	16	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9546APWTE4	ACTIVE	TSSOP	PW	16	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9546ARGWR	PREVIEW	QFN	RGW	20	3000	TBD	Call TI	Call TI
PCA9546ARGYR	ACTIVE	QFN	RGY	16	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1YEAR
PCA9546AZQNR	PREVIEW	BGA MICROSTAR JUNIOR	ZQN	20	1000	TBD	Call TI	Call TI

(1) The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.
TBD: The Pb-Free/Green conversion plan has not been defined.
Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.
Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.
Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder

temperature.

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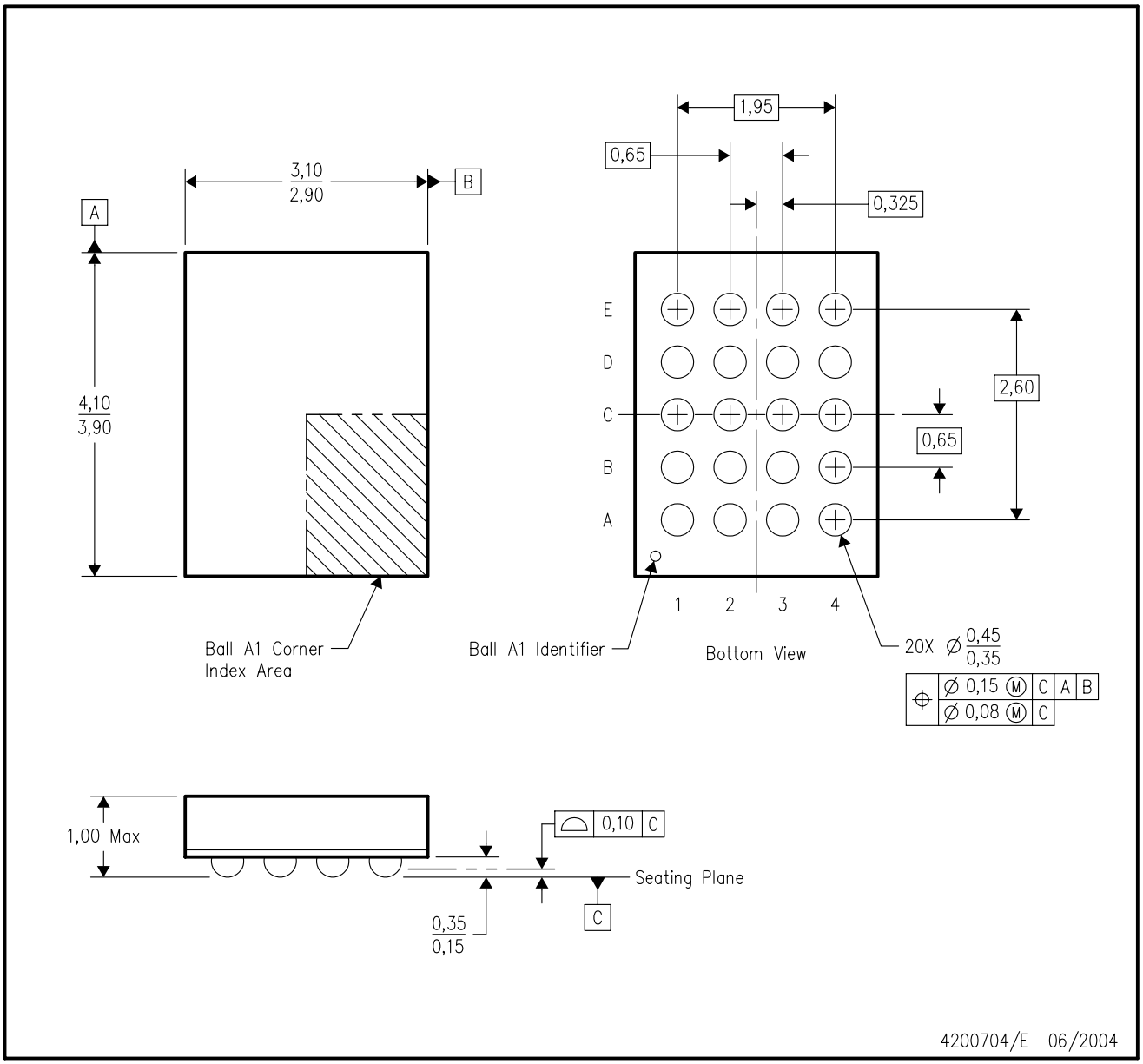
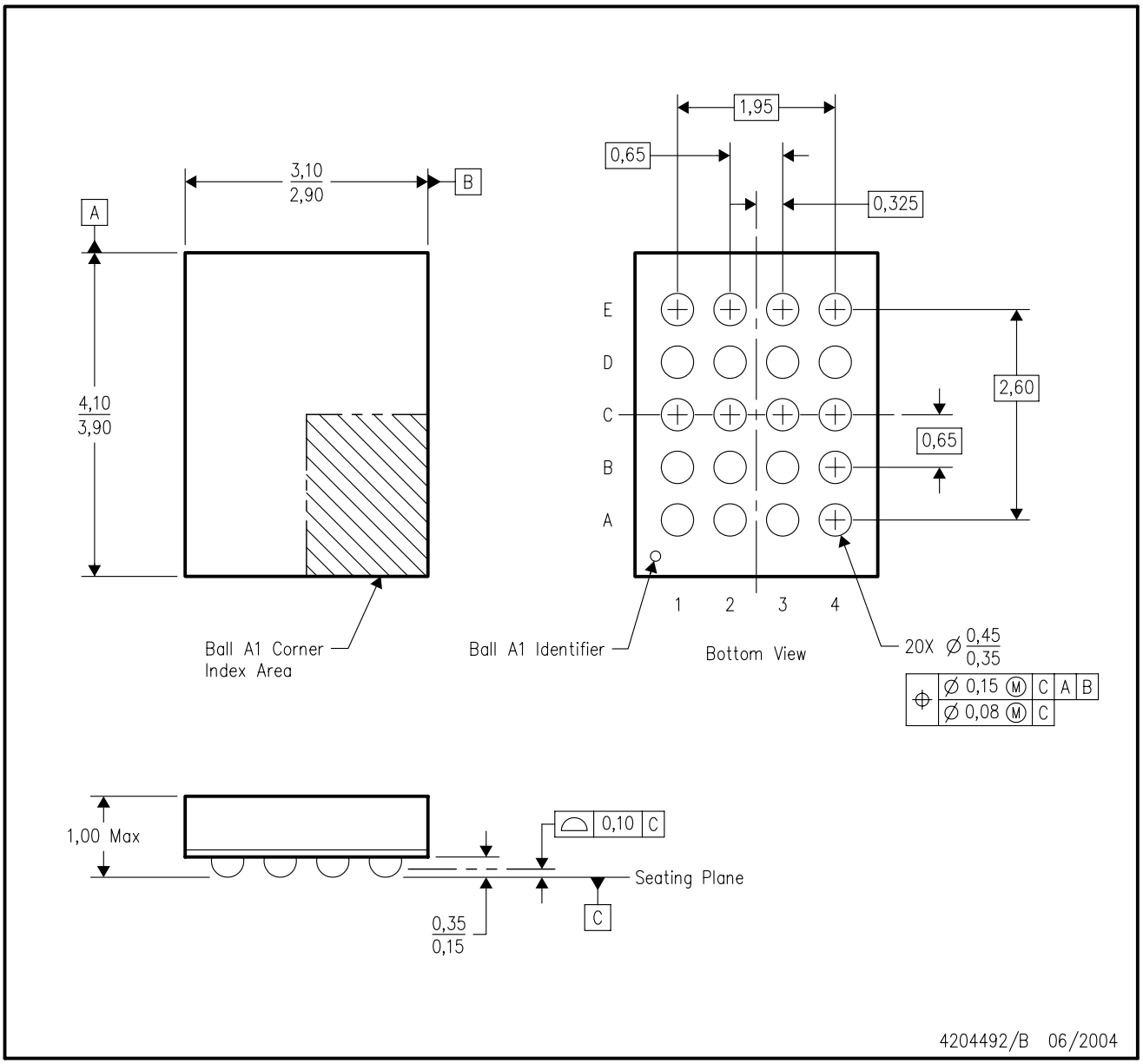
GQN (R–PBGA–N20) PLASTIC BALL GRID ARRAY



NOTES:
A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Falls within JEDEC MO–225 variation BC.
D. This package is tin–lead (SnPb). Refer to the 20 ZQN package (drawing 4204492) for lead–free.

