

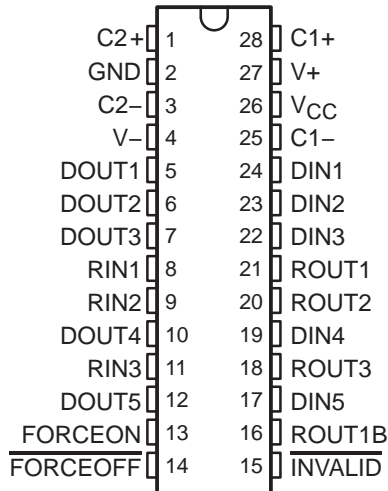
MAX3238

3-V TO 5.5-V MULTICHANNEL RS-232 LINE DRIVER/RECEIVER WITH ± 15 -kV ESD (HBM) PROTECTION

SLLS349J – JUNE 1999 – REVISED MARCH 2004

- RS-232 Bus-Pin ESD Protection Exceeds ± 15 kV Using Human-Body Model (HBM)
- Meets or Exceeds the Requirements of TIA/EIA-232-F and ITU v.28 Standards
- Operates With 3-V to 5.5-V V_{CC} Supply
- Operates Up To 250 kbit/s
- Five Drivers and Three Receivers
- Low Standby Current . . . 1 μ A Typical
- External Capacitors . . . $4 \times 0.1 \mu$ F
- Accepts 5-V Logic Input With 3.3-V Supply
- Always-Active Noninverting Receiver Output (ROUT1B)
- Alternative High-Speed Pin-Compatible Device (1 Mbit/s)
 - SNx5C3238
- Applications
 - Battery-Powered Systems, PDAs, Notebooks, Subnotebooks, Laptops, Palmtop PCs, Hand-Held Equipment, Modems, and Printers

DB OR PW PACKAGE
(TOP VIEW)



description/ordering information

The MAX3238 consists of five line drivers, three line receivers, and a dual charge-pump circuit with ± 15 -kV ESD (HBM) protection pin to pin (serial-port connection pins, including GND). The device meets the requirements of TIA/EIA-232-F and provides the electrical interface between notebook and subnotebook computer applications. The charge pump and four small external capacitors allow operation from a single 3-V to 5.5-V supply. In addition, the device includes an always-active noninverting output (ROUT1B), which allows applications using the ring indicator to transmit data while the device is powered down. These devices operate at data signaling rates up to 250 kbit/s and a maximum of 30-V/ μ s driver output slew rate.

ORDERING INFORMATION

T_A	PACKAGE†		ORDERABLE PART NUMBER	TOP-SIDE MARKING
–0°C to 70°C	SSOP (DB)	Tube of 50	MAX3238CDB	MAX3238C
		Reel of 2000	MAX3238CDBR	
	TSSOP (PW)	Tube of 50	MAX3238CPW	MA3238C
		Reel of 2000	MAX3238CPWR	
–40°C to 85°C	SSOP (DB)	Tube of 50	MAX3238IDB	MAX3238I
		Reel of 2000	MAX3238IDBR	
	TSSOP (PW)	Tube of 50	MAX3238IPW	MB3238I
		Reel of 2000	MAX3238IPWR	

† Package drawings, standard packing quantities, thermal data, symbolization, and PCB design guidelines are available at www.ti.com/sc/package.



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PRODUCTION DATA information is current as of publication date. Products conform to specifications per the terms of Texas Instruments standard warranty. Production processing does not necessarily include testing of all parameters.

**TEXAS
INSTRUMENTS**

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description/ordering information (continued)

Flexible control options for power management are featured when the serial port and driver inputs are inactive. The auto-powerdown plus feature functions when **FORCEON** is low and **FORCEOFF** is high. During this mode of operation, if the device does not sense valid signal transitions on all receiver and driver inputs for approximately 30 s, the built-in charge pump and drivers are powered down, reducing the supply current to 1 μ A. By disconnecting the serial port or placing the peripheral drivers off, auto-powerdown plus occurs if there is no activity in the logic levels for the driver inputs. Auto-powerdown plus can be disabled when **FORCEON** and **FORCEOFF** are high. With auto-powerdown plus enabled, the device activates automatically when a valid signal is applied to any receiver or driver input. **INVALID** is high (valid data) if any receiver input voltage is greater than 2.7 V or less than –2.7 V, or has been between –0.3 V and 0.3 V for less than 30 μ s. **INVALID** is low (invalid data) if all receiver input voltages are between –0.3 V and 0.3 V for more than 30 μ s. Refer to Figure 5 for receiver input levels.

