

# **EVM430-FR6047 Hardware Guide**

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## **ABSTRACT**

This guide is intended to provide users of the EVM430-FR6047 with a quick reference to the different hardware options available. This includes power, header configurations and pinouts, and communication interfaces.

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**Trademarks**

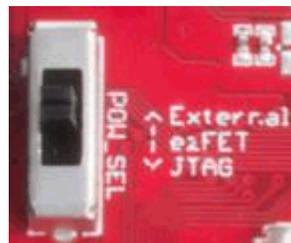
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**1 Power**

The EVM430-FR6047 can be supplied power through USB or an external supply (for example, a battery or bench supply). Jumper and switch configurations must be set appropriately for power to be properly routed to the MSP430FR6047 device.[\[1\]](#)

**1.1 USB Power**

When using USB as the power source, set the POW\_SEL switch to the middle position (ezFET) (see [Figure 1](#)).



**Figure 1. Power Selection**

Set J1 and J3 as in [Figure 2](#).



**Figure 2. USB Power Jumper Configuration**

**1.2 External Power**

When using external power, the POW\_SEL switch should be set to the top position (External) (see [Figure 3](#)). External supply voltage should be applied to the EXT\_POW header shown below. For lowest power consumption, all jumpers on J2, J3, and J4 should be open. If not using a regulator (optional), operational supply voltage range is 1.8 V to 3.6 V. GND on J3 and communication jumpers on J4 are required if communicating through USB.

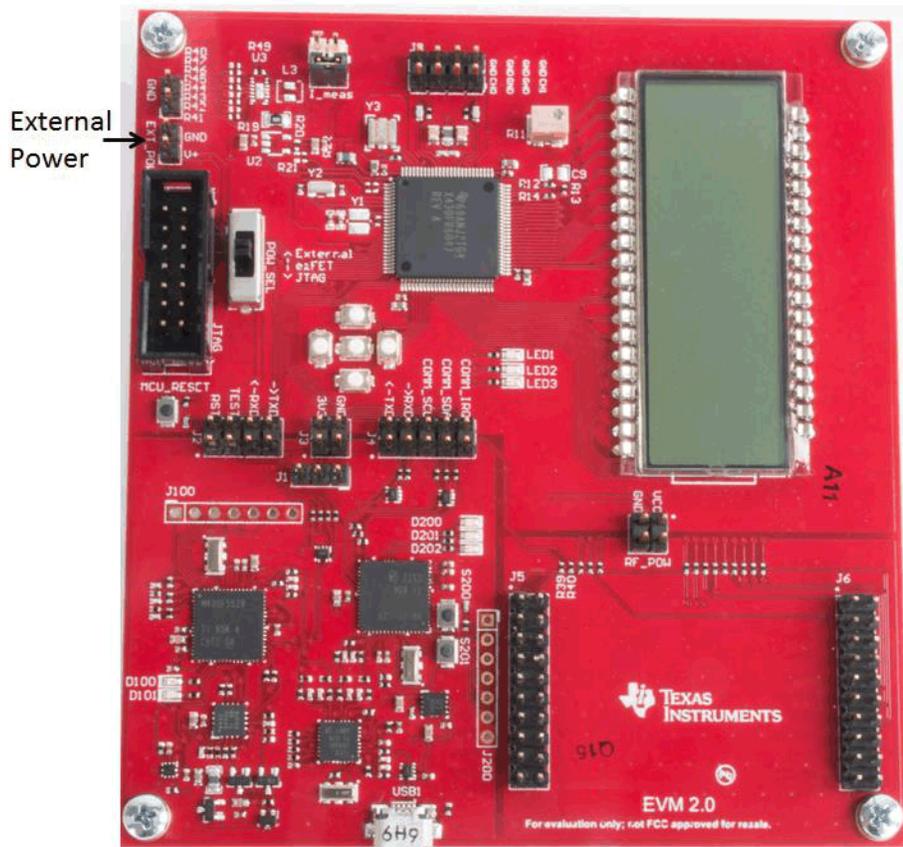


Figure 3. External Power

### 1.3 Using Voltage Regulators(optional)

Voltage regulators can be populated on the PCB if required. A switch mode regulator or LDO can be utilized. To use the TPS62740DSSR switch mode regulator, de-populate R19, and then populate U3 and surrounding components shown below. R41 to R48 should be set for the required output voltage. For more information, see the TPS62740 data sheet.[3]

