# 18-BIT, 1-MSPS, PSEUDO-BIPOLAR, FULLY DIFFERENTIAL INPUT, MICROPOWER SAMPLING ANALOG-TO-DIGITAL CONVERTER WITH PARALLEL INTERFACE, REFERENCE

## FEATURES

- 0 to 1-MHz Sample Rate
- ±1.2 LSB Typ, ±2.5 LSB Max INL
- +0.75/-0.6 LSB Typ, +1.5/-1 LSB Max DNL

**Burr-Brown Products** 

from Texas Instruments

- 18-Bit NMC Ensured Over Temperature
- ±0.05-mV Offset Error
- ±0.05-PPM/°C Offset Error Drift
- ±0.035 %FSR Gain Error
- ±0.5-PPM/°C Gain Error Drift
- 99dB SNR, -121dB THD, 123dB SFDR
- Zero Latency
- Low Power: 225 mW at 1 MSPS
- Unipolar Differential Input Range: V<sub>ref</sub> to –Vref
- Onboard Reference with 6 PPM/°C Drift
- Onboard Reference Buffer
- High-Speed Parallel Interface
- Wide Digital Supply 2.7 V to 5.25 V
- 8-/16-/18-Bit Bus Transfer
- 48-Pin 7x7 QFN Package

## **APPLICATIONS**

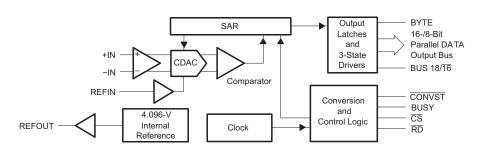
- Medical Instruments
- Optical Networking
- Transducer Interface
- High Accuracy Data Acquisition Systems
- Magnetometers

## DESCRIPTION

The ADS8482 is an 18-bit, 1-MSPS A/C converter with an internal 4.096-V reference and a pseudo-bipolar, fully differential input. The device includes a 18-bit capacitor-based SAR A/D converter with inherent sample and hold. The ADS8482 offers a full 18-bit interface, a 16-bit option where data is read using two read cycles, or an 8-bit bus option using three read cycles.

The ADS8482 is available in a 48-lead 7x7 QFN package and is characterized over the industrial  $-40^{\circ}$ C to 85°C temperature range.

TYPE/SPEED	500 kHz	~600 kHz	750 kHz	1 MHz	1.25 MHz	2 MHz	3 MHz	4MHz
18-Bit Pseudo-Diff	ADS8383	ADS8381		ADS8481				
18-Bit Pseudo-Dili		ADS8380 (s)						
18-Bit Pseudo-Bipolar, Fully Diff		ADS8382 (s)		ADS8482				
	ADS8327	ADS8370 (s)	ADS8371	ADS8471	ADS8401	ADS8411		
16-Bit Pseudo-Diff	ADS8328	ADS8372 (s)			ADS8405	ADS8410 (s)		
40 Dit Descule Disalar, Fully Diff				ADS8472	ADS8402	ADS8412		ADS8422
16-Bit Pseudo-Bipolar, Fully Diff					ADS8406	ADS8413 (s)		
14-Bit Pseudo-Diff					ADS7890 (s)		ADS7891	
12-Bit Pseudo-Diff				ADS7886		ADS7883		ADS7881



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

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## HIGH SPEED SAR CONVERTER FAMILY



## ADS8482



#### SLAS386A-JULY 2005-REVISED JUNE 2006



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

#### ORDERING INFORMATION<sup>(1)</sup>

MODEL	MAXIMUM INTEGRAL LINEARITY (LSB)	MAXIMUM DIFFERENTIAL LINEARITY (LSB)	NO MISSING CODES RESOLUTION (BIT)	PACKAGE TYPE	PACKAGE DESIGNATOR	TEMPER-ATURE RANGE	ORDERING INFORMATION	TRANS-PORT MEDIA QTY.
ADS84821	±4	-1 to +1.5	18	7x7 48 Pin	RGZ	–40°C to 85°C	ADS8482IRGZT	Tape and reel 250
AD304021	14	-110 +1.5	10	QFN	KGZ	-40 C 10 85 C	ADS8482IRGZR	Tape and reel 1000
ADS8482IB	±2.5	-1 to +1.5	18 7x7 48 Pin QFN RGZ	7x7 48 Pin	507	–40°C to 85°C	ADS8482IBRGZT	Tape and reel 250
AD30402ID	± <b>z</b> .5	-110 +1.5		-40 0 10 85 0	ADS8482IBRGZR	Tape and reel 1000		

(1) For the most current specifications and package information, refer to our website at www.ti.com.

### ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>

over operating free-air temperature range (unless otherwise noted)

			VALUE	UNIT
		+IN to AGND	-0.4 to +VA + 0.1	V
		-IN to AGND	-0.4 to +VA + 0.1	V
	Voltage	+VA to AGND	–0.3 to 7	V
		+VBD to BDGND	-0.3 to 7	V
		+VA to +VBD	-0.3 to 2.55	V
	Digital input voltage to BDGND	-0.3 to +VBD + 0.3	V	
	Digital output voltage to BDGN	D	-0.3 to +VBD + 0.3	V
T <sub>A</sub>	Operating free-air temperature	range	-40 to 85	°C
T <sub>stg</sub>	Storage temperature range		-65 to 150	°C
-	Junction temperature (T <sub>J</sub> max)		150	°C
		Power dissipation	$(T_JMax - T_A)/\theta_{JA}$	
	QFN package	$\theta_{JA}$ thermal impedance	22	°C/W
		Vapor phase (60 sec)	215	°C
	Lead temperature, soldering	Infrared (15 sec)	220	°C

(1) Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

## **SPECIFICATIONS**

 $T_A = -40^{\circ}C$  to  $85^{\circ}C$ , +VA = 5 V, +VBD = 3 V or 5 V,  $V_{ref} = 4.096$  V,  $f_{SAMPLE} = 1$  MSPS (unless otherwise noted)

PARAMETE	ER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
ANALOG INPUT							
Full-scale input voltage <sup>(1)</sup>		+IN - (-IN)	-V <sub>ref</sub>		V <sub>ref</sub>	V	
		+IN	-0.2		V <sub>ref</sub> + 0.2		
Absolute input voltage		-IN	-0.2		V <sub>ref</sub> + 0.2	V	
Common-mode input range			(V <sub>ref</sub> )/2 - 0.2	(V <sub>ref</sub> )/2	$(V_{ref})/2 + 0.2$	V	
Input capacitance				65		pF	
Input leakage current				1		nA	
SYSTEM PERFORMANCE			Ш				
Resolution				18		Bits	
ADS84821			18			D''	
No missing codes	ADS8482IB		18			Bits	
(2)	ADS8482I		-4	±1.2	4	LSB	
Integral linearity (2)	ADS8482IB		-2.5	±1.2	2.5	(18 bit) <sup>(3)</sup>	
	ADS8482I		-1	-0.6/0.75	1.5	LSB	
Differential linearity	ADS8482IB		-1	-0.6/0.75	1.5	(18 bit)	
Offset error <sup>(4)</sup>	ADS8482I		-0.5	±0.05	0.5		
	ADS8482IB		-0.5	±0.05	0.5	mV	
	ADS8482I			±0.05		ppm/°C	
Offset error temperature drift	ADS8482IB			±0.05			
Q : (4)(5)	ADS8482I	V <sub>ref</sub> = 4.096 V	-0.1	±0.035	0.1	%FS	
Gain error <sup>(4)(5)</sup>	ADS8482IB	V <sub>ref</sub> = 4.096 V	-0.1	±0.035	0.1	%FS	
	ADS8482I			±0.5			
Gain error temperature drift	ADS8482IB			±0.5		ppm/°C	
<b>0</b>		At dc (±0.2 V around V <sub>ref</sub> /2)		60		in	
Common-mode rejection ratio		+IN – (–IN) = 1 Vpp at 1 MHz		55		dB	
Noise				25		μV RMS	
Power supply rejection ratio		At 1FFFFh output code		60		dB	
SAMPLING DYNAMICS		·					
Conversion time				625	650	ns	
Acquisition time			320	350		ns	
Throughput rate					1	MHz	
Aperture delay				4		ns	
Aperture jitter				5		ps	
Step response				150		ns	
Over voltage recovery				150		ns	

Ideal input span, does not include gain or offset error.
 This is endpoint INL, not best fit.