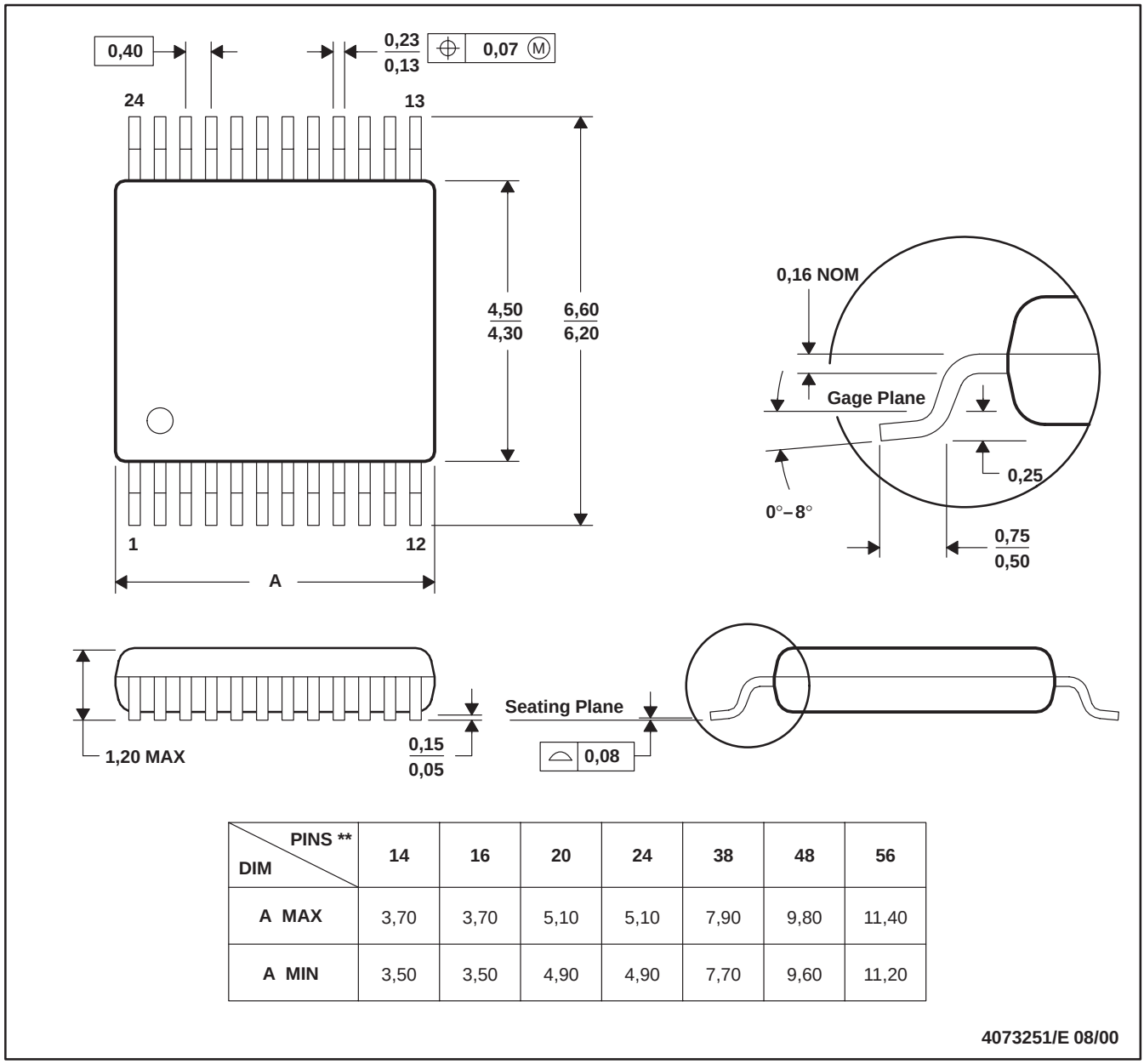
ZQN (R–PBGA–N20) PLASTIC BALL GRID ARRAY



NOTES:
A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Falls within JEDEC MO–225 variation BC.
D. This package is lead–free. Refer to the 20 GQN package (drawing 4200704) for tin–lead (SnPb).