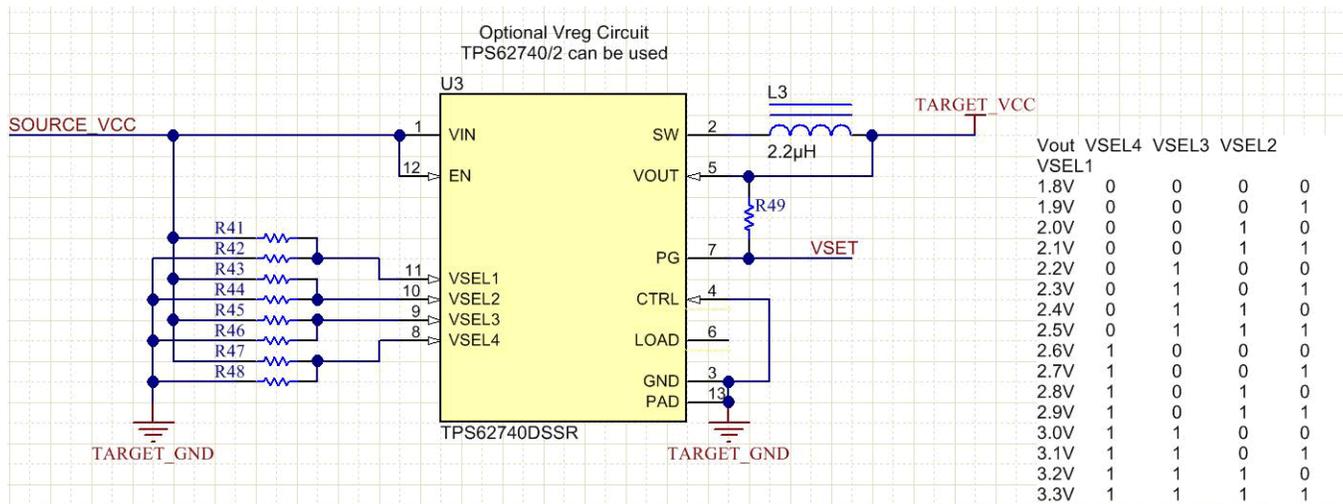


Figure 4. TPS62740 Schematic



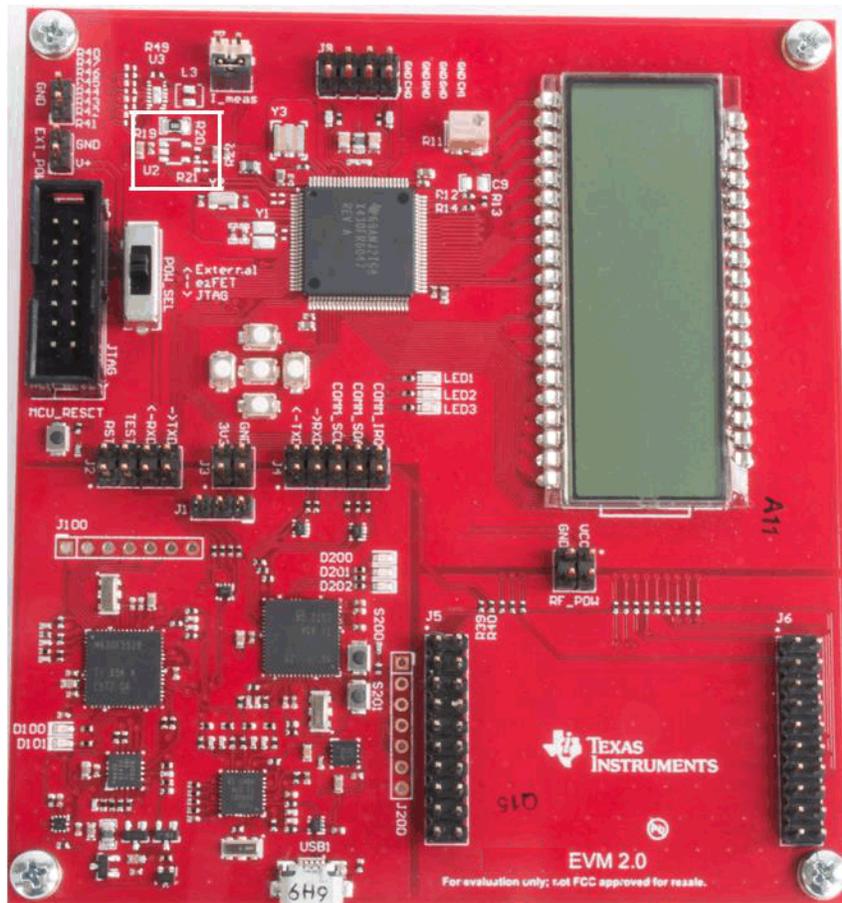


Figure 7. U2 Board Location

### 1.4 Measuring Current Consumption

Current consumption can be measured by removing the I\_meas jumper and placing an ammeter across the header. When current measurements are not being performed, be sure this jumper is set.

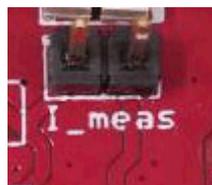


Figure 8. Current Measurement Header

## 2 Header Connections

### 2.1 Transducer Headers

Two transducers can be connected to the board through J8. Additional ground connections are available on this header to accommodate transducers which use 3 pins (1 signal pin and 2 ground pins). The transducers signal pins should be connected to CH0 and CH1 and ground pin(s) to GND.

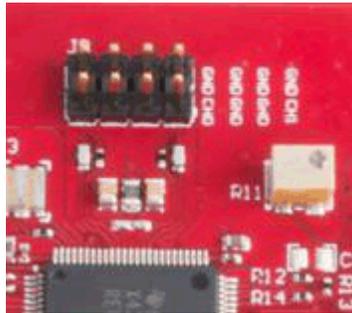


Figure 9. Transducer Header

Table 1. Transducer Connections

GND	GND	GND	GND
CH0	GND	GND	CH1

### 2.2 USSXT\_BOUT

When enabled in software, the buffered output clock of USSXT is available on J7. This allows for monitoring of the USSXT signal. Ground is also provided on J7.