(3) LSB means least significant bit
 (4) Measured relative to an ideal full-scale input [+IN - (-IN)] of 8.192 V

(5) This specification does not include the internal reference voltage error and drift.

## **SPECIFICATIONS (Continued)**

 $T_A = -40^{\circ}C$  to 85°C, +VA = 5 V, +VBD = 3 V or 5 V,  $V_{ref} = 4.096$  V,  $f_{SAMPLE} = 1$  MSPS (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT			
DYNAMIC CHARACTERISTICS								
	ADS84821			-120				
	ADS8482IB	- V <sub>IN</sub> = 8 V <sub>pp</sub> at 2 kHz		-121				
Total harmonic distortion (TUD)(1)	ADS84821			-105		15		
Total harmonic distortion (THD) <sup>(1)</sup>	ADS8482IB	- V <sub>IN</sub> = 8 V <sub>pp</sub> at 20 kHz		-110		dB		
	ADS84821			-100				
	ADS8482IB	- V <sub>IN</sub> = 8 V <sub>pp</sub> at 100 kHz		-103				
	ADS84821		96	98.6				
Signal to noise ratio (SNR) <sup>(1)</sup>	ADS8482IB	- V <sub>IN</sub> = 8 V <sub>pp</sub> at 2 kHz	97.5	99		dB		
	ADS84821	$V_{\rm e} = 8 V_{\rm e}$ of 20 kHz		98				
Signal to holse ratio (SINR)("	ADS8482IB	- V <sub>IN</sub> = 8 V <sub>pp</sub> at 20 kHz		98.5				
	ADS84821	− V <sub>IN</sub> = 8 V <sub>pp</sub> at 100 kHz		95				
	ADS8482IB	$v_{IN} = \delta v_{pp} at 100 \text{ kHz}$		97				
	ADS84821		96	98.5		dB		
	ADS8482IB	- V <sub>IN</sub> = 8 V <sub>pp</sub> at 2 kHz	97.5	99				
Signal to noise + distortion (SINAD) <sup>(1)</sup>	ADS84821	−− V <sub>IN</sub> = 8 V <sub>pp</sub> at 20 kHz		97				
Signal to hoise + distortion (SINAD)	ADS8482IB	$v_{IN} = 0 v_{pp} at 20 \text{ km}z$		98				
	ADS84821	$V_{\rm c} = 8 V_{\rm c}$ at 100 kHz		93				
	ADS8482IB	- V <sub>IN</sub> = 8 V <sub>pp</sub> at 100 kHz		95				
	ADS84821			120				
	ADS8482IB	- V <sub>IN</sub> = 8 V <sub>pp</sub> at 2 kHz		123				
Spurious free dynamic range (SEDB)(1)	ADS84821			107		dB		
Spurious free dynamic range (SFDR) <sup>(1)</sup>	ADS8482IB	- V <sub>IN</sub> = 8 V <sub>pp</sub> at 20 kHz		113				
	ADS84821			102				
	ADS8482IB	- V <sub>IN</sub> = 8 V <sub>pp</sub> at 100 kHz		105				
–3dB Small signal bandwidth				15		MHz		

(1) Calculated on the first nine harmonics of the input frequency.

# SPECIFICATIONS (Continued)

 $T_A = -40^{\circ}C$  to 85°C, +VA = 5 V, +VBD = 3 V or 5 V,  $V_{ref} = 4.096$  V,  $f_{SAMPLE} = 1$  MSPS (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
VOLTAGE REI	FERENCE INPUT					
Reference volta	age at REFIN, V <sub>ref</sub>		3.0	4.096	+VA – 0.8	V
Reference resistance <sup>(1)</sup>				500		kΩ
Reference current drain		f <sub>s</sub> = 1 MHz			1	mA
INTERNAL RE	FERENCE OUTPUT					
Internal referen	ce start-up time	From 95% (+VA), with 1-µF storage capacitor			120	ms
Reference volta	age range, V <sub>ref</sub>	$I_{O} = 0$	4.081	4.096	4.111	V
Source current		Static load			10	μA
Line regulation		+VA = 4.75 V ~ 5.25 V		60		μV
Drift		$I_{O} = 0$		±6		PPM/°C
DIGITAL INPU	T/OUTPUT					
Logic family -C	MOS					
	V <sub>IH</sub>	I <sub>IH</sub> = 5 μA	+VBD – 1		+VBD + 0.3	
Logic level	VIL	$I_{IL} = 5 \ \mu A$	-0.3		0.8	v
Logic level	V <sub>OH</sub>	I <sub>OH</sub> = 2 TTL loads	+VBD - 0.6			v
	V <sub>OL</sub>	I <sub>OL</sub> = 2 TTL loads				
Data format – S	Straight Binary					
POWER SUPP	LY REQUIREMENTS					
Power supply	+VBD		2.7	3.3	5.25	V
voltage +VA			4.75	5	5.25	V
Supply current	2)	f <sub>s</sub> = 1 MHz		45	50	mA
Power dissipation <sup>(2)</sup>		f <sub>s</sub> = 1 MHz		225	250	mW
TEMPERATUR	ERANGE					
Operating free-	air		-40		85	°C

(1) Can vary ±20%

(2) This includes only +VA current. +VBD current is typical 1 mA with 5 pF load capacitance on all output pins.

### **TIMING CHARACTERISTICS**

All specifications typical at  $-40^{\circ}$ C to  $85^{\circ}$ C, +VA = +VBD = 5 V (1)(2)(3)