Function Tables**EACH DRIVER**

INPUTS				OUTPUT DOUT	DRIVER STATUS
DIN	FORCEON	FORCEOFF	TIME ELAPSED SINCE LAST RIN OR DIN TRANSITION		
X	X	L	X	Z	Powered off
L	H	H	X	H	Normal operation with auto-powerdown plus disabled
H	H	H	X	L	
L	L	H	<30 s	H	Normal operation with auto-powerdown plus enabled
H	L	H	<30 s	L	
L	L	H	>30 s	Z	Powered off by auto-powerdown plus feature
H	L	H	>30 s	Z	

H = high level, L = low level, X = irrelevant, Z = high impedance

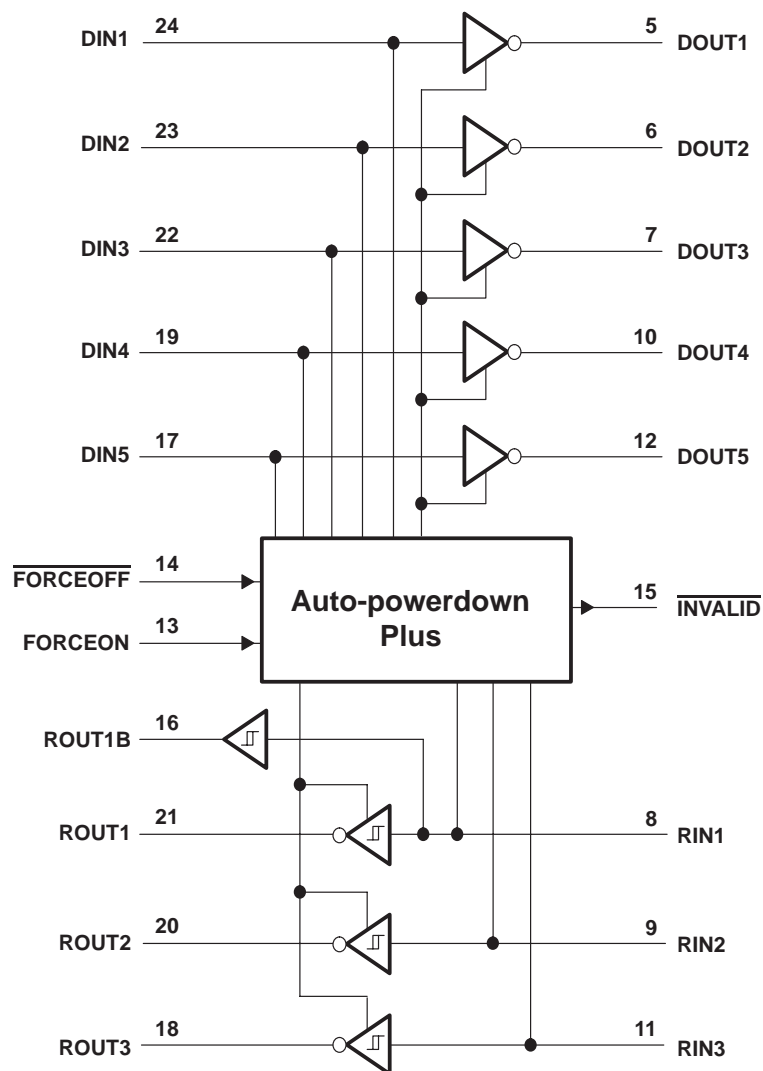
EACH RECEIVER

INPUTS				OUTPUTS		RECEIVER STATUS
RIN1	RIN2–RIN3	FORCEOFF	TIME ELAPSED SINCE LAST RIN OR DIN TRANSITION	ROUT1B	ROUT	
L	X	L	X	L	Z	Powered off while ROUT1B is active
H	X	L	X	H	Z	
L	L	H	<30 s	L	H	Normal operation with auto-powerdown plus disabled/enabled
L	H	H	<30 s	L	L	
H	L	H	<30 s	H	H	
H	H	H	<30 s	H	L	
Open	Open	H	>30 s	L	H	

H = high level, L = low level, X = irrelevant, Z = high impedance (off), Open = input disconnected or connected driver off

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logic diagram (positive logic)



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absolute maximum ratings over operating free-air temperature range (unless otherwise noted)[†]

Supply voltage range, V_{CC} (see Note 1)	–0.3 V to 6 V
Positive output supply voltage range, V_+ (see Note 1)	–0.3 V to 7 V
Negative output supply voltage range, V_- (see Note 1)	0.3 V to –7 V
Supply voltage difference, $V_+ - V_-$ (see Note 1)	13 V
Input voltage range, V_I : Driver ($\overline{\text{FORCEOFF}}$, FORCEON)	–0.3 V to 6 V
Receiver	–25 V to 25 V
Output voltage range, V_O : Driver	–13.2 V to 13.2 V
Receiver (INVALID)	–0.3 V to $V_{CC} + 0.3$ V
Package thermal impedance, θ_{JA} (see Notes 2 and 3): DB package	62°C/W
PW package	62°C/W
Operating virtual junction temperature, T_J	150°C
Storage temperature range, T_{stg}	–65°C to 150°C

[†] Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under “recommended operating conditions” is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTES: 1. All voltages are with respect to network GND.