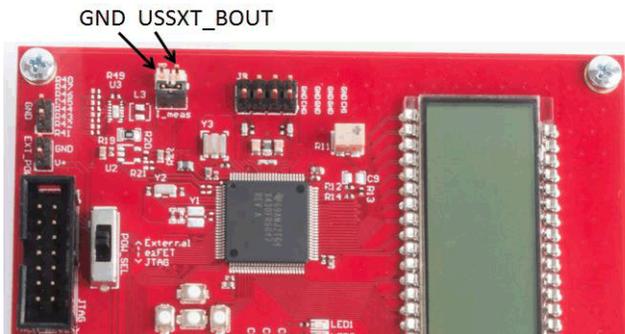
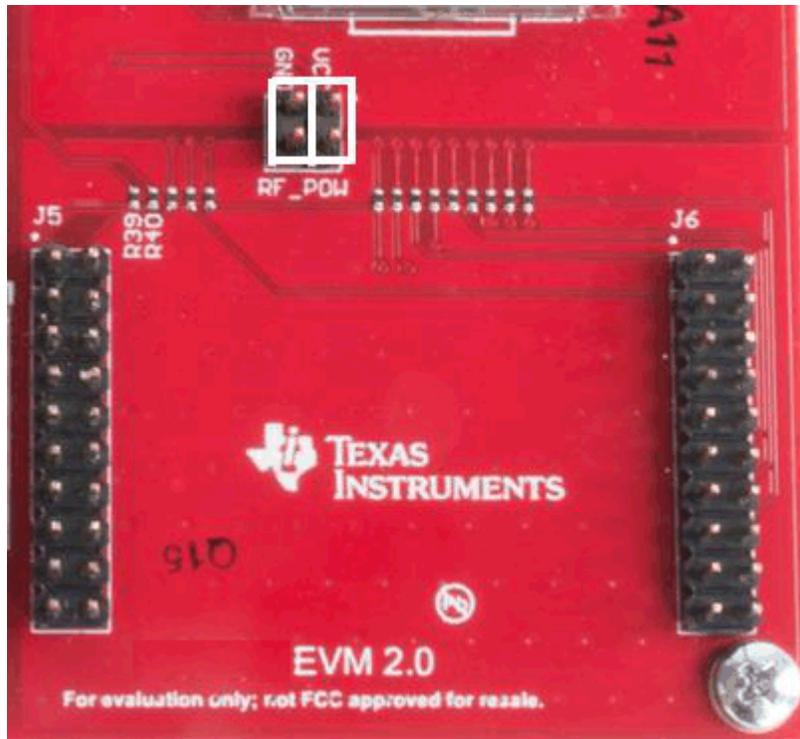


Figure 10. USSXT\_BOUT Header

### 2.3 BoosterPack™ Plug-in Module Connectors

J5 and J6 allow for connection to BoosterPack™ plug-in module or other devices which offer functionality such as wireless connectivity. To power a BoosterPack plug-in module from the main power supply, set jumpers on the RF\_POW header (see [Figure 11](#) and [Table 2](#)).



**Figure 11. BoosterPack Plug-in Module Headers**

**Table 2. BoosterPack Plug-in Module Connections**

	J5		J6	
VCC	N.C.		N.C.	GND
	N.C.		N.C.	GPIO
RXD	N.C.		N.C.	SPI_CS
TXD	N.C.		N.C.	
CTS	N.C.		N.C.	
	N.C.		N.C.	SPI_MOSI
SPI_CLK	N.C.		N.C.	SPI_MISO
RTS	N.C.		N.C.	RESET
SCL	N.C.		N.C.	GPIO
SDA	N.C.		N.C.	GPIO

## 2.4 JTAG

A standard MSP430™ 14 pin JTAG header is available for programming and debug. When using JTAG for programming, the POW\_SEL switch should be set to the bottom position (JTAG) when power will be supplied through JTAG. If external power will be used, the switch should be set to the top position (External).

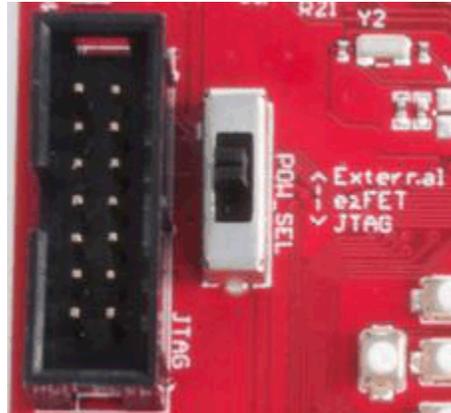


Figure 12. JTAG Header

## 2.5 Communications

UART, I<sup>2</sup>C, and Spy-Bi-Wire interfaces are available.

JTAG TX and RX (UART) are available on J2. To use this interface with the on-board eZ-FET circuit, place jumpers on J2 TXD and RXD pins.

