# **MLX91216 High Speed Current Sensor IC**

Datasheet

## **1. Features and Benefits**

- IMC-Hall<sup>®</sup> Technology
- High Field and Very High Field variants
- End-of-line programmable sensor
- Selectable analog ratiometric output
- Measurement range from ±5 to ±450mT
- Wideband sensing: DC to 250kHz
- Very short response time (2μs)
- High linearity down to ±0.2% full scale
- Very low thermal drift
  - Offset drift (<5mV)</li>
  - Sensitivity drift (<1%)</li>
- Programmable output clamping levels
- Broken wire detection and diagnostics
- AEC-Q100 Grade 0 Automotive Qualified
- RoHS compliant
- SOIC-8 package
- MSL-3

## 2. Application Examples

- High Voltage Traction Motor Inverter
- 48V Boost Recuperation Inverter
- DCDC Converter
- Smart Battery Junction Boxes
- Smart Fuse Overcurrent Detection

## **3. Description**

The MLX91216 is a monolithic Hall-effect sensor utilizing the IMC-Hall<sup>®</sup> technology. The sensor provides an analog output voltage proportional to the applied magnetic flux density parallel to the IC surface.

The transfer characteristic of the MLX91216 is factory trimmed over temperature, and is

programmable (offset, sensitivity, clamping, filtering) during end-of-line customer calibration. The output clamping levels and on-chip filtering are also programmable as a function of application needs. With the 250kHz bandwidth and fast response time, it is particularly adapted for high speed applications such as inverters and converters where fast response time due to fast switching is required.

In a typical current sensing application, the sensor is used in combination with a U-shaped shield which facilitates the mechanical assembly of the current sensor over traditional ferromagnetic cores. This shield is recommended to be laminated for high bandwidth applications. The MLX91216 can then be mounted over the bus bar and separated from it by the PCB. As the shield does not serve the primary purpose of concentration, it can be made smaller and lighter than ferromagnetic cores without losing signal thanks to the integrated magnetic concentrator (IMC) depicted also in Figure 1. As a result, dense power electronics can be achieved enabling system savings and surface mount assembly.



Figure 1. Typical IMC-Hall® Current Sensing Application

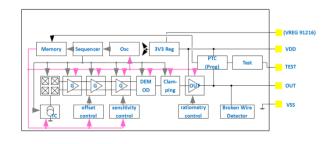


Figure 2. General Block Diagram

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## 4. Ordering Information

Product	Temperature	Package	Option Code	Packing Form	Typical Sensitivity
MLX91216	L	DC	ACH – 000	RE	100 mV/mT (prog: 50350mV/mT)
MLX91216	L	DC	ACV - 000	RE	40 mV/mT (prog: 30200mV/mT)
MLX91216	L	DC	ACV - 001	RE	60 mV/mT (prog: 30200mV/mT)

Table 1: Available ordering codes.

## Legend:

Temperature Code:	L: from -40°C to 150°C ambient temperature
Package Code:	"DC" for SOIC8 package, refer to Chapter 16 for detailed drawings
Option Code:	ACH-000: 100mV/mT sensitivity (50-350mV/mT programmable range) ACV-003: 40mV/mT sensitivity (5-200mV/mT programmable range) ACV-005: 60mV/mT sensitivity (30-200mV/mT programmable range)
Packing Form:	"RE" for Plastic Reel.
Ordering Example:	"MLX91216LDC-ACV-001-RE" MLX91216 IMC-Hall <sup>®</sup> current sensor in SOIC8 package, temperature range -40°C to 150°C. Sensitivity 60mV/mT. Parts delivered in Plastic Reel



## **5. Functional Diagram**

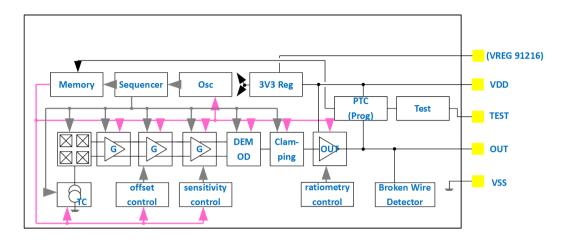


Figure 3: Block Diagram of the MLX91216:

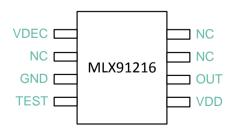
## 6. Glossary of Terms

Terms	Definition
ТС	Temperature Coefficient
FS	Full Scale, output referred. Corresponds to 2V excursion around 2.5V $V_{\text{OQ}}$ point
T, mT	Tesla, milliTesla = units for the magnetic flux density
G	Gauss = unit for the magnetic flux density [1mT = 10G]
PTC	Programming Through Connector
IMC	Integrated Magnetic Concentrator

Table 2: Glossary of Terms

## 7. Pin Definitions and Descriptions

Note: MLX91216 is pin-to-pin compatible with MLX91208.





Pin #	Name	Туре	Description
1	VDEC	Digital	Digital Supply Voltage
2	NC	-	Not Connected
3	GND	Ground	Supply Voltage
4	TEST	Digital	Test and Factory Calibration
5	VDD	Supply	Supply Voltage
6	OUT	Analog	Current Sensor Output
7,8	NC	-	Not Connected

Table 3: Pin definitions and descriptions

For optimal EMC results, it is recommended to connect the unused pins to the Ground (see section 0).

## 8. Absolute Maximum Ratings

Parameter	Symbol	Value	Unit
Positive Supply Voltage (overvoltage)	V <sub>DD</sub>	+10	V
Reverse Voltage Protection	$VS_{REV}$	-0.3	V
Positive Output Voltage	V <sub>OUT</sub>	+10	V
Output Current	I <sub>OUT</sub>	+70	mA
Reverse Output Voltage	VO <sub>REV</sub>	-0.3	V
Reverse Output Current	IO <sub>REV</sub>	-50	mA
Operating Ambient Temperature Range	T <sub>A</sub>	-40 to +150	°C
Storage Temperature Range	Τ <sub>s</sub>	-55 to +165	°C
Magnetic Flux Density	B <sub>MAX</sub>	±3	т
ESD – Human Body Model	ESD <sub>HBM</sub>	2	kV

#### Table 4: Absolute maximum ratings

Exceeding the absolute maximum ratings may cause permanent damage. Exposure to absolute maximum-rated conditions for extended periods of time may affect device reliability.



## 9. General Electrical Specifications

Parameter	Symbol	Test Conditions	Min.	Тур.	Max.	Units
Nominal Supply Voltage	V <sub>DD</sub>		4.5	5	5.5	V
Supply Current	I <sub>DD</sub>	No OUT load LOW_POWER_MODE=0 <sup>1</sup> LOW_POWER_MODE=1		12.5 10	15 13	mA mA
Output Impedance	R <sub>OUT</sub>	Normal Operation		1	5	Ω
Output Capacitive Load	CL	OUT_MODE=0 <sup>1</sup> OUT_MODE=1	2 10		10 47	nF nF
Output Resistive Load	RL		10	25	200	kΩ
Output Short Circuit Current	I <sub>SHORT</sub>	Output shorted to VDD – Permanent Output shorted to GND – Permanent		Not Destr	royed	
Linear Output Range	VO <sub>LIN</sub>	pull-down ≥ 10 kΩ	10		90	%Vdd
Diagnostic Band <sup>2</sup>	DIAG	$R_L \ge 10k\Omega, R_L \le 200 k\Omega, V_{DD} = 5V$ DIAG_LEVEL = 0 DIAG_LEVEL = 1	0 96		4 100	%Vdd %Vdd
BrokenGND Output Level <sup>2</sup>		$R_L \ge 10k\Omega$ , $V_{DD} = 5V$	96		100	%Vdd
BrokenVDD Output Level <sup>2</sup>		$R_L \ge 10 k\Omega$ , $V_{DD} = 5V$	0		4	%Vdd
Under-voltage detection <sup>2</sup>	$V_{DD_UVD}$	Detected Voltage (Low to High)	4.0		4.4	V
onder vortage detection	$V_{\text{DD}\_\text{UVH}}$	Hysteresis	0.00		0.15	V
Over-voltage detection $1^2$	$V_{DD_OVD1}$ $V_{DD_OVH1}$	Detected Voltage (Low to High) Hysteresis	6.7 0.37		7.4 0.66	V V
Over-voltage detection 2 <sup>2</sup>	$V_{DD_OVD2}$	Detected Voltage (Low to High)	8.4		9.3	V
Over-voltage detection 2	$V_{DD_OVH2}$	Hysteresis	0.32		0.68	V
	Clamp_lo0	CLAMP_LEVEL=0	5	6	7	%Vdd
	Clamp_hi0	CLAMP_LEVEL=0	92	93	94	%Vdd
	Clamp_lo1	CLAMP_LEVEL=1	5	6	7	%Vdd
Clamped Output Level	Clamp_hi1	CLAMP_LEVEL=1	93	94	95	%Vdd
	Clamp_lo2	CLAMP_LEVEL=2	7	8	9	%Vdd
	Clamp_hi2	CLAMP_LEVEL=2	91	92	93	%Vdd
	Clamp_lo3	CLAMP_LEVEL=3	9	10	11	%Vdd
	Clamp_hi3	CLAMP_LEVEL=3	89	90	91	%Vdd

