Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

General Description

The MAX20343 is an ultra-low quiescent current, noninverting buck-boost converter with 1A current capability at 3.5V intended for applications that require long run times while also demanding bursts of high current. The device employs a unique control algorithm which seamlessly transitions between buck, buck-boost, and boost modes, minimizing discontinuities and subharmonics in the output voltage ripple. The low 1.9V input voltage for startup allows users to power the device from a variety of sources, and the near-zero minimum operating voltage gives the user the ability to extract as much as possible from their energy source. The MAX20343 has also been designed to keep inductance and output capacitance requirements as low as possible for space-constrained applications.

The MAX20343 is ideal for power in optical sensor applications as well as for powering radios in low power, wide area network (LPWAN) applications since in both cases noise must be minimal and efficiency must be high. For instance, the small light-load output voltage ripple allows a photoplethysmography (PPG) system to operate at low LED currents without interference. Additionally, seamless transitions between operating modes enables the use of dynamic voltage scaling (DVS) to minimize headroom on the LED and to save power in such systems. In applications where a low-power-density battery must be buffered by a super-capacitor to provide large LPWAN type bursts of current, the ultra-low operating voltage of the MAX20343 allows the user to extract as much energy as possible from the super capacitor. The low output inductance/capacitance requirement allows a small total solution size. For example in PPG systems, this provides the flexibility to place the MAX20343 on a remote optical module if overcrowding on the main PCB is an issue.

The MAX20343 is available with a highly configurable I²C serial interface or as a single-pin-enabled fixed-programming version. See <u>Table 3</u> for specific device settings. The device operates over the -40°C to +85°C temperature range, is available in a 16-bump, 1.77mm x 2.01mm, 0.4mm pitch WLP package and a 12-pin, 2.50mm x 2.50mm, 0.5mm pitch FC2QFN package.

Benefits and Features

- Extend System Run Time
 - Ultra-Low, 3.5µA (typ) Quiescent Current
 - 250mW Output Power with 500mV Input Voltage
 - Dynamic Voltage Scaling (DVS)
- Low, Continuous Noise Profile
 - Eliminates Discontinuities Across Operating Voltage Range
 - Eliminates Post-Filtering LDO in Noise Sensitive Applications
- Adaptable Load Transient Response
 - Adjustable Peak Current for Optimal Performance in Each Application
 - Fast Load Transient Response Minimizes Settling
 Time
 - Optional Feedback Integrator
 - · Enable for up to 3.5W Output Power Capabilities
 - Disable for up to 3.2W Output Power and Faster Load Transient Settling Time
 - FAST Pin Pretriggers Load Response and Offers
 Improved Load Transient
- Flexible Control Options
 - I²C Interface with Status Interrupts
 - EN and Status Pins, Single-Resistor V_{OUT} Selection (RSEL)
 - See <u>Table 3</u> for specific device defaults
- Extended Operating Temperature from -40°C to +85°C
- Optimally Sized for Small Applications
 - 16-bump, 1.77mm x 2.01mm, 0.4mm Pitch WLP 12-pin, 2.50mm x 2.50mm, Side-Wettable, 0.5mm Pitch Flip-Chip QFN
 - Inductor/Capacitor Available in 0603/0402 Case Sizes

Applications

- Biometric Optical Sensing Including PPG
- LPWAN (LTE/NB-IoT, LTE/Cat-M1)
- IoT
- Industrial Sensors

Ordering Information appears at end of data sheet.



Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

Simplified Block Diagram



Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

Absolute Maximum Ratings

IN, OUT, SDA, SCL, EN, FA	ST, RSEL,
PGOOD, INGOOD, INT, C	CAP0.3V to +6.0V
LVLX	0.3V to V _{IN} + 0.3V
HVLX	0.3V to min(V _{OUT} + 0.3V, +6.0V)
Continuous Power Dissipatio	on (Multilaver Board.