2. Maximum power dissipation is a function of $T_J(\text{max})$, θ_{JA} , and T_A . The maximum allowable power dissipation at any allowable ambient temperature is $P_D = (T_J(\text{max}) - T_A)/\theta_{JA}$. Operating at the absolute maximum T_J of 150°C can affect reliability.

3. The package thermal impedance is calculated in accordance with JEDEC 51-7.

recommended operating conditions (see Note 4 and Figure 6)

			MIN	NOM	MAX	UNIT
Supply voltage		$V_{CC} = 3.3$ V	3	3.3	3.6	V
		$V_{CC} = 5$ V	4.5	5	5.5	
V_{IH}	Driver and control high-level input voltage	$V_{CC} = 3.3$ V	2			V
		$V_{CC} = 5$ V	2.4			
V_{IL}	Driver and control low-level input voltage	DIN, $\overline{\text{FORCEOFF}}$, FORCEON			0.8	V
V_I	Driver and control input voltage	DIN, $\overline{\text{FORCEOFF}}$, FORCEON	0		5.5	V
V_I	Receiver input voltage		–25		25	V
T_A	Operating free-air temperature	MAX3238C	0		70	°C
		MAX3238I	–40		85	

NOTE 4: Testing supply conditions are C1–C4 = 0.1 μ F at $V_{CC} = 3.3$ V \pm 0.15 V; C1–C4 = 0.22 μ F at $V_{CC} = 3.3$ V \pm 0.3 V; and C1 = 0.047 μ F and C2–C4 = 0.33 μ F at $V_{CC} = 5$ V \pm 0.5 V.

electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 4 and Figure 6)

PARAMETER		TEST CONDITIONS	MIN	TYP [‡]	MAX	UNIT
I_I	Input leakage current	$\overline{\text{FORCEOFF}}$, FORCEON		± 0.01	± 1	μ A
I_{CC}	Supply current ($T_A = 25^\circ\text{C}$)	Auto-powerdown plus disabled		0.5	2	mA
		Powered off		1	10	
		Auto-powerdown plus enabled		1	10	μ A

[‡] All typical values are at $V_{CC} = 3.3$ V or $V_{CC} = 5$ V, and $T_A = 25^\circ\text{C}$.

NOTE 4: Testing supply conditions are C1–C4 = 0.1 μ F at $V_{CC} = 3.3$ V \pm 0.15 V; C1–C4 = 0.22 μ F at $V_{CC} = 3.3$ V \pm 0.3 V; and C1 = 0.047 μ F and C2–C4 = 0.33 μ F at $V_{CC} = 5$ V \pm 0.5 V.



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DRIVER SECTION

electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 4 and Figure 6)

PARAMETER	TEST CONDITIONS	MIN	TYP†	MAX	UNIT
V _{OH} High-level output voltage	All DOUT at R _L = 3 k Ω to GND	5	5.4		V
V _{OL} Low-level output voltage	All DOUT at R _L = 3 k Ω to GND	–5	–5.4		V
I _{IH} High-level input current	V _I = V _{CC}		± 0.01	± 1	μ A
I _{IL} Low-level input current	V _I at GND		± 0.01	± 1	μ A
I _{OS} Short-circuit output current‡	V _{CC} = 3.6 V, V _O = 0 V		± 35	± 60	mA
	V _{CC} = 5.5 V, V _O = 0 V		± 40	± 100	
r _o Output resistance	V _{CC} , V ₊ , and V _– = 0 V, V _O = ± 2 V	300	10M		Ω
I _{off} Output leakage current	FORCEOFF = GND, V _O = ± 12 V, V _{CC} = 3 V to 3.6 V			± 25	μ A
	V _O = ± 10 V, V _{CC} = 4.5 V to 5.5 V			± 25	

† All typical values are at V_{CC} = 3.3 V or V_{CC} = 5 V, and T_A = 25°C.

‡ Short-circuit durations should be controlled to prevent exceeding the device absolute power-dissipation ratings, and not more than one output should be shorted at a time.

NOTE 4: Testing supply conditions are C1–C4 = 0.1 μ F at V_{CC} = 3.3 V \pm 0.15 V; C1–C4 = 0.22 μ F at V_{CC} = 3.3 V \pm 0.3 V; and C1 = 0.047 μ F and C2–C4 = 0.33 μ F at V_{CC} = 5 V \pm 0.5 V.

switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 4 and Figure 6)

PARAMETER	TEST CONDITIONS	MIN	TYP†	MAX	UNIT
Maximum data rate	C _L = 1000 pF, One DOUT switching, R _L = 3 k Ω , See Figure 1	150	250		kbit/s
t _{sk(p)} Pulse skew§	C _L = 150 pF to 2500 pF, R _L = 3 k Ω to 7 k Ω , See Figure 2		100		ns
SR(tr) Slew rate, transition region (see Figure 1)	V _{CC} = 3.3 V, R _L = 3 k Ω to 7 k Ω	C _L = 150 pF to 1000 pF	6	30	V/ μ s
		C _L = 150 pF to 2500 pF	4	30	

† All typical values are at V_{CC} = 3.3 V or V_{CC} = 5 V, and T_A = 25°C.