DGV (R-PDSO-G)** **PLASTIC SMALL-OUTLINE**

24 PINS SHOWN



DIM \ PINS **	14	16	20	24	38	48	56
A MAX	3,70	3,70	5,10	5,10	7,90	9,80	11,40
A MIN	3,50	3,50	4,90	4,90	7,70	9,60	11,20

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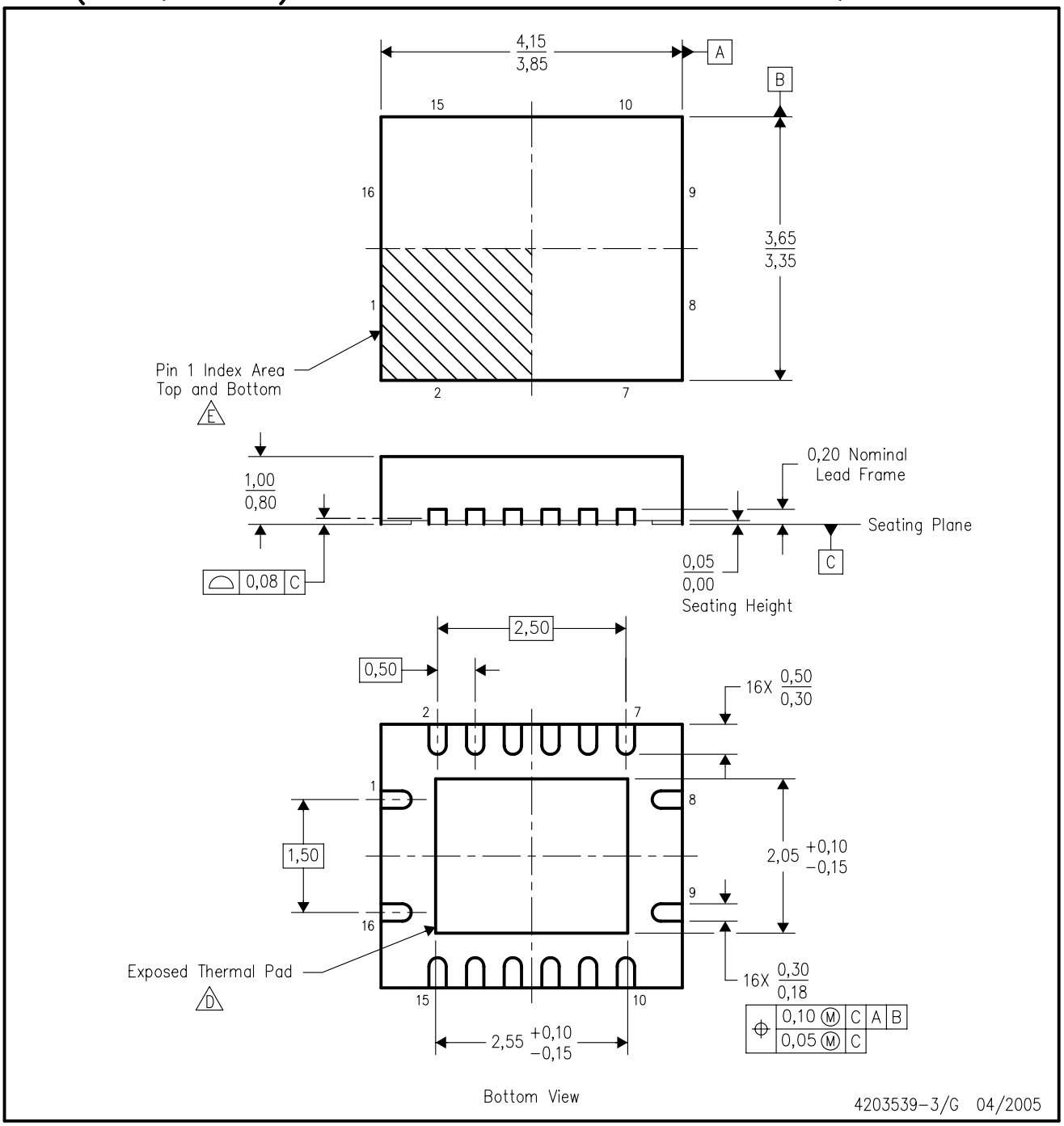
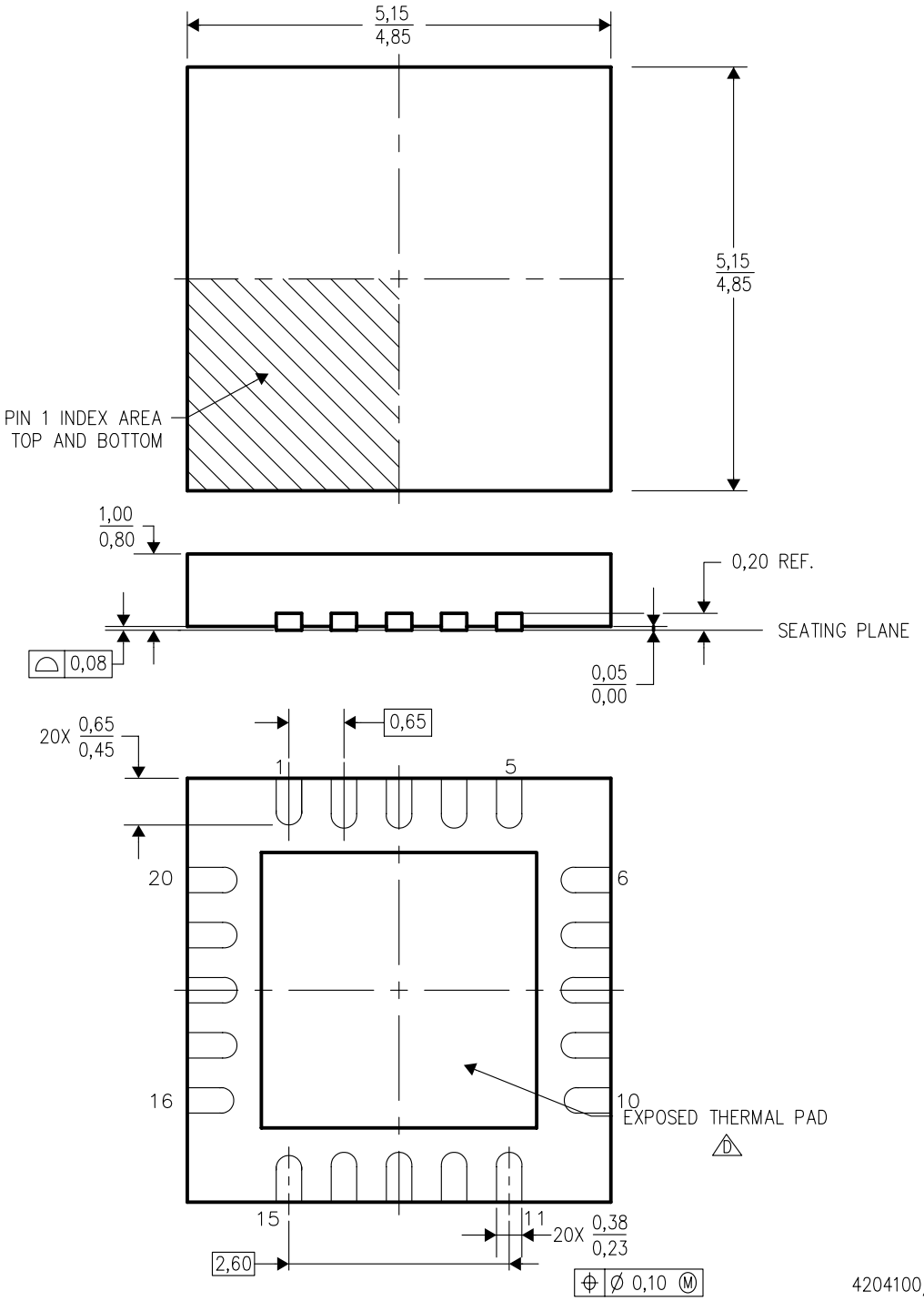
NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion, not to exceed 0,15 per side.
D. Falls within JEDEC: 24/48 Pins – MO-153
14/16/20/56 Pins – MO-194