 $T_A = +70^{\circ}C$) (4 x 4 Array 16-Ball, 1.77mm x 2.01mm, 0.4mm Pitch WLP) (derate 17.26mW/°C above +70°C)949.30mW Continuous Power Dissipation (Multilayer Board,

T _A = +70°C) (12-Pin, 2.50mm x 2.50mm,	, 0.5mm Pitch
FC2QFN) (derate 17.04mW/°C above +7	′0°C)936.97mW
Operating Temperature Range	40°C to +85°C
Junction Temperature	+150°C
Storage Temperature Range	40°C to +150°C
Soldering Temperature (reflow)	+260°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Package Information

PACKAGE TYPE: 16-BUMP WLP	PACKAGE TYPE: 16-BUMP WLP						
Package Code	W161C2+1						
Outline Number	<u>21-100328</u>						
Land Pattern Number	Refer to Application Note 1891						
THERMAL RESISTANCE, FOUR-LAYER BOARD:							
Junction to Ambient (θ_{JA})	57.93°C/W						

PACKAGE TYPE: 12-PIN FC2QFN						
Package Code	F122B2F+1					
Outline Number	21-100331					
Land Pattern Number	90-100130					
THERMAL RESISTANCE, FOUR-LAYER BOARD:						
Junction to Ambient (θ_{JA})	58.70°C/W					
Junction to Case (θ _{JC})	23.10°C/W					

For the latest package outline information and land patterns (footprints), go to <u>www.maximintegrated.com/packages</u>. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to www.maximintegrated.com/thermal-tutorial.

Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

Electrical Characteristics

 $(V_{IN} = +1.8V \text{ to } +5.5V, C_{IN} = 5\mu\text{F}, C_{OUT} = 8\mu\text{F}, T_{J} = -40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C}, \text{ unless otherwise noted. Typical values are at } T_{A} = +25^{\circ}\text{C}, V_{IN} = +3.7V, L = 1\mu\text{H}, \text{ Limits are } 100\% \text{ tested at } T_{A} = +25^{\circ}\text{C}.) \text{ (Note 1)}$

PARAMETER	SYMBOL		CONDITIONS	MIN	TYP	MAX	UNITS	
BUCK-BOOST								
Input Voltage Range	V _{IN_START}	Input voltage re	equired for startup (Note 2)	1.9		5.5	V	
Quiescent Supply	۱ _Q	No load,	V_{CAP} forced to V_{IN}		3.51	5	μA	
Current	IQ_FAST	V _{OUT} = 50, V _{IN} = 3.7V	FAST = 1		35		μA	
Shutdown Supply Current	ISHDN	I ² C controlled			0.3		μA	
		Integrator enabled,	BBstFETScale = 0, L = 1 μ H, C _{OUT} = 8 μ F	3.5				
		V _{IN} > 2.7V, V _{OUT} ≥ 3.2V	BBstFETScale = 1, L = 2.2μ H, C _{OUT} = 4μ F	1.75				
Maximum Output			BBstFETScale = 0, L = 1 μ H, C _{OUT} = 8 μ F, MAX20343B/E	2.8				
(Note 3)	P _{MAX}	Integrator disabled,	BBstFETScale = 0, L = 1 μ H, C _{OUT} = 8 μ F, All Other Versions	3.2			W	
		V _{IN} > 3.2V (Note 4), V _{OUT} ≥ 3.2V	BBstFETScale = 1, L = 2.2 μ H, C _{OUT} = 4 μ F, MAX20343B/E	1.6				
			BBstFETScale = 1, L = 2.2μ H, C _{OUT} = 4μ F, All Other Versions	1.75				
Output Voltage Set Range		50mV step resolution		2.5		5.5	1	
	V _{OUT}		V _{IN} < 2.1V, CAP forced to V _{OUT} (see Input Operating Voltage section), MAX20343B/E	3.3		5.5	V	
			V _{IN} < 2.1V, CAP forced to V _{OUT} (see Input Operating Voltage section), All other versions	3.2		5.5		
Average Output Voltage Accuracy	ACC_OUT	I _{OUT} = 1mA, C	-2.4		+2.4	%		
Line Regulation Error	V _{LINE_REG}			-1		+1	%/V	
		Integrator enabled, V_{IN} = 2.7V, V_{OUT} = 3.3V, BBstFETScale = 0, P_{OUT} = 3.5W			-1		~	
Load Regulation Error	VLOAD_REG	Integrator disabled, V_{IN} = 3.7V, V_{OUT} = 5V, P_{OUT} = 1.5W, BBstFETScale = 1, C_{OUT} = 4µF, L = 2.2µH			-3.2		%	
Line Transient Response	V _{LINE_TRAN}	V _{OUT} = 3.4V, V I _{LOAD} = 750m/	/ _{IN} from 3.4V to 2.9V, 1µs fall time, A, BBstIntegEn = 1, SwoFrcIN = 0		0		mV	
Load Transient Response	VLOAD_TRAN	V _{OUT} = 5V, V _{II} to 700mA, BBs	_N = 3.7V, I _{LOAD} = 10μA stIntegEn = 1		-150		mV	

Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

Electrical Characteristics (continued)

 $(V_{IN} = +1.8V \text{ to } +5.5V, C_{IN} = 5\mu\text{F}, C_{OUT} = 8\mu\text{F}, T_{J} = -40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C}, \text{ unless otherwise noted. Typical values are at } T_{A} = +25^{\circ}\text{C}, V_{IN} = +3.7V, L = 1\mu\text{H}, \text{ Limits are } 100\% \text{ tested at } T_{A} = +25^{\circ}\text{C}.) \text{ (Note 1)}$

PARAMETER	SYMBOL	C	ONDITIONS	MIN	TYP	MAX	UNITS
Input Supply Current During Startup	I _{IN_STUP}	V _{IN} = 3.6V, V _{OUT} =		1		mA/C _{OUT} (µF)	
		BBstFETScale = 0,	330	450			
Maximum Output Power During Startup (Note 3)	IPWR MAX	BBstFETScale = 0, All Other Versions			600		
	STUP	BBstFETScale = 1, MAX20343B/E			280		- mvv
		BBstFETScale = 1,	All Other Versions	200	300		
Startup Time	tetaptup	Time from V _{OUT} =	I ² C controlled		9.6		ms
	STARTUP	0V to final value	RSEL, BBstRampEn = 0		32		
PGOOD Threshold	V _{PGOOD}				84.7		%V _{OUT}
PGOOD Threshold Hysteresis	V _{PGOOD_HYS}				2.25		%V _{OUT}
Active Discharge Current	IACTD				20		mA
Passive Discharge Resistance	R _{PSVD}				1.2		kΩ
Input UVLO Rising Threshold	VIN_UVLO_R	V _{IN} rising	Soft-start active, CAP forced to V_{IN}, or V_{OUT} set below 3.3V		1.836		v
			V _{OUT} set higher than 3.3V, soft-start period complete		2.185		
Input UVLO Falling	Vin uvlo f	V _{IN} falling	Soft-start active, CAP forced to V_{IN}, or V_{OUT} set below 3.3V		1.782		v
Threshold			V _{OUT} set higher than 3.3V, soft-start period complete		2.101		-
Output UVLO Falling Threshold	V _{OUT_UVLO_F}	V _{OUT} falling			1.873		V
Output UVLO Rising Threshold	V _{OUT_UVLO_R}	V _{OUT} rising			1.963		V
DIGITAL							
SDA, EN, SCL, ĪNT, PGOOD, INGOOD FAST, RSEL Input Leakage Current	I _{LK_IO}	T _J = +25°C		-1		+1	μΑ
SDA, EN, SCL, FAST Input Logic High	V _{IO_IH}			1.4			V
SDA, EN, SCL, FAST Input Logic Low	V _{IO_IL}					0.4	V

Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

Electrical Characteristics (continued)