§ Pulse skew is defined as |t_{PLH} – t_{PHL}| of each channel of the same device.

NOTE 4: Testing supply conditions are C1–C4 = 0.1 μ F at V_{CC} = 3.3 V \pm 0.15 V; C1–C4 = 0.22 μ F at V_{CC} = 3.3 V \pm 0.3 V; and C1 = 0.047 μ F and C2–C4 = 0.33 μ F at V_{CC} = 5 V \pm 0.5 V.

RECEIVER SECTION

electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 4 and Figure 6)

PARAMETER	TEST CONDITIONS	MIN	TYP†	MAX	UNIT
V_{OH} High-level output voltage	$I_{OH} = -1$ mA	$V_{CC} - 0.6$ V	$V_{CC} - 0.1$ V		V
V_{OL} Low-level output voltage	$I_{OL} = 1.6$ mA			0.4	V
V_{IT+} Positive-going input threshold voltage	$V_{CC} = 3.3$ V		1.5	2.4	V
	$V_{CC} = 5$ V		1.8	2.4	
V_{IT-} Negative-going input threshold voltage	$V_{CC} = 3.3$ V	0.6	1.2		V
	$V_{CC} = 5$ V	0.8	1.5		
V_{hys} Input hysteresis ($V_{IT+} - V_{IT-}$)			0.3		V
I_{off} Output leakage current (except ROUT1B)	$\overline{FORCEOFF} = 0$ V		± 0.05	± 10	μ A
r_i Input resistance	$V_I = \pm 3$ V to ± 25 V	3	5	7	k Ω

† All typical values are at $V_{CC} = 3.3$ V or $V_{CC} = 5$ V, and $T_A = 25^\circ\text{C}$.

NOTE 4: Testing supply conditions are C1–C4 = 0.1 μ F at $V_{CC} = 3.3$ V ± 0.15 V; C1–C4 = 0.22 μ F at $V_{CC} = 3.3$ V ± 0.3 V; and C1 = 0.047 μ F and C2–C4 = 0.33 μ F at $V_{CC} = 5$ V ± 0.5 V.

switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 4)

PARAMETER	TEST CONDITIONS	MIN	TYP†	MAX	UNIT
t_{PLH} Propagation delay time, low- to high-level output	$C_L = 150$ pF, See Figure 3		150		ns
t_{PHL} Propagation delay time, high- to low-level output			150		ns
t_{en} Output enable time	$C_L = 150$ pF, $R_L = 3$ k Ω , See Figure 4		200		ns
t_{dis} Output disable time			200		ns
$t_{sk(p)}$ Pulse skew‡	See Figure 3		50		ns

† All typical values are at $V_{CC} = 3.3$ V or $V_{CC} = 5$ V, and $T_A = 25^\circ\text{C}$.

‡ Pulse skew is defined as $|t_{PLH} - t_{PHL}|$ of each channel of the same device.

NOTE 4: Testing supply conditions are C1–C4 = 0.1 μ F at $V_{CC} = 3.3$ V ± 0.15 V; C1–C4 = 0.22 μ F at $V_{CC} = 3.3$ V ± 0.3 V; and C1 = 0.047 μ F and C2–C4 = 0.33 μ F at $V_{CC} = 5$ V ± 0.5 V.

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AUTO-POWERDOWN PLUS SECTION

electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Figure 5)

PARAMETER	TEST CONDITIONS	MIN	TYP†	MAX	UNIT
$V_{T+}(\text{valid})$	Receiver input threshold for INVALID high-level output voltage $\text{FORCEON} = \text{GND}, \text{FORCEOFF} = V_{CC}$			2.7	V
$V_{T-}(\text{valid})$	Receiver input threshold for INVALID high-level output voltage $\text{FORCEON} = \text{GND}, \text{FORCEOFF} = V_{CC}$	-2.7			V
$V_{T}(\text{invalid})$	Receiver input threshold for INVALID low-level output voltage $\text{FORCEON} = \text{GND}, \text{FORCEOFF} = V_{CC}$	-0.3		0.3	V
V_{OH}	INVALID high-level output voltage $I_{OH} = -1 \text{ mA}, \text{FORCEON} = \text{GND}, \text{FORCEOFF} = V_{CC}$	$V_{CC} - 0.6$			V
V_{OL}	INVALID low-level output voltage $I_{OL} = 1.6 \text{ mA}, \text{FORCEON} = \text{GND}, \text{FORCEOFF} = V_{CC}$			0.4	V