Table 5: General electrical parameters

<sup>1</sup> Default Factory Calibration

<sup>2</sup> Please refer to section 12 for more information on self-diagnostic modes.



## **10. Magnetic specification**

Operating Parameters  $T_A = -40$  to 150°C,  $V_{DD} = 5V\pm10\%$ , unless otherwise specified.

## 10.1. High Field version (marking ACH)

Parameter	Symbol	Test Conditions	Min	Тур	Max	Units
Operational Magnetic Field Range	B <sub>OP</sub>				±25	mT
Linearity Error (Magnetic)	NL	B within $B_{OP}$ , $T_A = 25^{\circ}C$			±0.5	%FS
Hysteresis – Remanent Field	B <sub>R</sub>	Measured after $B = B_{OP}$			±25	μΤ
Programmable Sensitivity	S	MLX91216LDC-ACH-000	50	100	350	mV/mT
Sensitivity Programming Resolution	S <sub>RES</sub>	$B = B_{OP}$		0.1		%

Table 6: Magnetic specification High Field version

### 10.2. Very High Field version (marking ACV)

Parameter	Symbol	Test Conditions	Min	Тур	Max	Units
Operational Magnetic Field Range	B <sub>OP</sub>				±60	mT
Linearity Error (Magnetic)	NL	B within $B_{OP}$ , $T_A = 25^{\circ}C$			±0.5	%FS
Hysteresis – Remanent Field	B <sub>R</sub>	Measured after $B = B_{OP}$			±60	μΤ
Programmable Sensitivity	S	MLX91216LDC-ACV-000 MLX91216LDC-ACV-001	30 30	40 60	200 200	mV/mT
Sensitivity Programming Resolution	S <sub>RES</sub>	$B = B_{OP}$		0.1		%

Table 7: Magnetic specification Very High Field version



## **11.** Analog output specification

#### 11.1. Accuracy specifications

Operating Parameters  $T_A = -40$  to 150°C,  $V_{DD} = 5V\pm10\%$ , unless otherwise specified.

Parameter	Symbol	Test Conditions	Min	Тур	Max	Units
Thermal Offset Drift	$\Delta^{T}V_{OQ}$	T <sub>A</sub> = -40 to 125°C T <sub>A</sub> = -40 to 150°C			±5 ±8	mV mV
Thermal Sensitivity Drift	$\Delta^{T}S$	T <sub>A</sub> = -40 to 125°C T <sub>A</sub> = -40 to 150°C			±1.0 ±1.2	%S %S
RMS Output Noise	N <sub>RMS</sub>	Values for 50mV/mT sensitivity Scales with typical sensitivity of Table 1 NOISE_FILTER=0 NOISE_FILTER=1 NOISE_FILTER=2 NOISE_FILTER=3		10 7 5 3		mV <sub>RMS</sub> mV <sub>RMS</sub> mV <sub>RMS</sub> mV <sub>RMS</sub>
V <sub>OQ</sub> Ratiometry	$\Delta^{R}V_{OQ}$	$V_{DD}$ = 5V±5%, $V_{OQ}$ = 50% $V_{DDx}$			±0.4	%V <sub>OQ</sub>
Sensitivity Ratiometry	$\Delta^{R}S$	$V_{DD} = 5V\pm5\%, B = B_{OP}$			±0.4	%S
Clamped output accuracy	$CL_ACC$				±1	%Vdd