RGY (R–PQFP–N16) PLASTIC QUAD FLATPACK



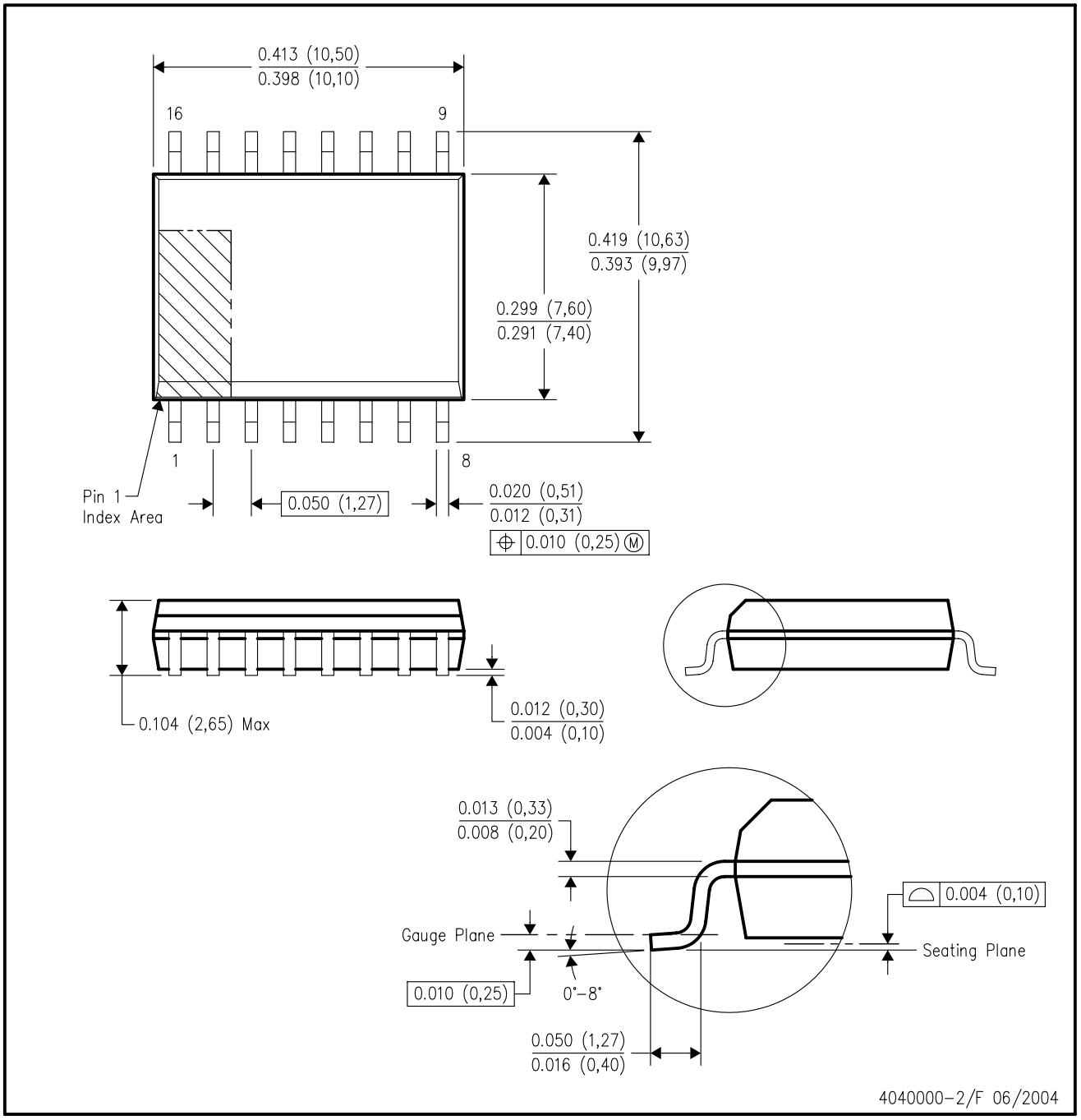
NOTES:
A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M–1994.
B. This drawing is subject to change without notice.
C. QFN (Quad Flatpack No–Lead) package configuration.
D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
E. Pin 1 identifiers are located on both top and bottom of the package and within the zone indicated. The Pin 1 identifiers are either a molded, marked, or metal feature.
F. Package complies to JEDEC MO–241 variation BB.