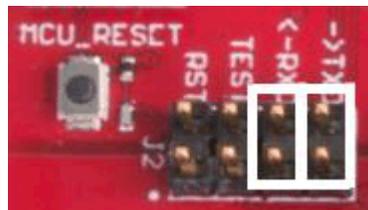


Figure 13. JTAG UART Jumpers

J2 also provides a connection for the Spy-Bi-Wire programming and debug interface. To use the on-board eZ-FET circuit, place jumpers on the J2 TEST and RST pins.

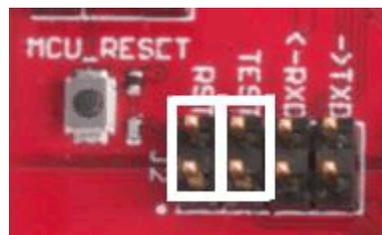


Figure 14. Spy-Bi-Wire Jumpers

J4 provides a connection between the MSP430FR6047 and the high speed USB HID interface. To enable I<sup>2</sup>C, the J4 COMM\_SDA, COMM\_SCL, and COMM\_IRQ jumpers should be populated. To enable UART on the USB HID interface, J4 TXD and RXD jumpers should be populated.

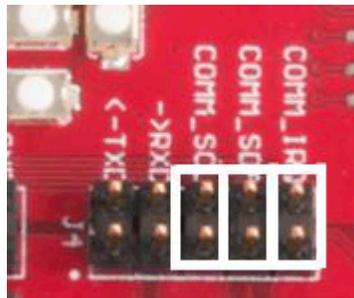


Figure 15. I<sup>2</sup>C Jumpers

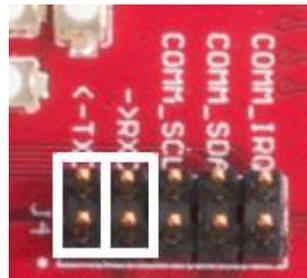


Figure 16. USB HID UART Jumpers

### 3 LCD

The LCD contrast can be adjusted with the R11 potentiometer. Use a small flathead screwdriver to adjust the resistance of R11 and monitor the contrast on the display.

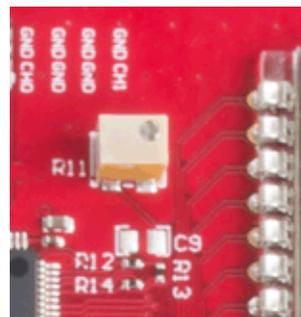


Figure 17. LCD Contrast Control

### 4 References

1. [MSP430FR6047 Mixed-Signal Microcontroller](#)
2. [TPS780xx 150-mA Low-Dropout Regulator, Ultralow-Power, I<sub>Q</sub> 500 nA With Pin-Selectable, Dual-Level Output Voltage](#)
3. [TPS6274x 360nA I<sub>Q</sub> Step Down Converter For Low Power Applications](#)

## 5 REACH Compliance

In compliance with the Article 33 provision of the EU REACH regulation, TI notifies you that this EVM includes components that contain at least one Substance of Very High Concern (SVHC) above 0.1%. These uses from TI do not exceed 1 ton per year. The SVHCs are:

Component Manufacturer	Component Part Number	SVHC Substance	SVHC CAS
Murata	CSTCR4M00G15L99-R0	Lead Titanium Zirconium Oxide	12626-81-2
Murata	CSTCR6M00G53Z-R0	Lead Titanium Zirconium Oxide	12626-81-2
Abracon	ABM3-8.000MHZ-D2Y-T	Diboron Trioxide	1303-86-2
Abracon	ABM3-8.000MHZ-D2Y-T	Lead Oxide	1317-36-8
Abracon	AWSCR-8.00CV-T	Boric Acid	10043-35-3
Abracon	AWSCR-8.00CV-T	Lead Oxide	1317-36-8

### Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from June 2, 2017 to April 25, 2018	Page
• Added <a href="#">Section 5, REACH Compliance</a> .....	10

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This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

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- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
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Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes: (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

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