 Table 8: Accuracy specifications – analog parameters

The accuracy specifications are defined for the factory calibrated sensitivity. The achievable accuracy is dependent on the user's end-of-line calibration. For application notes on sensor programming and calibration, Resolution for offset and offset drift calibration is better than 0.02%V<sub>DD</sub>. Trimming capability is higher than measurement accuracy. End-user calibration can therefore increase the accuracy of the system.

### 11.2. Timing specifications

Operating Parameters  $T_A = -40$  to  $150^{\circ}$ C, Vdd = 5V±10%, unless otherwise specified.

Parameter	Symbol	Test Conditions	Min	Тур	Max	Units
Step Response Time	T <sub>R</sub>	C <sub>L</sub> =10nF NOISE_FILTER=0, LOW_POWER_MODE=0 NOISE_FILTER=0, LOW_POWER_MODE=1 NOISE_FILTER=1, LOW_POWER_MODE=0 NOISE_FILTER=2, LOW_POWER_MODE=1 NOISE_FILTER=2, LOW_POWER_MODE=1 NOISE_FILTER=3, LOW_POWER_MODE=0 NOISE_FILTER=3, LOW_POWER_MODE=1		2 3 5 4 6 8 10	3 4 6 5 7 9 11	μs μs μs μs μs μs μs μs μs
Power on Delay	T <sub>POD</sub>	Vout =100% of F.S.			1	ms
Ratiometry Cut-off Frequency	F <sub>RAT</sub>			250		Hz

Table 9: Timing specifications of the high-speed analog output



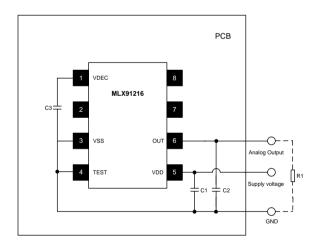
## **12. Self-diagnostic**

MLX91216 provides several self-diagnostic features, which prevent the IC from providing erroneous output signal in case of internal or external failure modes.

Error	Effect on Output	Remarks
Calibration data CRC Error	DIAG_LEVEL=0 $\rightarrow$ active pull-down to GND DIAG_LEVEL=1 $\rightarrow$ active pull-up to VDD	at power up and in normal mode
Power-On Delay	Pull-down to GND	1ms max followed by settling
Over-voltage Mode 1	Active pull-down to GND	
Over-voltage Mode 2	DIAG_LEVEL=0 $\rightarrow$ active pull-down to GND DIAG_LEVEL=1 $\rightarrow$ active pull-up to VDD	
Under-voltage Mode	DIAG_LEVEL=0 $\rightarrow$ active pull-down to GND DIAG_LEVEL=1 $\rightarrow$ active pull-up to VDD	Valid with enabled ratiometry (Default: RATIOEN = 1)
Broken OUT	Active pull-down to GND	
Broken GND	Output pulled up to VDD	IC is switched off
Broken VDD	Output pulled down to GND	IC is switched off

Table 10: Description of the self-diagnostic modes in MLX91216

## **13. Recommended Application Diagram**



#### Figure 4: Application Diagram with external Pull-Down resistance

Part	Description	Value	Unit
C1	Supply capacitor, EMI, ESD	100	nF
C2	Decoupling, EMI, ESD, OUT_MODE=0	2-10	nF
	Decoupling, EMI, ESD, OUT_MODE=1	10-47	nF
C3	Decoupling, EMI, ESD		
R1	Pull down resistor	10-200	kΩ

Table 11: Resistor and capacitor values



## **14. Standard Information**

Our products are classified and qualified regarding soldering technology, solderability and moisture sensitivity level according to standards in place in Semiconductor industry.