 $(V_{IN} = +1.8V \text{ to } +5.5V, C_{IN} = 5\mu\text{F}, C_{OUT} = 8\mu\text{F}, T_J = -40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C}, \text{ unless otherwise noted}.$ Typical values are at $T_A = +25^{\circ}\text{C}, V_{IN} = +3.7V, L = 1\mu\text{H}, \text{Limits are } 100\% \text{ tested at } T_A = +25^{\circ}\text{C}.)$ (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS
SDA, INT, PGOOD, INGOOD Output Logic Low	V _{IO_OL}	I _{OL} = 4mA			0.4	V
	f	MAX20343B/E	400		680	kH-
SCL Clock Frequency	ISCL	All Other Versions			680	KIIZ
Bus Free Time Between STOP and START Condition	^t BUF		0.75			μs
START Condition (Repeated) Hold Time	^t HD_STA	(Note 5)	0.35			μs
Low Period of SCL Clock	t _{LOW}		0.75		1.25	μs
High Period of SCL Clock	^t HIGH		0.35			μs
Setup Time for a Repeated START Condition	^t su_sta		0.35			μs
Data Hold Time	^t HD_DAT	(Note 6)	0		0.53	μs
Data Setup Time	t _{SU_DAT}		100			ns
Setup Time for STOP Condition	^t s∪_sto		0.35			μs
Spike Pulse Widths Suppressed by Input Filter	t _{SP}		50			ns

Note 1: All devices are 100% production tested at T_A = +25°C. Limits over the operating temperature range are guaranteed by design.

Note 2: Output power across the input operating voltage range is limited by input current. Refer to TOC03 for details on how the power limit changes with V_{IN}.

Note 3: The parameter is not production tested and values are generated through characterization only.

Note 4: Operation down to 2.7V is supported with the integrator disabled, but stability is only guaranteed up to 1.75W output power. Beyond 1.75W, oscillations could occur unless output capacitance is increased.

Note 5: f_{SCL} must meet the minimum clock low time plus the rise/fall times.

Note 6: The maximum t_{HD DAT} has to be met only if the device does not stretch the low period (t_{LOW}) of the SCL signal.

Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

Typical Operating Characteristics

 $(V_{IN} = +3.7V, C_{IN} = GRM155R60J226ME11, refer to Figure 9 single capacitor derating, C_{OUT} = 2x GRM155R60J226ME11, L = 1µH, BBstZCCmpDis = 0, BBstLowEMI = 0, BBstMode = 0, SwoFrcIN = 1, BBstIPAdptDis = 0, BBstFETScale = 0, T_A = +25°C, unless otherwise noted.)$



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Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

Typical Operating Characteristics (continued)

 $(V_{IN} = +3.7V, C_{IN} = GRM155R60J226ME11, refer to Figure 9 single capacitor derating, C_{OUT} = 2x GRM155R60J226ME11, L = 1µH, BBstZCCmpDis = 0, BBstLowEMI = 0, BBstMode = 0, SwoFrcIN = 1, BBstIPAdptDis = 0, BBstFETScale = 0, T_A = +25°C, unless otherwise noted.)$



Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

Typical Operating Characteristics (continued)

 $(V_{IN} = +3.7V, C_{IN} = GRM155R60J226ME11, refer to Figure 9 single capacitor derating, C_{OUT} = 2x GRM155R60J226ME11, L = 1µH, BBstZCCmpDis = 0, BBstLowEMI = 0, BBstMode = 0, SwoFrcIN = 1, BBstIPAdptDis = 0, BBstFETScale = 0, T_A = +25°C, unless otherwise noted.)$



Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

Typical Operating Characteristics (continued)

 $(V_{IN} = +3.7V, C_{IN} = GRM155R60J226ME11, refer to Figure 9 single capacitor derating, C_{OUT} = 2x GRM155R60J226ME11, L = 1\muH, BBstZCCmpDis = 0, BBstLowEMI = 0, BBstMode = 0, SwoFrcIN = 1, BBstIPAdptDis = 0, BBstFETScale = 0, T_A = +25°C, unless otherwise noted.)$



Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

Typical Operating Characteristics (continued) (VIN = +3.7V, CIN = GRM155R60J226ME11, refer to Figure 9 single capacitor derating, C_{OUT} = 2x GRM155R60J226ME11, L = 1µH, BBstZCCmpDis = 0, BBstLowEMI = 0, BBstMode = 0, SwoFrcIN = 1, BBstIPAdptDis = 0, BBstFETScale = 0, T_A = +25°C, unless otherwise noted.)















Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

Typical Operating Characteristics (continued) (VIN = +3.7V, CIN = GRM155R60J226ME11, refer to Figure 9 single capacitor derating, C_{OUT} = 2x GRM155R60J226ME11, L = 1µH, BBstZCCmpDis = 0, BBstLowEMI = 0, BBstMode = 0, SwoFrcIN = 1, BBstIPAdptDis = 0, BBstFETScale = 0, T_A = +25°C, unless otherwise noted.)









Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

Pin Configuration

I²C-Controlled WLP



I²C-Controlled FC2QFN



Single-Pin-Enabled WLP



Single-Pin-Enabled FC2QFN



Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

Pin Description

	PI	N						
l ² C- Controlled WLP	Single-Pin- Enabled WLP	l ² C- Controlled FC2QFN	Single-Pin- Enabled FC2QFN	NAME	FUNCTION			
A1	A1	1	1	CAP	Bypass Capacitor Connection for Internal Supply. Connect through 470nF of capacitance to GND.			
A2, B2, C2	A2, B2, C2	12	12	GND	Ground			
A3, A4	A3, A4	10, 11	10, 11	IN	Input Supply. Bypass to GND with effective capacitance equal to the minimum of 5μ F and the value of the derating curve (Figure 9) for a bias voltage V _{IN} placed as close to the device as possible.			
B1	B1	2	2	FAST*	Fast Transient Response. When FAST is high, the quiescent current of MAX20343 increases in order to improve response time to a load step. When FAST is low, the quiescent current is decreased to save power.			
B1	B1	2	2	RSEL*	Output Voltage Select. Connect a resistor from RSEL to GND based on the desired output voltage. See Figure 8.			
B3, B4	B3, B4	9	9	LVLX	Switching Node. Connect to HVLX through a 1µH inductor if BBstFETScale = 0 or a 2.2µH inductor if BBstFETScale = 1.			
C1	_	3	_	SCL	I ² C Serial Clock Input. For I ² C versions, note the BBstEn setting. If a version is disabled by default an externally supplied source must be used for the I ² C interface to enable the output by I ² C command.			
_	C1	_	3	INGOOD	Input Power Good. LOW indicates that the CAP pin voltage is forced to V _{OUT} and the input voltage is below V _{IN_UVLO_F} when V _{OUT} \geq 3.3V and the soft-start period is complete. Power capabilities might be limited. If CAP is forced to V _{IN} , INGOOD does not function when V _{IN} < V _{IN_UVLO_F} . It is an open drain output and should be connected to an external logic supply using a pullup resistor.			
C3, C4	C3, C4	8	8	HVLX	Switching Node. Connect to LVLX through a 1 μ H inductor if BBst-FETScale = 0 or a 2.2 μ H inductor if BBstFETScale = 1.			
D1		4	_	SDA	I ² C Serial Data Input/Open-Drain Output. For I ² C versions, note the BBstEn setting. If a version is disabled by default an externally supplied source must be used for the I ² C interface to enable the output by I ² C command.			
_	D1	_	4	EN	Enable. Active high.			
D2	_	5	_	ĪNT	Interrupt Output. Open-drain, connect through pullup resistor to system logic supply.			

*The function of B1 is determined by the factory configuration of the device. See FastRSEL in <u>Table 3</u> for the specific configuration of each device.

Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

	PI	N			
l ² C- Controlled WLP	Single-Pin- Enabled WLP	l ² C- Controlled FC2QFN	Single-Pin- Enabled FC2QFN	NAME	FUNCTION
_	D2	_	5	PGOOD	Power Good Output. Indicates when output is ready for use. It is an open drain output and should be connected to an external logic supply using a pullup resistor.
D3, D4	D3, D4	6, 7	6, 7	OUT	Buck-Boost Output. If BBstFETScale = 0, bypass to GND with effective capacitance equal to twice the value of the derating curve (Figure 9) for a bias voltage V_{OUT} , placed as close to the device as possible. If BBstFETScale = 1, bypass to GND with effective capacitance equal to the value of the derating curve (Figure 9) for a bias voltage V_{OUT} , placed as close to the device as possible.

Functional Diagram



Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

Detailed Description

The MAX20343 is an ultra-low quiescent current, noninverting buck-boost converter with 1A current capability at 3.5V intended for applications that require long run times while also demanding bursts of high current. A peak/valley current-controlled hysteretic architecture yields a fast transient response time with minimal settling time that allows the device to handle large load transients in high peak-power applications. The device has a unique control algorithm that seamlessly transitions between buck, buck-boost, and boost operation to minimize discontinuities and sub-harmonic noise in the output ripple.

The low, 1.9V startup voltage is compatible with a variety of power sources, and the near-zero minimum operating voltage extracts as much energy as possible from the source. Low inductance and capacitance requirements allow for a small total-solution size and make the MAX20343 well-suited for space-constrained applications. The device has a high efficiency and low noise that also makes it suitable for wireless and noise-sensitive applications such as LPWAN and optical sensor systems. It has an ultra-low, $3.5\mu A$ (typ) quiescent current and discontinuous conduction mode (DCM) to operate at low loads and extend run time in low average-power, batterypowered applications

Startup Voltage

The MAX20343 is guaranteed to start up with a minimum input voltage of 1.9V. After device startup, an internal bootstrapping function allows the device to operate to very low input voltages limited only by the amount of current that can be drawn effectively from the input. See the *Input Operating Voltage* section for more details.

Architectural Description

The MAX20343 buck-boost comprises a typical noninverting buck-boost topology. Figure 1 illustrates the



Figure 1. The Buck-Boost Regulator and Switching Phases

basic structure of the regulator with arrows depicting the inductor current flow in each switching phase.

Switching Phases

Depending on the register settings and input-to-output voltage relationship, the buck-boost sequences through the below switching phases in a particular order to deliver charge to the output. Only two switches are on in each phase.

- Phase 1: MP1 on, MP2 on. Inductor charges.
- Phase 2: MP1 on, MN2 on. Inductor charges.
- Phase 3: MN1 on, MP2 on. Inductor discharges.
- Phase 4: MN1 on, MN2 on. Freewheeling.

Buck-Boost Mode

When BBstMode = 0 (register 0x01[2]), the regulator operates in buck-boost mode. The inductor charges in Phase 2 up to BBstIPSet1 (register 0x03[3:0]). The buck-boost then transitions to Phase 1. If $V_{IN} > V_{OUT}$, the inductor continues charging until either the current reaches BBstIPSet1 + BBstIPSet2 (register 0x03[7:4]) or after a 500ns delay. If $V_{IN} \leq V_{OUT}$, the buck-boost waits for the 500ns timeout to elapse or until the current drops to the valley limit. Next, the regulator enters Phase 3 to discharge the inductor current to the valley limit. When the inductor current reaches the valley-current crossing threshold or falls below 0, the regulator freewheels in Phase 4 until the next charge phase. When operating in continuous conduction mode (CCM), the buck-boost enters Phase 4 for approximately 30ns if BBstZCCmpDis = 1 (register 0x01[4]). The buck-boost skips Phase 4 when operating in CCM and BBstZCCmpDis = 0. The valley behavior is determined by BBstZCCmpDis. Figure 2 shows the inductor current in buck-boost mode.