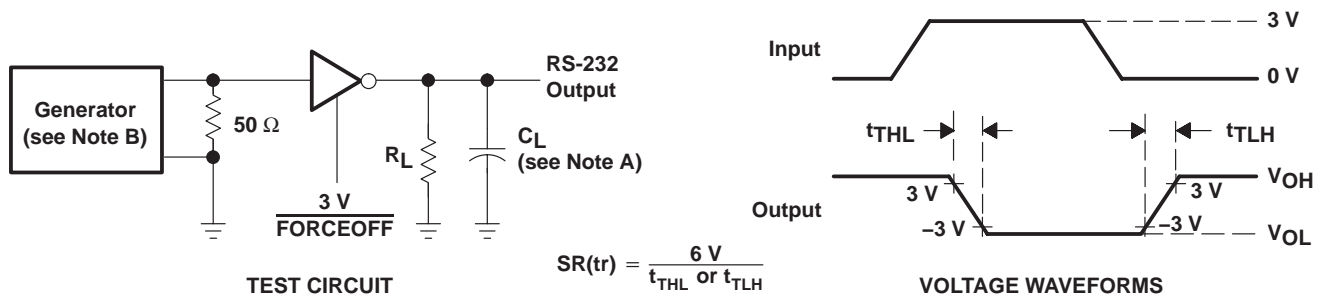
† All typical values are at $V_{CC} = 3.3 \text{ V}$ or $V_{CC} = 5 \text{ V}$, and $T_A = 25^\circ\text{C}$.

switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Figure 5)

PARAMETER	MIN	TYP†	MAX	UNIT
t_{valid}		0.1		μs
t_{invalid}		50		μs
t_{en}		25		μs
t_{dis}	15	30	60	s

† All typical values are at $V_{CC} = 3.3 \text{ V}$ or $V_{CC} = 5 \text{ V}$, and $T_A = 25^\circ\text{C}$.

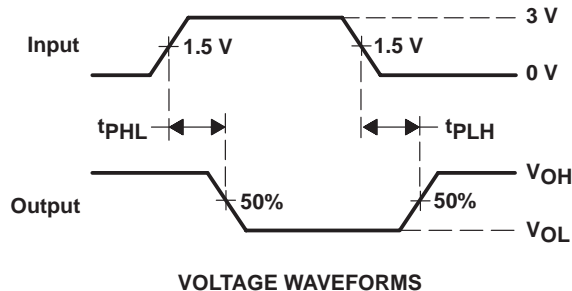
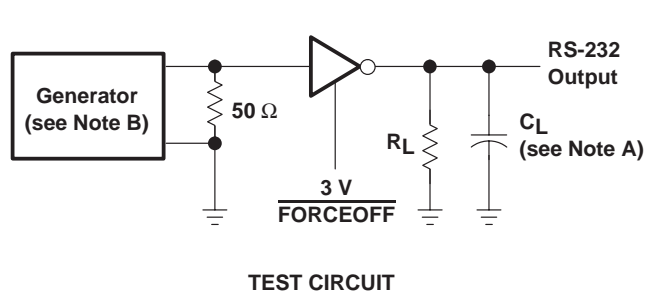
PARAMETER MEASUREMENT INFORMATION



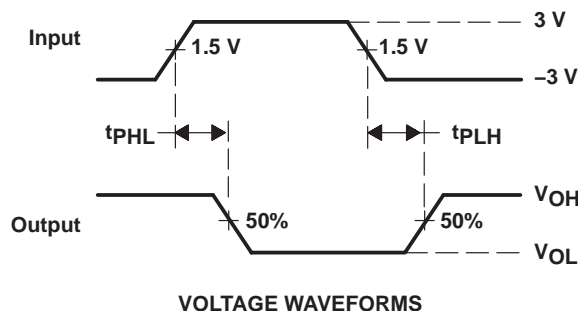
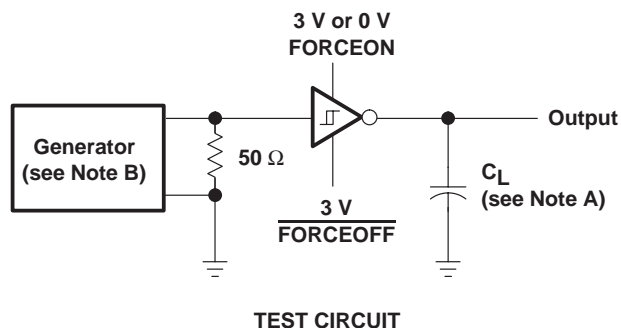
NOTES: A. C_L includes probe and jig capacitance.