	PARAMETER	MIN	ТҮР	MAX	UNIT
t <sub>(CONV)</sub>	Conversion time			650	ns
t <sub>(ACQ)</sub>	Acquisition time	320			ns
t <sub>(HOLD)</sub>	Sample capacitor hold time			25	ns
t <sub>pd1</sub>	CONVST low to BUSY high			40	ns
t <sub>pd2</sub>	Propagation delay time, end of conversion to BUSY low			15	ns
t <sub>pd3</sub>	Propagation delay time, start of convert state to rising edge of BUSY			15	ns
t <sub>w1</sub>	Pulse duration, CONVST low	40			ns
t <sub>su1</sub>	Setup time, CS low to CONVST low	20			ns
t <sub>w2</sub>	Pulse duration, CONVST high	20			ns
	CONVST falling edge jitter			10	ps
t <sub>w3</sub>	Pulse duration, BUSY signal low	t <sub>(ACQ)</sub> min			ns
t <sub>w4</sub>	Pulse duration, BUSY signal high			650	ns
t <sub>h1</sub>	Hold time, first data bus transition ( $\overline{RD}$ low, or $\overline{CS}$ low for read cycle, or BYTE or BUS18/16 input changes) after $\overline{CONVST}$ low	40			ns
t <sub>d1</sub>	Delay time, CS low to RD low	0			ns
t <sub>su2</sub>	Setup time, RD high to CS high	0			ns
t <sub>w5</sub>	Pulse duration, RD low	50			ns
t <sub>en</sub>	Enable time, $\overline{RD}$ low (or $\overline{CS}$ low for read cycle) to data valid			20	ns
t <sub>d2</sub>	Delay time, data hold from RD high	5			ns
t <sub>d3</sub>	Delay time, BUS18/16 or BYTE rising edge or falling edge to data valid	10		20	ns
t <sub>w6</sub>	Pulse duration, RD high	20			ns
t <sub>w7</sub>	Pulse duration, CS high	20			ns
t <sub>h2</sub>	Hold time, last $\overline{RD}$ (or $\overline{CS}$ for read cycle ) rising edge to $\overline{CONVST}$ falling edge	50			ns
t <sub>pd4</sub>	Propagation delay time, BUSY falling edge to next $\overline{RD}$ (or $\overline{CS}$ for read cycle) falling edge	0			ns
t <sub>d4</sub>	Delay time, BYTE edge to BUS18/16 edge skew	0			ns
t <sub>su3</sub>	Setup time, BYTE or BUS18/16 transition to RD falling edge	10			ns
t <sub>h3</sub>	Hold time, BYTE or BUS18/16 transition to RD falling edge	10			ns
t <sub>dis</sub>	Disable time, RD high (CS high for read cycle) to 3-stated data bus			20	ns
t <sub>d5</sub>	Delay time, BUSY low to MSB data valid delay			0	ns
t <sub>d6</sub>	Delay time, CS rising edge to BUSY falling edge	50			ns
t <sub>d7</sub>	Delay time, BUSY falling edge to $\overline{CS}$ rising edge	50			ns
t <sub>su5</sub>	BYTE transition setup time, from BYTE transition to next BYTE transition, or BUS18/16 transition setup time, from BUS18/16 to next BUS18/16.	50			ns
t <sub>su(ABORT)</sub>	Setup time from the falling edge of $\overline{\text{CONVST}}$ (used to start the valid conversion) to the next falling edge of $\overline{\text{CONVST}}$ (when CS = 0 and $\overline{\text{CONVST}}$ are used to abort) or to the next falling edge of $\overline{\text{CS}}$ (when $\overline{\text{CS}}$ is used to abort).	60		550	ns

(1) All input signals are specified with  $t_r = t_f = 5$  ns (10% to 90% of +VBD) and timed from a voltage level of (V<sub>IL</sub> + V<sub>IH</sub>)/2. (2) See timing diagrams. (3) All timing are measured with 20 pF equivalent loads on all data bits and BUSY pins.

## **TIMING CHARACTERISTICS**

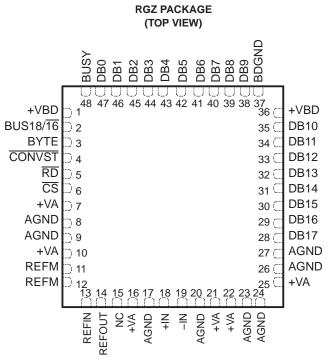
All specifications typical at  $-40^{\circ}$ C to  $85^{\circ}$ C, +VA = 5 V + VBD = 3 V (1)(2)(3)

	PARAMETER	MIN	TYP	MAX	UNIT
t <sub>(CONV)</sub>	Conversion time			650	ns
t <sub>(ACQ)</sub>	Acquisition time	310			ns
t <sub>(HOLD)</sub>	Sample capacitor hold time			25	ns
t <sub>pd1</sub>	CONVST low to BUSY high			40	ns
t <sub>pd2</sub>	Propagation delay time, end of conversion to BUSY low			25	ns
t <sub>pd3</sub>	Propagation delay time, start of convert state to rising edge of BUSY			25	ns
t <sub>w1</sub>	Pulse duration, CONVST low	40			ns
t <sub>su1</sub>	Setup time, CS low to CONVST low	20			ns
t <sub>w2</sub>	Pulse duration, CONVST high	20			ns
	CONVST falling edge jitter			10	ps
t <sub>w3</sub>	Pulse duration, BUSY signal low	t <sub>(ACQ)</sub> min			ns
t <sub>w4</sub>	Pulse duration, BUSY signal high			650	ns
t <sub>h1</sub>	Hold time, first data bus transition ( $\overline{RD}$ low, or $\overline{CS}$ low for read cycle, or BYTE or BUS18/16 input changes) after $\overline{CONVST}$ low	40			ns
t <sub>d1</sub>	Delay time, CS low to RD low	0			ns
t <sub>su2</sub>	Setup time, RD high to CS high	0			ns
t <sub>w5</sub>	Pulse duration, RD low	50			ns
t <sub>en</sub>	Enable time, $\overline{RD}$ low (or $\overline{CS}$ low for read cycle) to data valid			30	ns
t <sub>d2</sub>	Delay time, data hold from RD high	5			ns
t <sub>d3</sub>	Delay time, BUS18/16 or BYTE rising edge or falling edge to data valid	10		30	ns
t <sub>w6</sub>	Pulse duration, RD high	20			ns
t <sub>w7</sub>	Pulse duration, CS high	20			ns
t <sub>h2</sub>	Hold time, last $\overline{RD}$ (or $\overline{CS}$ for read cycle ) rising edge to $\overline{CONVST}$ falling edge	50			ns
t <sub>pd4</sub>	Propagation delay time, BUSY falling edge to next $\overline{RD}$ (or $\overline{CS}$ for read cycle) falling edge	0			ns
t <sub>d4</sub>	Delay time, BYTE edge to BUS18/16 edge skew	0			ns
t <sub>su3</sub>	Setup time, BYTE or BUS18/16 transition to RD falling edge	10			ns
t <sub>h3</sub>	Hold time, BYTE or BUS18/16 transition to RD falling edge	10			ns
t <sub>dis</sub>	Disable time, $\overline{RD}$ high ( $\overline{CS}$ high for read cycle) to 3-stated data bus			30	ns
t <sub>d5</sub>	Delay time, BUSY low to MSB data valid delay			0	ns
t <sub>d6</sub>	Delay time, CS rising edge to BUSY falling edge	50			ns
t <sub>d7</sub>	Delay time, BUSY falling edge to $\overline{CS}$ rising edge	50			ns
t <sub>su5</sub>	BYTE transition setup time, from BYTE transition to next BYTE transition, or BUS18/16 transition setup time, from BUS18/16 to next BUS18/16.	50			ns
t <sub>su(ABORT)</sub>	Setup time from the falling edge of $\overrightarrow{\text{CONVST}}$ (used to start the valid conversion) to the next falling edge of $\overrightarrow{\text{CONVST}}$ (when CS = 0 and $\overrightarrow{\text{CONVST}}$ are used to abort) or to the next falling edge of $\overrightarrow{\text{CS}}$ (when $\overrightarrow{\text{CS}}$ is used to abort).	70		550	ns

(1) All input signals are specified with  $t_r = t_f = 5$  ns (10% to 90% of +VBD) and timed from a voltage level of (V<sub>IL</sub> + V<sub>IH</sub>)/2.

(2) See timing diagrams.
(3) All timing are measured with 20 pF equivalent loads on all data bits and BUSY pins.