RGW (S–PQFP–N20) PLASTIC QUAD FLATPACK



NOTES:
A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5–1994.
B. This drawing is subject to change without notice.
C. Quad Flat pack, No–leads (QFN) package configuration
D. The package thermal pad must be soldered to the board for thermal and mechanical performance.. See the Product Data Sheet for details regarding the exposed thermal pad dimensions.
E. Falls within JEDEC MO–220.

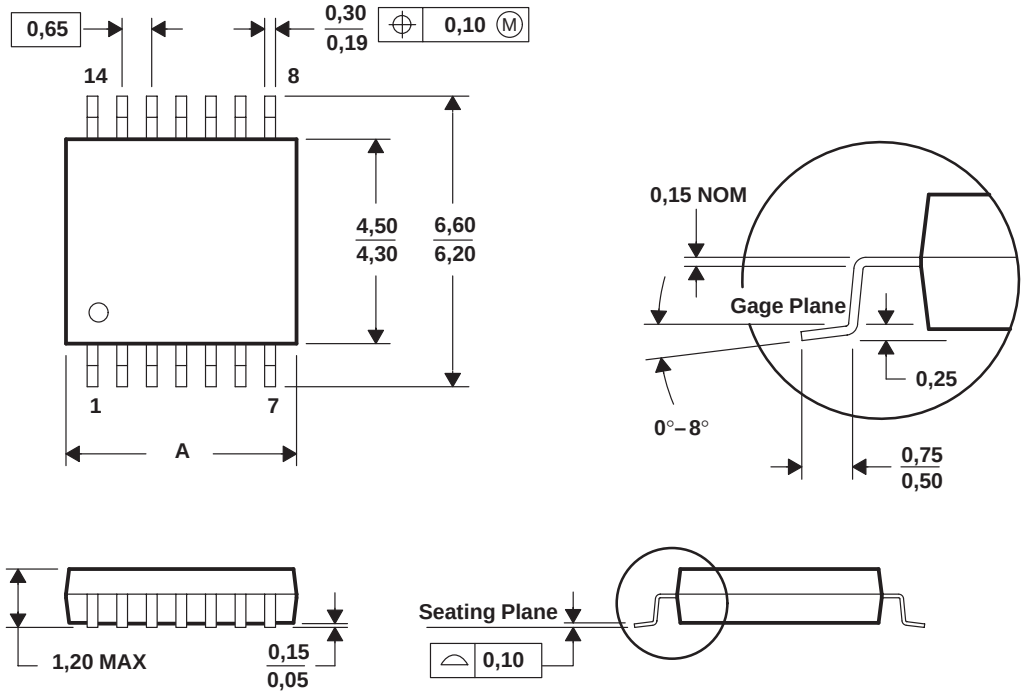
DW (R–PDSO–G16) PLASTIC SMALL–OUTLINE PACKAGE



NOTES:
A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).
D. Falls within JEDEC MS–013 variation AA.

PW (R-PDSO-G)** **PLASTIC SMALL-OUTLINE PACKAGE**

14 PINS SHOWN



DIM \ PINS **	8	14	16	20	24	28
A MAX	3,10	5,10	5,10	6,60	7,90	9,80
A MIN	2,90	4,90	4,90	6,40	7,70	9,60

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NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.
D. Falls within JEDEC MO-153

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