B. The pulse generator has the following characteristics: PRR = 250 kbit/s, $Z_O = 50 \Omega$, 50% duty cycle, $t_r \leq 10 \text{ ns}$, $t_f \leq 10 \text{ ns}$.

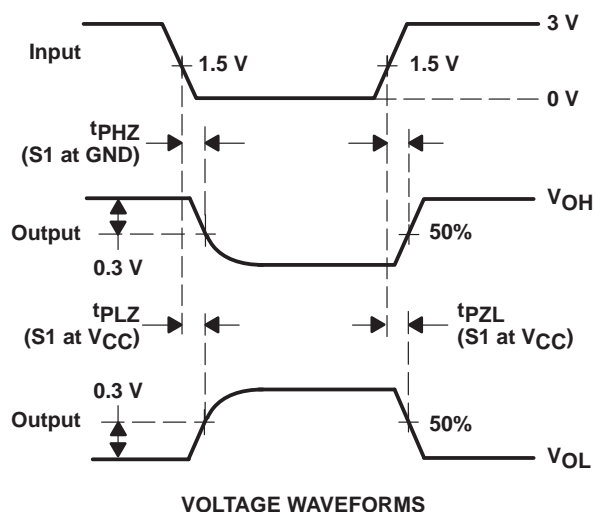
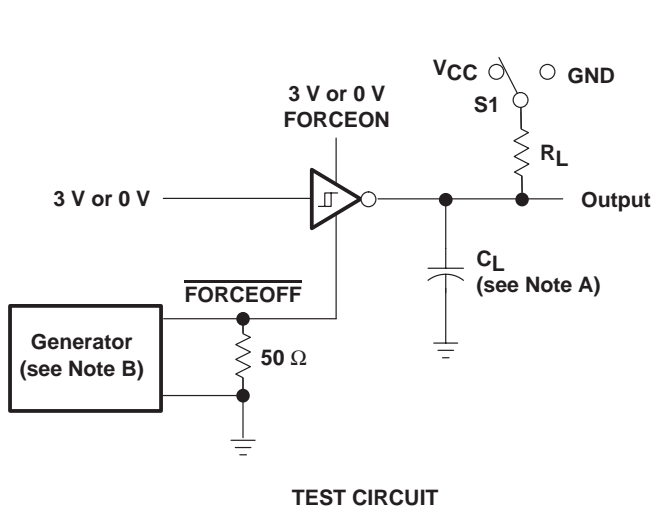
Figure 1. Driver Slew Rate

PARAMETER MEASUREMENT INFORMATION

 NOTES: A. C_L includes probe and jig capacitance.

 B. The pulse generator has the following characteristics: PRR = 250 kbit/s, $Z_O = 50\ \Omega$, 50% duty cycle, $t_r \leq 10$ ns, $t_f \leq 10$ ns.

Figure 2. Driver Pulse Skew

 NOTES: A. C_L includes probe and jig capacitance.

 B. The pulse generator has the following characteristics: $Z_O = 50\ \Omega$, 50% duty cycle, $t_r \leq 10$ ns, $t_f \leq 10$ ns.

Figure 3. Receiver Propagation Delay Times

 NOTES: A. C_L includes probe and jig capacitance.

 B. The pulse generator has the following characteristics: $Z_O = 50\ \Omega$, 50% duty cycle, $t_r \leq 10$ ns, $t_f \leq 10$ ns.

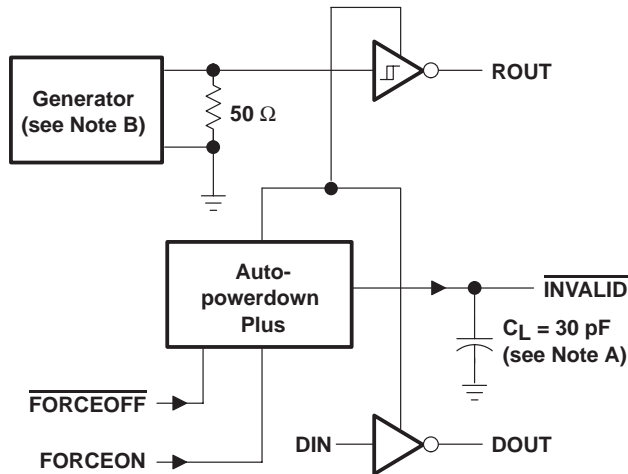
 C. t_{PLZ} and t_{PHZ} are the same as t_{dis} .