#### **PIN ASSIGNMENTS**



NC - No internal connection

NOTE: The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

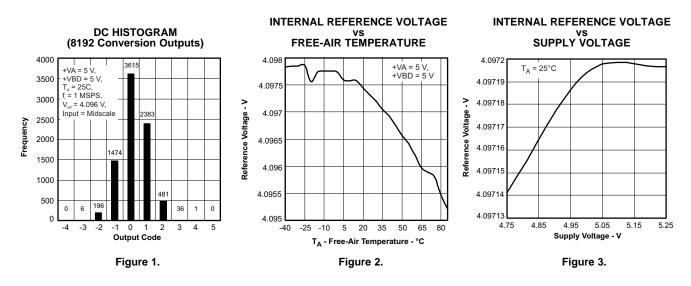
#### **TERMINAL FUNCTIONS**

NAME	NO	I/O			DESCRI	PTION					
AGND	8, 9, 17, 20, 23, 24, 26, 27	-	Analog ground	nalog ground							
BDGND	37	-	Digital ground for bus	ital ground for bus interface digital supply							
BUSY	48	0	Status output. High w	hen a conversion is	in progress.						
BUS18/ <del>16</del>	2	I	0: Data bits output or 1: Last two data bits a) the low byte pir	te select input. Used for selecting 18-bit or 16-bit wide bus transfer. I bits output on the 18-bit data bus pins DB[17:0]. two data bits D[1:0] from 18-bit wide bus output on: the low byte pins DB[9:2] if BYTE = 0 the high byte pins DB[17:10] if BYTE = 1							
BYTE	3	Ι	0: No fold back	ect input. Used for 8-bit bus reading. d back yte D[9:2] of the 16 most significant bits is folded back to high byte of the 16 most significant pins DB[17:10].							
CONVST	4	Ι	Convert start. The fa	vert start. The falling edge of this input ends the acquisition period and starts the hold period.							
CS	6	-	Chip select. The falling	ng edge of this input	starts the acquisition	period.					
				8-BIT BUS		16-BI	T BUS	18-BIT BUS			
Data Bus			BYTE = 0	BYTE = 1	BYTE = 1	BYTE = 0	BYTE = 0	BYTE = 0			
			BUS18/16 = 0	BUS18/16 = 0	BUS18/16 = 1	BUS18/16 = 0	BUS18/16 = 1	BUS18/16 = 0			
DB17	28	0	D17 (MSB)	D9	All ones	D17 (MSB)	All ones	D17 (MSB)			
DB16	29	0	D16	D8	All ones	D16	All ones	D16			
DB15	30	0	D15	D7	All ones	D15	All ones	D15			
DB14	31	0	D14	D6	All ones	D14	All ones	D14			
DB13	32	0	D13	D5	All ones	D13	All ones	D13			
DB12	33	0	D12	D4	All ones	D12	All ones	D12			
DB11	34	0	D11	D3	D1	D11	All ones	D11			
DB10	35	0	D10	D2	D0 (LSB)	D10	All ones	D10			
DB9	38	0	D9	All ones	All ones	D9	All ones	D9			

NAME	NO	I/O				SCRIPTION			
DB8	39	0	D8	All ones	All ones	D8	All ones	D8	
DB7	40	0	D7	All ones	All ones	D7	All ones	D7	
DB6	41	0	D6	All ones	All ones	D6	All ones	D6	
DB5	42	0	D5	All ones	All ones	D5	All ones	D5	
DB4	43	0	D4	All ones	All ones	D4	All ones	D4	
DB3	44	0	D3	All ones	All ones	D3	D1	D3	
DB2	45	0	D2	All ones	All ones	D2	D0 (LSB)	D2	
DB1	46	0	D1	All ones	All ones	D1	All ones	D1	
DB0	47	0	D0 (LSB)	All ones	All ones	D0 (LSB)	All ones	D0 (LSB)	
–IN	19	I	Inverting input cha	innel					
+IN	18	I	Noninverting input	channel					
NC	15		No connection						
REFIN	13	- I	Reference input						
REFOUT	14	0	Reference output.	Add 1-µF capacito	r between the REFO	UT pin and REFM pi	n when internal refe	erence is used.	
REFM	11, 12	- I	Reference ground						
RD	5	I		which represent the parallel output. When $\overline{\text{CS}}$ is low, this serves as output enable and puts the previous proversion results on the bus.					
+VA	7, 10, 16, 21, 22, 25	-	Analog power sup	nalog power supplies, 5-V DC					
+VBD	1, 36	-	Digital power supp	ly for bus					

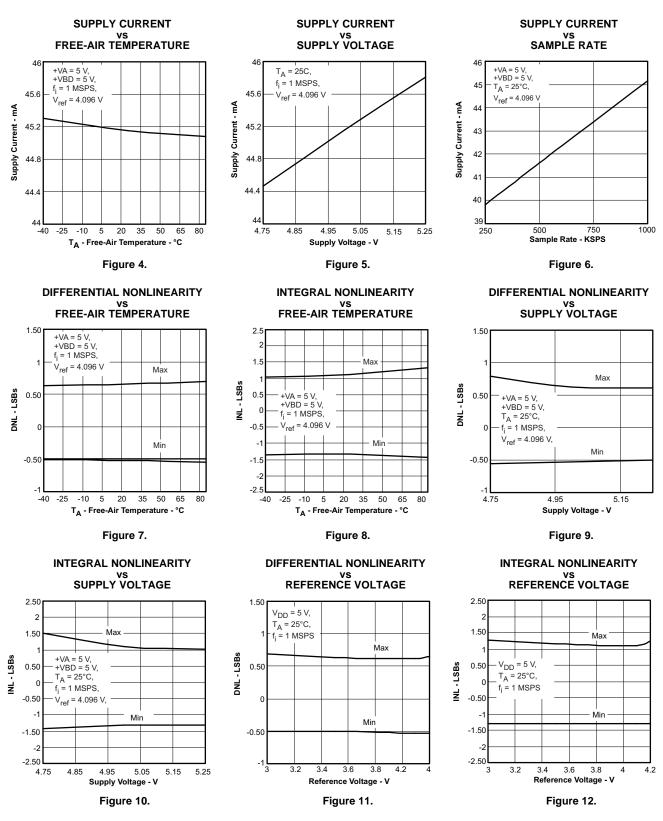
### **TERMINAL FUNCTIONS (continued)**

## **TYPICAL CHARACTERISTICS**

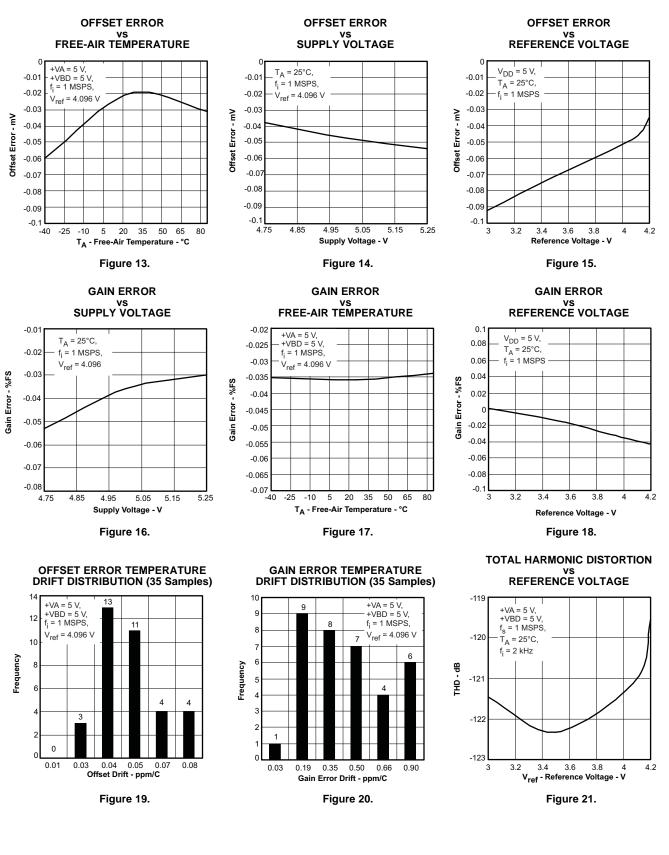








## **TYPICAL CHARACTERISTICS (continued)**



99.5

99

98.5

98

97.5

120.5

120

119.5

119

118.5

-40 -25 -10 5 20 35 50 65 80

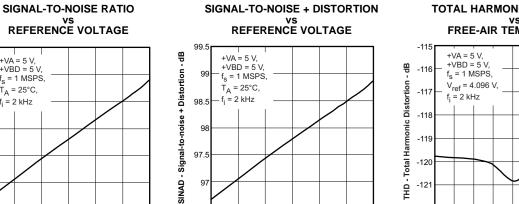


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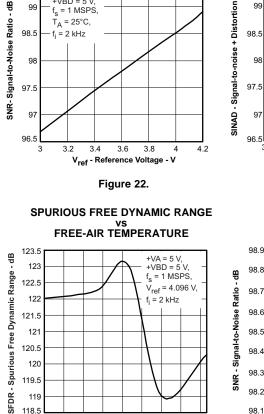
+VA = 5 V, +VBD = 5 V, f<sub>s</sub> = 1 MSPS,

T<sub>A</sub> = 25°C,

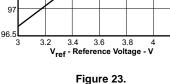
 $f_i = 2 \text{ kHz}$ 



### **TYPICAL CHARACTERISTICS (continued)**



T<sub>A</sub> - Free-Air Temperature - °C Figure 25.