Figure 2. Buck-Boost Inductor Current in Buck-Boost Mode

Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

Buck-Only Mode

To maximize efficiency when $V_{IN} > V_{OUT}$, the buck-boost regulator has a buck-only mode. When BBstMode = 1, the regulator behaves as a synchronously rectified buck regulator. If the device is set to buck-only mode, the regulator never enters Phase 2. Instead, the inductor is always charged in Phase 1. The inductor charges until its current reaches BBstIPSet1 or the 500ns timeout elapses. The regulator then transitions to Phase 3 to provide a path to deliver the inductor current to the output. Figure 3 shows the inductor current in buck-only mode.

Buck-only mode reduces switching losses present in buck-boost mode. Buck-only mode should be used when V_{OUT} is always less than $V_{IN}.$

Inductor Peak and Valley Current Limits

The buck-boost regulator monitors the maximum and minimum values of the inductor current. If BBstIPAdptDis = 1 (register 0x04[1]), the peak currents are fixed to the values in BBstIPAdptDis (register 0x03) and the valley current is fixed to 0mA. If BBstAdptDis = 0, the peak and valley currents are allowed to change based on load requirements.

Peak currents are set in the BBstISet register. BBstIPSet1 controls the peak current when V_{IN} < V_{OUT} and begins the timeout period for Phase 1. BBstIPSet2 sets a secondary current limit in buck-boost mode when V_{IN} >

V_{OUT}. The total inductor current limit when V_{IN} > V_{OUT} is BBstIPSet1 + BBstIPSet2. The buck-boost regulator transitions from Phase 1 to Phase 3 if the inductor current reaches BBstIPSet1 + BBstIPSet2 or if the 500ns timeout has elapsed. Minimizing the difference between BBstIPSet1 and BBstIPSet2 reduces the output ripple, but decreases efficiency. Care must be taken to optimize the peak current settings to keep a low output ripple while maximizing efficiency. Figure 4 and Figure 5 present the safe operating area of BBstIPSet2 with respect to BBstIPSet1. Selecting values outside of the limits shown in Figure 4 and Figure 5 can cause unwanted behavior. Figure 6 and Figure 7 are graphical guides to selecting combinations of BBstPSet1 and BBstIPSet2 to balance efficiency and voltage ripple for specific BBstVSet values.

In order to control inrush current during startup, the MAX20343 forces discontinuous conduction mode during startup (valley current is always 0) and overrides the peak current settings with BBstIP1SS and BBstIP2SS. Once the output reaches its final voltage, continuous conduction mode is allowed and the BBstIPSet1 and BBstIPSet2 settings are restored. See BBstIP1SS and BBstIP2SS (Table 3) for device-specific values.

The MAX20343 behavior when BBstIPAdptDis = 0 can be further defined with a zero current comparator. The device transitions to Phase 4 when its control loop detects a zero current crossing.



Figure 3. Buck-Boost Inductor Current in Buck-Only Mode

Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator



Figure 4. Minimum BBstIPSet2 Limit for a Given BBstIPSet1 Setting for BBstFETScale = 0 (MAX20343B/E Only)



Figure 6. Recommended BBstIPSet1 and BBstIPSet2 Settings for BBstFETScale = 0 (MAX20343B/E Only)



Figure 5. Minimum BBstIPSet2 Limit for a Given BBstIPSet1 Setting for BBstFETScale = 1 (on MAX20343B/E, and for either BBstFETScale setting for all other versions)



Figure 7. Recommended BBstIPSet1 and BBstIPSet2 Settings for BBstFETScale = 1 (on MAX20343B/E, and for either BBstFETScale setting for all other versions)