 D. t_{PZL} and t_{PZH} are the same as t_{en} .

Figure 4. Receiver Enable and Disable Times

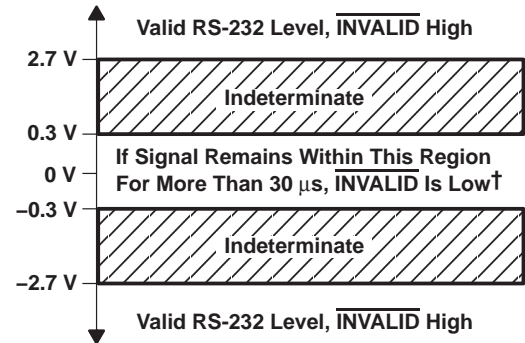
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PARAMETER MEASUREMENT INFORMATION



TEST CIRCUIT

- NOTES: A. C_L includes probe and jig capacitance.
 B. The pulse generator has the following characteristics: PRR = 5 kbit/s, $Z_O = 50 \Omega$, 50% duty cycle, $t_r \leq 10$ ns, $t_f \leq 10$ ns.



† Auto-powerdown plus disables drivers and reduces supply current to 1 μ A.

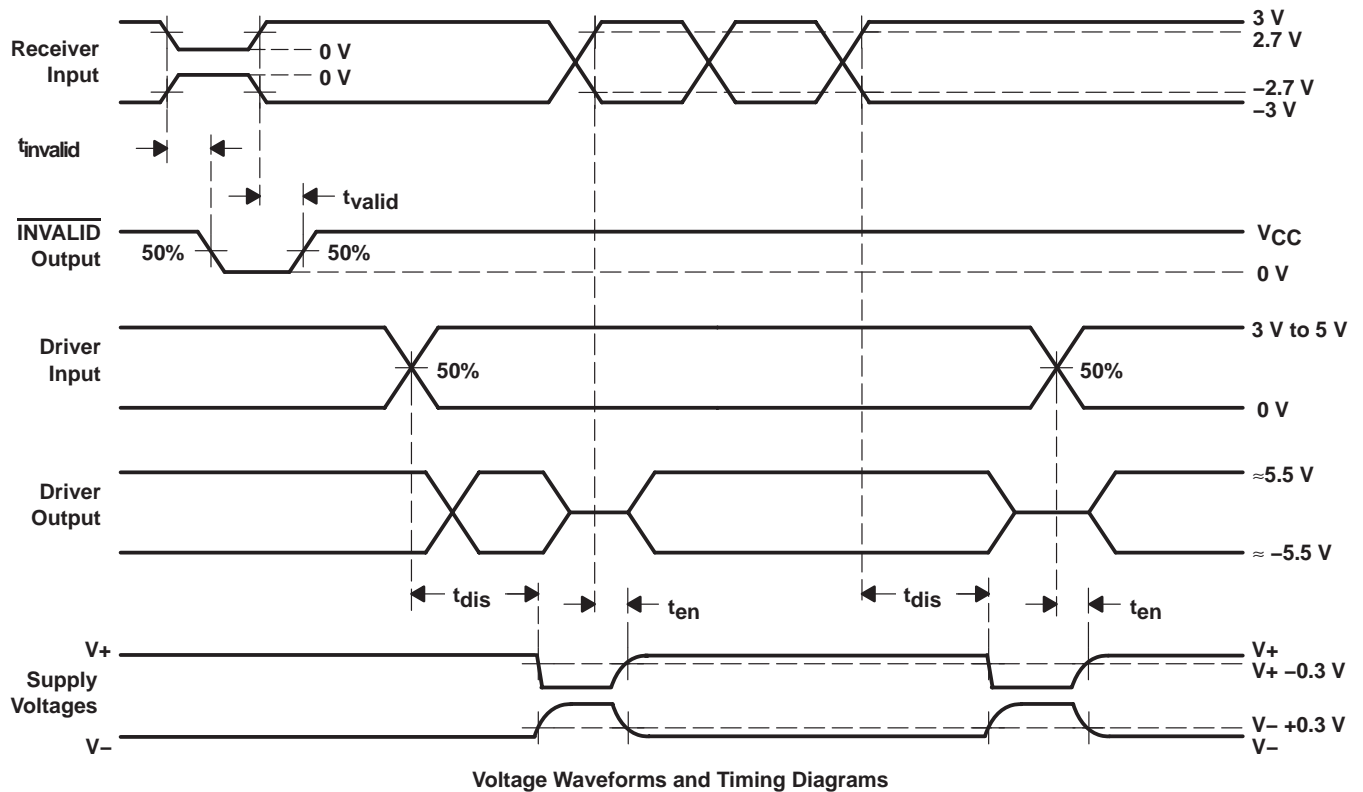


Figure 5. $\overline{\text{INVALID}}$ Propagation-Delay Times and Supply-Enabling Time