SIGNAL-TO-NOISE RATIO VS FREE-AIR TEMPERATURE

98.4

98.3

98.2

98.1

-40 -25 -10 5 20 35 50 65 80

+VA = 5 V,

 $f_i = 2 \text{ kHz}$ 

+VBD = 5 V.

 $f_s = 1 \text{ MSPS},$ 

V<sub>ref</sub> = 4.096 V.

4.2

## TOTAL HARMONIC DISTORTION vs FREE-AIR TEMPERATURE

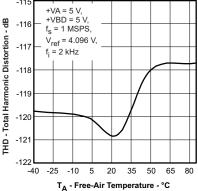


Figure 24.

SIGNAL-TO-NOISE + DISTORTION VS FREE-AIR TEMPERATURE

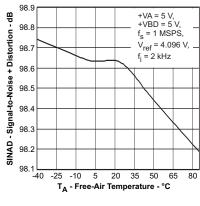
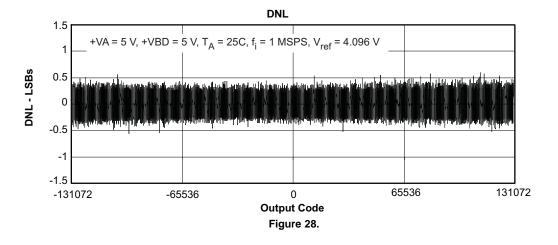


Figure 27.



T<sub>A</sub> - Free-Air Temperature - °C

Figure 26.



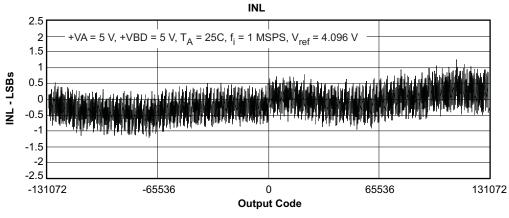
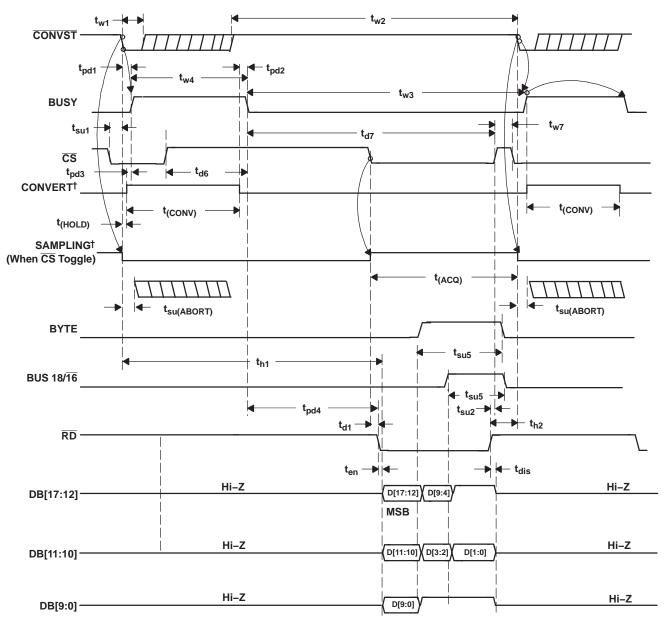


Figure 29.

### TIMING DIAGRAMS



<sup>†</sup>Signal internal to device

## Figure 30. Timing for Conversion and Acquisition Cycles With $\overline{CS}$ and $\overline{RD}$ Toggling

## ADS8482

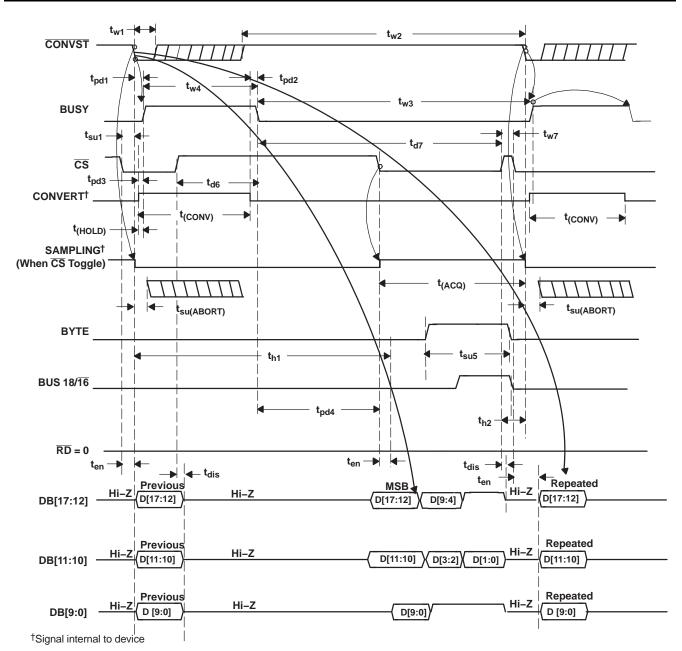
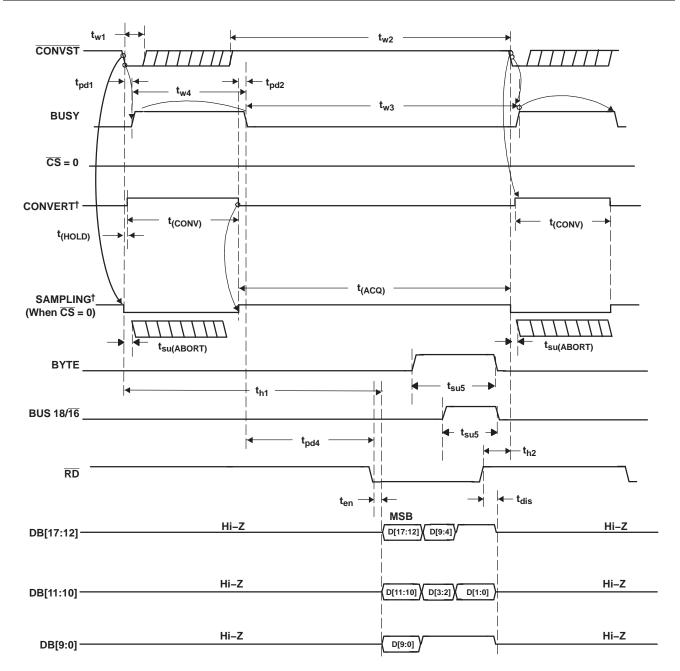


Figure 31. Timing for Conversion and Acquisition Cycles With CS Toggling, RD Tied to BDGND