#### Reflow Soldering SMD's (Surface Mount Devices)

- IPC/JEDEC J-STD-020 Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices (classification reflow profiles according to table 5-2)
- EIA/JEDEC JESD22-A113 Preconditioning of Nonhermetic Surface Mount Devices Prior to Reliability Testing (reflow profiles according to table 2)

#### Wave Soldering SMD's (Surface Mount Devices) and THD's (Through Hole Devices)

- EN60749-20 Resistance of plastic- encapsulated SMD's to combined effect of moisture and soldering heat
- EIA/JEDEC JESD22-B106 and EN60749-15 Resistance to soldering temperature for through-hole mounted devices

#### Iron Soldering THD's (<u>Through Hole Devices</u>)

• EN60749-15 Resistance to soldering temperature for through-hole mounted devices

#### Solderability SMD's (Surface Mount Devices) and THD's (Through Hole Devices)

• EIA/JEDEC JESD22-B102 and EN60749-21 Solderability

For further details about test method references and for compliance verification of selected soldering method for product integration, Melexis recommends reviewing on our web site the General Guidelines <u>soldering recommendation</u>. For all soldering technologies deviating from the one mentioned in above document (regarding peak temperature, temperature gradient, temperature profile etc), additional classification and qualification tests have to be agreed upon with Melexis.

For package technology embedding trim and form post-delivery capability, Melexis recommends to consult the dedicated trim&form recommendation application note: <u>lead trimming and forming recommendations</u>.

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## **15. ESD Precautions**

Electronic semiconductor products are sensitive to Electro Static Discharge (ESD). Always observe Electro Static Discharge control procedures whenever handling semiconductor products.



## **16.** Packaging information

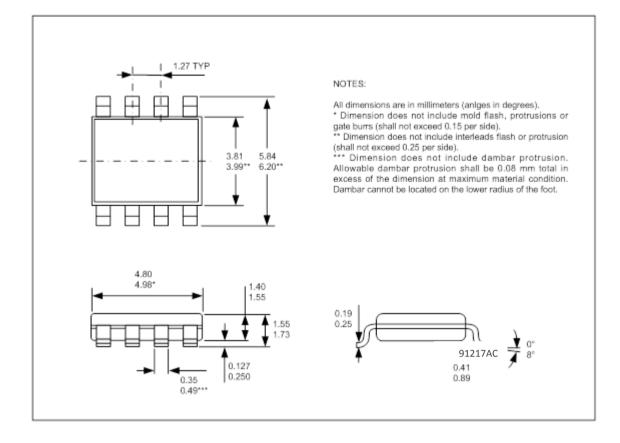


Figure 5: SOIC8 - Package Information

#### 16.1. SOIC-8 Pinout and Marking

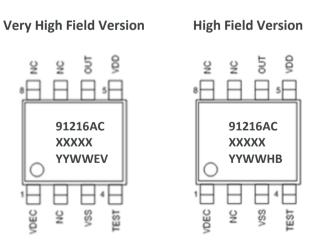


Figure 6: SOIC8 - Pinout and marking



### 16.2. Hall plate position

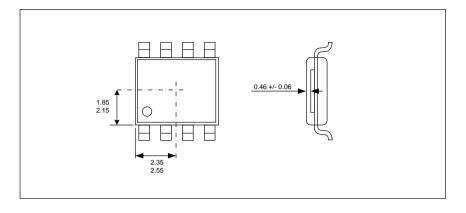


Figure 7: Hall plate position

#### 16.3. IMC Position and sensor active measurement direction

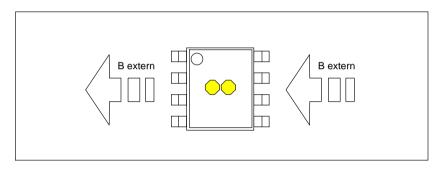


Figure 8: IMC position and geometry high-field version

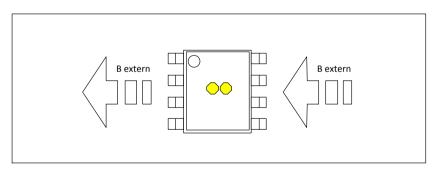


Figure 9: IMC position and geometry very high-field version



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