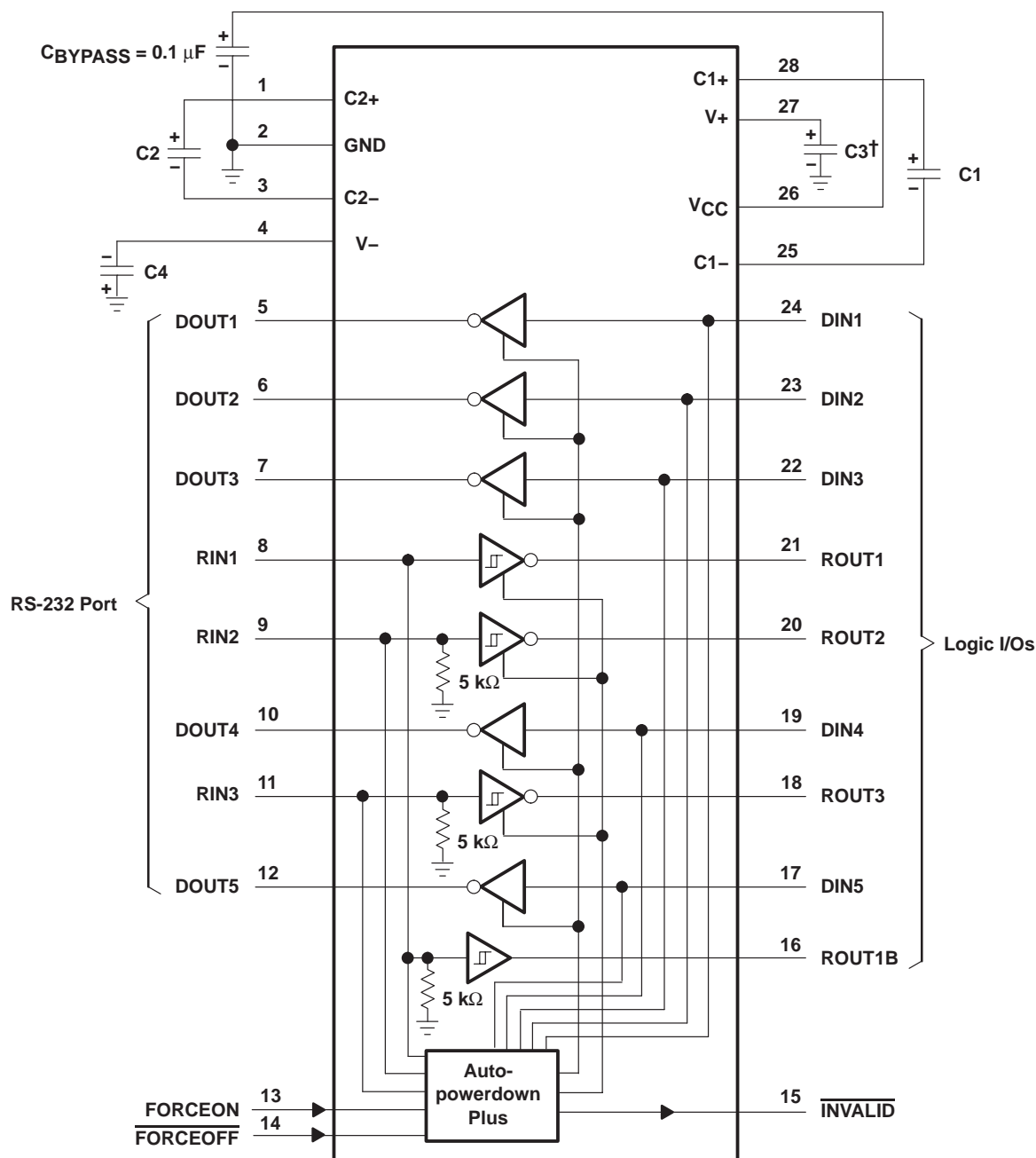
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APPLICATION INFORMATION



V_{CC} vs CAPACITOR VALUES

V _{CC}	C1	C2, C3, and C4
3.3 V \pm 0.15 V	0.1 μ F	0.1 μ F
3.3 V \pm 0.3 V	0.22 μ F	0.22 μ F
5 V \pm 0.5 V	0.047 μ F	0.33 μ F
3 V to 5.5 V	0.22 μ F	1 μ F

† C3 can be connected to V_{CC} or GND.

NOTES: A. Resistor values shown are nominal.

B. Nonpolarized ceramic capacitors are acceptable. If polarized tantalum or electrolytic capacitors are used, they should be connected as shown.

Figure 6. Typical Operating Circuit and Capacitor Values

DB (R-PDSO-G**)

PLASTIC SMALL-OUTLINE

28 PINS SHOWN



- NOTES: A. All linear dimensions are in millimeters.
 B. This drawing is subject to change without notice.
 C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.
 D. Falls within JEDEC MO-150

PW (R-PDSO-G**)

PLASTIC SMALL-OUTLINE PACKAGE

14 PINS SHOWN



- NOTES: A. All linear dimensions are in millimeters.
 B. This drawing is subject to change without notice.
 C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.
 D. Falls within JEDEC MO-153

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