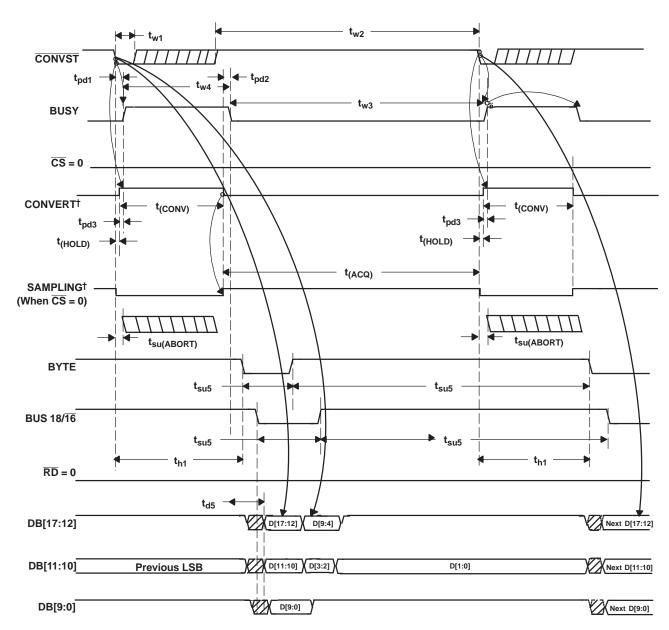


<sup>†</sup>Signal internal to device

Figure 32. Timing for Conversion and Acquisition Cycles With CS Tied to BDGND, RD Toggling

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<sup>†</sup>Signal internal to device

Figure 33. Timing for Conversion and Acquisition Cycles With CS and RD Tied to BDGND - Auto Read

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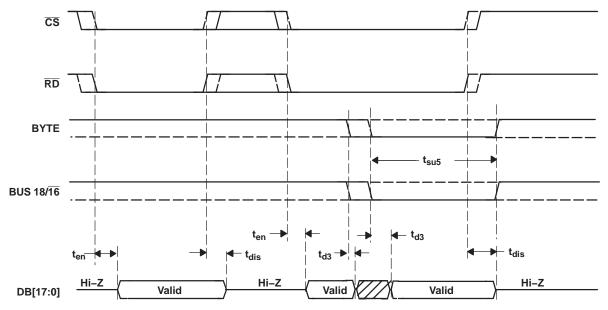


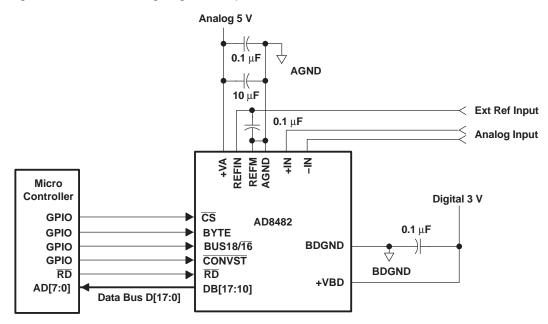
Figure 34. Detailed Timing for Read Cycles

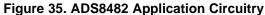
## **APPLICATION INFORMATION**

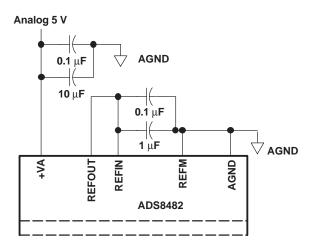
### **MICROCONTROLLER INTERFACING**

### ADS8482 to 8-Bit Microcontroller Interface

Figure 35 shows a parallel interface between the ADS8482 and a typical microcontroller using the 8-bit data bus. The BUSY signal is used as a falling-edge interrupt to the microcontroller.











## **PRINCIPLES OF OPERATION**

The ADS8482 is a high-speed successive approximation register (SAR) analog-to-digital converter (ADC). The architecture is based on charge redistribution which inherently includes a sample/hold function. See Figure 35 for the application circuit for the ADS8482.

The conversion clock is generated internally. The conversion time of 650 ns is capable of sustaining a 1 MHz throughput.

The analog input is provided to two input pins: +IN and –IN. When a conversion is initiated, the differential input on these pins is sampled on the internal capacitor array. While a conversion is in progress, both inputs are disconnected from any internal function.

### REFERENCE

The ADS8482 can operate with an external reference with a range from 3.0 V to 4.2 V. The reference voltage on the input pin #13 (REFIN) of the converter is internally buffered. A clean, low noise, well-decoupled reference voltage on this pin is required to ensure good performance of the converter. A low noise band-gap reference like the REF3240 can be used to drive this pin. A 0.1- $\mu$ F decoupling capacitor is required between REFIN and REFM pins (pin #13 and pin #12) of the converter. This capacitor should be placed as close as possible to the pins of the device. Designers should strive to minimize the routing length of the traces that connect the terminals of the capacitor to the pins of the converter. An RC network can also be used to filter the reference voltage. A 100- $\Omega$  series resistor and a 0.1- $\mu$ F capacitor, which can also serve as the decoupling capacitor can be used to filter the reference voltage.

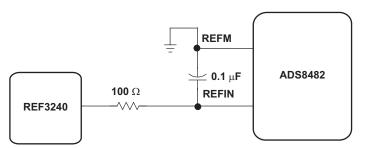


Figure 37. ADS8482 Using External Reference

The ADS8482 also has limited low pass filtering capability built into the converter. The equivalent circuitry on the REFIN input ia as shown in Figure 38.

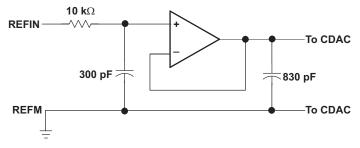


Figure 38. Simplified Reference Input Circuit

The REFM input of the ADS8482 should always be shorted to AGND. A 4.096-V internal reference is included. When internal reference is used, pin 14 (REFOUT) is connected to pin 13 (REFIN) with an 0.1- $\mu$ F decoupling capacitor and 1- $\mu$ F storage capacitor between pin 14 (REFOUT) and pins 11 and 12 (REFM) (see Figure 36). The internal reference of the converter is double buffered. If an external reference is used, the second buffer provides isolation between the external reference and the CDAC. This buffer is also used to recharge all of the capacitors of the CDAC during conversion. Pin 14 (REFOUT) can be left unconnected (floating) if external reference is used.

## **PRINCIPLES OF OPERATION (continued)**

### **ANALOG INPUT**

When the converter enters the hold mode, the voltage difference between the +IN and –IN inputs is captured on the internal capacitor array. Both +IN and –IN input has a range of –0.2 V to Vref + 0.2 V. The input span [+IN – (–IN)] is limited to  $-V_{ref}$  to  $V_{ref}$ .

The input current on the analog inputs depends upon a number of factors: sample rate, input voltage, and source impedance. Essentially, the current into the ADS8482 charges the internal capacitor array during the sample period. After this capacitance has been fully charged, there is no further input current. The source of the analog input must be able to charge the input capacitance (65 pF) to an 18-bit settling level within the acquisition time (320 ns) of the device. When the converter goes into the hold mode, the input impedance is greater than 1 G $\Omega$ .

Care must be taken regarding the absolute analog input voltage. To maintain the linearity of the converter, the +IN and -IN inputs and the span [+IN - (-IN)] must be within the limits specified. Outside of these ranges, the converter's linearity may not meet specifications. To minimize noise, low bandwidth input signals with low-pass filters are used.

Care must be taken to ensure that the output impedance of the sources driving the +IN and -IN inputs are matched. If this is not observed, the two inputs could have different setting times. This may result in offset error, gain error, and linearity error which varies with temperature and input voltage.

The analog input to the converter needs to be driven with a low noise, high-speed op-amp like the THS4031. An RC filter is recommended at the input pins to low-pass filter the noise from the source. The input to the converter is a uni-polar input voltage in the range 0 to  $V_{ref}$ . The THS4031 can be used in the source follower configuration to drive the converter.



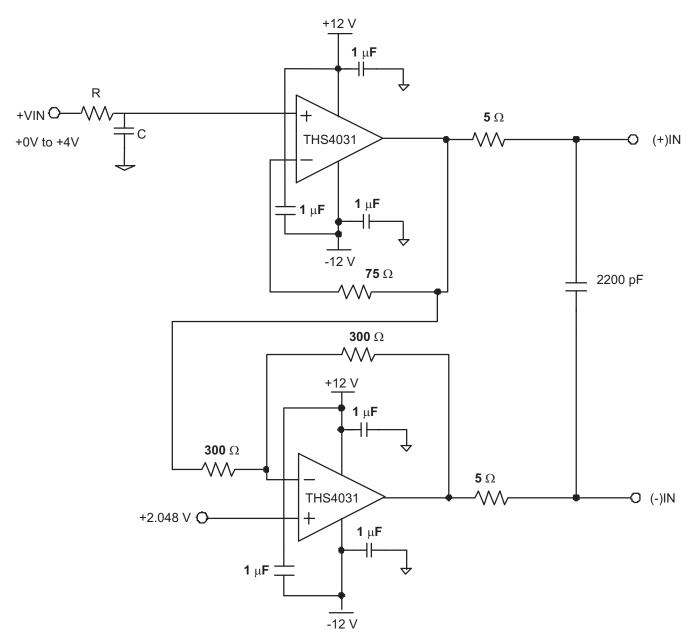


Figure 39. Single-Ended Input, Differential Output Configuration

In systems, where the input is differential, the THS4031 can be used in the inverting configuration with an additional DC bias applied to its + input so as to keep the input to the ADS8482 within its rated operating voltage range. The DC bias can be derived from the REF3220 or the REF3240 reference voltage ICs. The input configuration shown below is capable of delivering better than 97dB SNR and -103db THD at an input frequency of 100 kHz. In case band-pass filters are used to filter the input, care should be taken to ensure that the signal swing at the input of the band-pass filter is small so as to keep the distortion introduced by the filter minimal. In such cases, the gain of the circuit shown below can be increased to keep the input to the ADS8482 large to keep the SNR of the system high. Note that the gain of the system from the + input to the output of the THS4031 in such a configuration is a function of the gain of the AC signal. A resistor divider can be used to scale the output of the REF3220 or REF3240 to reduce the voltage at the DC input to THS4031 to keep the voltage at the input of the converter within its rated operating range.



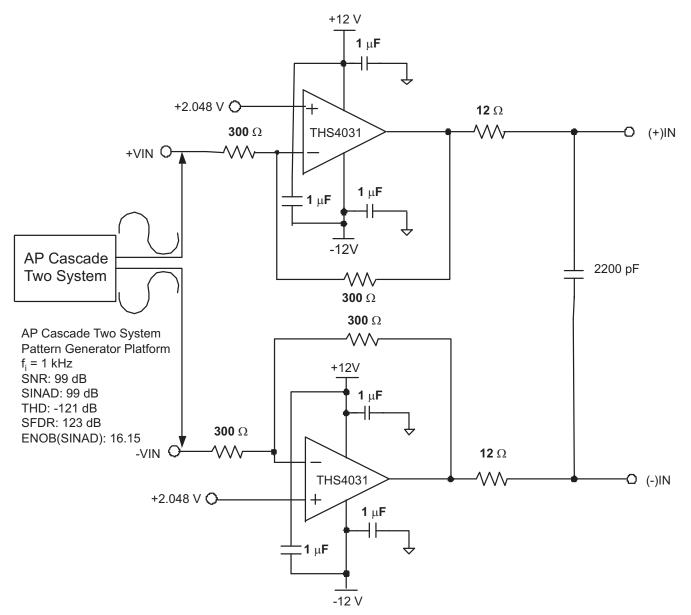


Figure 40. Differential Input, Differential Output Configuration

### DIGITAL INTERFACE

### Timing and Control

See the timing diagrams in the specifications section for detailed information on timing signals and their requirements.

The ADS8482 uses an internal oscillator generated clock which controls the conversion rate and in turn the throughput of the converter. No external clock input is required.



### PRINCIPLES OF OPERATION (continued)

Conversions are initiated by bringing the CONVST pin low for a minimum of 20 ns (after the 20 ns minimum requirement has been met, the CONVST pin can be brought high), while CS is low. The ADS8482 switches from the sample to the hold mode on the falling edge of the CONVST command. A clean and low jitter falling edge of this signal is important to the performance of the converter. The BUSY output is brought high immediately following CONVST going low. BUSY stays high throughout the conversion process and returns low when the conversion has ended.

Sampling starts with the falling edge of the BUSY signal when  $\overline{CS}$  is tied low or starts with the falling edge of  $\overline{CS}$  when BUSY is low.

Both  $\overline{RD}$  and  $\overline{CS}$  can be high during and before a conversion with one exception ( $\overline{CS}$  must be low when  $\overline{CONVST}$  goes low to initiate a conversion). Both the  $\overline{RD}$  and  $\overline{CS}$  pins are brought low in order to enable the parallel output bus with the conversion.

### **Reading Data**

The ADS8482 outputs full parallel data in straight binary format as shown in Table 1. The parallel output is active when  $\overline{CS}$  and  $\overline{RD}$  are both low. There is a minimal quiet zone requirement around the falling edge of  $\overline{CONVST}$ . This is 50 ns prior to the falling edge of  $\overline{CONVST}$  and 40 ns after the falling edge. No data read should attempted within this zone. Any other combination of  $\overline{CS}$  and  $\overline{RD}$  sets the parallel output to 3-state. BYTE and BUS18/16 are used for multiword read operations. BYTE is used whenever lower bits on the bus are output on the higher byte of the bus. BUS18/16 is used whenever the last two bits on the 18-bit bus is output on either bytes of the higher 16-bit bus. Refer to Table 1 for ideal output codes.

DESCRIPTION	ANALOG VALUE	DIGITAL OUTPUT STR	AIGHT BINARY	
Full scale range	+V <sub>ref</sub>			
Least significant bit (LSB)	$2 \times (+V_{ref})/262144$	BINARY CODE	HEX CODE	
+Full scale	(+V <sub>ref</sub> ) – 1 LSB	01 1111 1111 1111 1111	1FFFF	
Midscale	0 V	00 0000 0000 0000 0000	00000	
Midscale – 1 LSB	0 V – 1 LSB	11 1111 1111 1111 1111	3FFFF	
Zero	-V <sub>ref</sub>	10 0000 0000 0000 0000	20000	

#### Table 1. Ideal Input Voltages and Output Codes

The output data is a full 18-bit word (D17–D0) on DB17–DB0 pins (MSB–LSB) if both BUS18/16 and BYTE are low.

The result may also be read on an 16-bit bus by using only pins DB17–DB2. In this case two reads are necessary: the first as before, leaving both BUS18/16 and BYTE low and reading the 16 most significant bits (D17–D2) on pins DB17–DB2, then bringing BUS18/16 high while holding BYTE low. When BUS18/16 is high, the lower two bits (D1–D0) appear on pins DB3–DB2.

The result may also be read on an 8-bit bus for convenience. This is done by using only pins DB17–DB10. In this case three reads are necessary: the first as before, leaving both BUS18/16 and BYTE low and reading the 8 most significant bits on pins DB17–DB10, then bringing BYTE high while holding BUS18/16 low. When BYTE is high, the medium bits (D9–D2) appear on pins DB17–DB10. The last read is done by bringing BUS18/16 high while holding BYTE high. When BUS18/16 is high, the lower two bits (D1–D0) appear on pins DB11–DB10. The last read cycle is not necessary if only the first 16 most significant bits are of interest.

All of these multiword read operations can be performed with multiple active  $\overline{RD}$  (toggling) or with  $\overline{RD}$  held low for simplicity. This is referred to as the AUTO READ operation.

		DATA READ OUT						
BYTE	BUS18/16	PINS DB17–DB12	PINS DB11–DB10	PINS DB9-DB4	PINS DB3-DB2	PINS DB1–DB0		
High	High	All One's	D1-D0	All One's	All One's	All One's		
Low	High	All One's	All One's	All One's	D1-D0	All One's		

 Table 2. Conversion Data Read Out

				•					
		DATA READ OUT							
BYTE	BUS18/16	PINS DB17–DB12	PINS DB11–DB10	PINS DB9–DB4	PINS DB3-DB2	PINS DB1–DB0			
High	Low	D9–D4	D3–D2	All One's	All One's	All One's			
Low	Low	D17–D12	D11–D10	D9–D4	D3–D2	D1–D0			

### Table 2. Conversion Data Read Out (continued)

## RESET

On power-up, internal POWER-ON RESET circuitry generates the reset required for the device. The first three conversions after power-up are used to load factory trimming data for a specific device to assure high accuracy of the converter. The results of the first three conversions are invalid and should be discarded.

The device can also be reset through the use of the combination fo CS and CONVST. Since the BUSY signal is held at high during the conversion, either one of these conditions triggers an internal self-clear reset to the converter.

- Issue a CONVST when CS is low and the internal convert state is high. The falling edge of CONVST starts a reset.
- Issue a  $\overline{CS}$  (select the device) while the internal convert state is high. The falling edge of  $\overline{CS}$  causes a reset.

Once the device is reset, all output latches are cleared (set to zeroes) and the BUSY signal is brought low. A new sampling period is started at the falling edge of the BUSY signal immediately after the instant of the internal reset.

## LAYOUT

For optimum performance, care must be taken with the physical layout of the ADS8482 circuitry.

As the ADS8482 offers single-supply operation, it is often used in close proximity with digital logic, microcontrollers, microprocessors, and digital signal processors. The more digital logic present in the design and the higher the switching speed, the more difficult it is to achieve good performance from the converter.

The basic SAR architecture is sensitive to glitches or sudden changes on the power supply, reference, ground connections and digital inputs that occur just prior to latching the output of the analog comparator. Thus, driving any single conversion for an n-bit SAR converter, there are at least n windows in which large external transient voltages can affect the conversion result. Such glitches might originate from switching power supplies, nearby digital logic, or high power devices.

The degree of error in the digital output depends on the reference voltage, layout, and the exact timing of the external event.

On average, the ADS8482 draws very little current from an external reference as the reference voltage is internally buffered. If the reference voltage is external and originates from an op amp, make sure that it can drive the bypass capacitor or capacitors without oscillation. A  $0.1-\mu$ F capacitor is recommended from pin 13 (REFIN) directly to pin 12 (REFM). REFM and AGND must be shorted on the same ground plane under the device.

The AGND and BDGND pins should be connected to a clean ground point. In all cases, this should be the analog ground. Avoid connections which are too close to the grounding point of a microcontroller or digital signal processor. If required, run a ground trace directly from the converter to the power supply entry point. The ideal layout consists of an analog ground plane dedicated to the converter and associated analog circuitry.

As with the AGND connections, +VA should be connected to a 5-V power supply plane or trace that is separate from the connection for digital logic until they are connected at the power entry point. Power to the ADS8482 should be clean and well bypassed. A 0.1- $\mu$ F ceramic bypass capacitor should be placed as close to the device as possible. See Table 3 for the placement of the capacitor. In addition, a 1- $\mu$ F to 10- $\mu$ F capacitor is recommended. In some situations, additional bypassing may be required, such as a 100- $\mu$ F electrolytic capacitor or even a Pi filter made up of inductors and capacitors-all designed to essentially low-pass filter the 5-V supply, removing the high frequency noise.



## Table 3. Power Supply Decoupling Capacitor Placement

POWER SUPPLY PLANE	CONVERTER ANALOG SIDE	CONVERTER	
SUPPLY PINS	CONVERTER ANALOG SIDE	DIGITAL SIDE	
Pin pairs that require shortest path to decoupling capacitors	(7,8), (9,10), (16,17), (20,21), (22,23), (25,26)	(36,37)	
Pins that require no decoupling	24, 26	1	

### PACKAGING INFORMATION

Orderable Device	Status <sup>(1)</sup>	Package Type	Package Drawing	Pins	Package Qty	Eco Plan <sup>(2)</sup>	Lead/Ball Finish	MSL Peak Temp <sup>(3)</sup>
ADS8482IBRGZR	ACTIVE	QFN	RGZ	48	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS8482IBRGZRG4	ACTIVE	QFN	RGZ	48	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS8482IBRGZT	ACTIVE	QFN	RGZ	48	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS8482IBRGZTG4	ACTIVE	QFN	RGZ	48	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS8482IRGZR	ACTIVE	QFN	RGZ	48	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS8482IRGZRG4	ACTIVE	QFN	RGZ	48	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS8482IRGZT	ACTIVE	QFN	RGZ	48	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS8482IRGZTG4	ACTIVE	QFN	RGZ	48	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details. TBD: The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

<sup>(3)</sup> MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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## TAPE AND REEL INFORMATION





# QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal Device		Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ADS8482IBRGZR	QFN	RGZ	48	1000	330.0	16.4	7.3	7.3	1.5	12.0	16.0	Q2
ADS8482IBRGZT	QFN	RGZ	48	250	330.0	16.4	7.3	7.3	1.5	12.0	16.0	Q2
ADS8482IRGZR	QFN	RGZ	48	1000	330.0	16.4	7.3	7.3	1.5	12.0	16.0	Q2
ADS8482IRGZT	QFN	RGZ	48	250	330.0	16.4	7.3	7.3	1.5	12.0	16.0	Q2



# PACKAGE MATERIALS INFORMATION

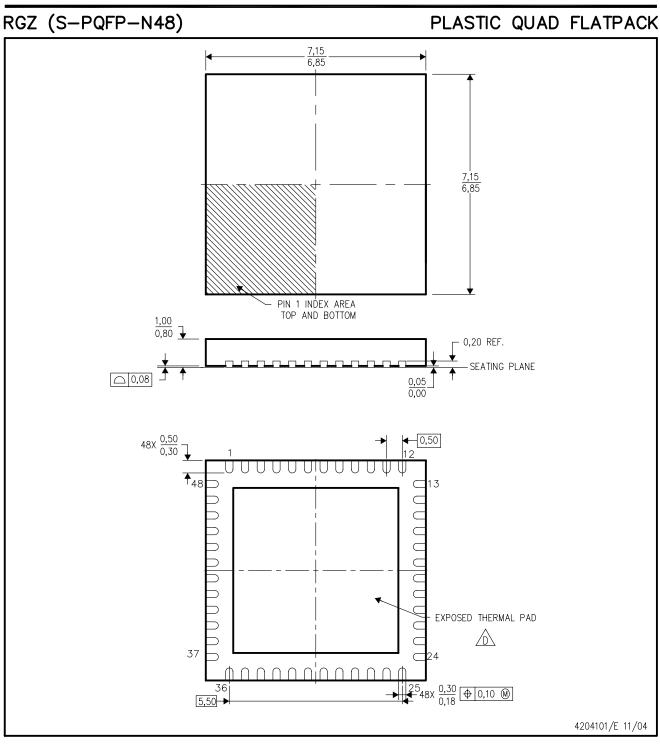
19-Mar-2008



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
ADS8482IBRGZR	QFN	RGZ	48	1000	333.2	345.9	28.6
ADS8482IBRGZT	QFN	RGZ	48	250	333.2	345.9	28.6
ADS8482IRGZR	QFN	RGZ	48	1000	333.2	345.9	28.6
ADS8482IRGZT	QFN	RGZ	48	250	333.2	345.9	28.6

# **MECHANICAL DATA**



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. Quad Flatpack, No-leads (QFN) package configuration.

The package thermal pad must be soldered to the board for thermal and mechanical performance. See the Product Data Sheet for details regarding the exposed thermal pad dimensions.

E. Falls within JEDEC MO-220.



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