When BBstZCCmpDis = 1 (register 0x01[4]), the zero crossing comparator is disabled and the buck-boost operates with only peak and valley current limits. In this configuration, the valley current limit acts as the zero crossing limit. In DCM, the valley limit is 0mA and is a true zero current crossing. In CCM, the peak and valley limits are automatically adjusted by the adaptive current control, so the effective zero current point might be larger than 0mA. This causes the MAX20343 to briefly enter Phase 4 each time the inductor current reaches the valley current threshold before transitioning to an inductor-charging phase. Setting BBstZCCmpDis = 0 enables the zero current comparator and the buck-boost operates with peak, valley, and zero crossing current limits. While the adaptive current loop adjusts the peak and valley currents, the zero crossing limit is fixed at 0mA. In DCM, the regulator functions similarly to when BBstZCCmpDis = 1. However, in CCM, the valley current is greater than the zero crossing current, so the regulator bypasses Phase 4 and directly enters an inductorcharging phase when the inductor current reaches the valley current threshold.

Disabling the zero current crossing comparator reduces the buck-boost output ripple. Enabling the comparator improves efficiency in CCM by removing the Phase 4 stage in CCM that is otherwise present when BBstZCCmpDis = 1.

Integrator Control Loop Disable

The MAX20343 contains an integrator in its control loop for normal operation. This integrator improves the load regulation for larger loads, but increases the transient response time. For applications where the output must quickly settle to a final regulation value to prevent noise injection during sensitive measurements (such as in PPG measurements), the integrator can be disabled so the regulator operates with a proportional-only control loop. The BBstIntegEn bit (register 0x04[2]) enables and disables the integrator to speed response time on load transients (integrator off) or to increase the load capacity (integrator on). Note that when the integrator is disabled output stability is only guaranteed up to the maximum output power for input voltages down to 2.5V. To operate at lower input voltages, the output capacitance must be increased.

Input Operating Voltage

Operating at low input voltages enables a system to extract as much energy as possible from its energy source before shutting down. After startup and with SwoFrcIn = 0, and $V_{OUT} \ge 3.3V$ (MAX20343B/E) or 3.2V (all other versions), the MAX20343 can operate to very low input voltages limited only by the amount of current that can be drawn effectively from the input. This allows

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a system to run the MAX20343 well below the minimum startup voltage, albeit at a reduced power capability.

When the input voltage is low, the R_{ON} of the input p-channel MOSFET increases. To offset the inherent increase in resistance, an n-channel MOSFET is present in parallel with the input MOSFET. The n-channel MOSFET is only enabled when the input voltage falls below V_{IN_UVLO_F} to reduce switching losses at higher input voltages. In order to provide sufficient overdrive for the n-channel device, it is necessary to keep V_{OUT} \geq 3.3V (MAX20343B/E) or 3.2V (all other versions). Therefore, high power operation below V_{IN_UVLO_F} is only guaranteed if the output voltage is set to 3.3V (MAX20343B/E) or 3.2V (all other versions) or above.

Output Operating Power and Other Optimizations

The MAX20343 is a highly flexible device with many operating modes that allows the user to optimize the performance for their application. For applications like driving an LED for on the wrist PPG, settling time to a steadystate voltage during a load transient is critical. In such cases, the user benefits from a proportional-only output response (BBstIntegEn = 0, disabled), which trades an increased steady-state load regulation error for speed of settling. On the other hand, some applications are not as sensitive to response time, but benefit from the lower steady-state load regulation error provided when the integrator is enabled (BBstIntegEn = 1, enabled).

The efficiency can also be optimized by selecting the BBstFETScale setting according to which load region should be the focus for efficiency. If the application should primarily be optimized for light-load efficiency, the BBstFETScale = 1 (enabled) setting is preferable and vice-versa. Note that the improvement in efficiency at light loads with BBstFETScale = 1 comes with the tradeoff of lower maximum output power, which should be a consideration when configuring the setting. A comparison of performances for each setting can be found in the *Typical Operating Characteristics* section.

Finally, the MAX20343 features an internal switchover circuit (configured by SwoFrcIN), which manages the supply from which the internal circuitry of the buck-boost is driven. For applications where quiescent current is important and the primary operating mode is to boost the output, the switchover should be forced to the input (SwoFrcIN = 1). This is because the quiescent current when SwoFrcIN = 0 is drawn from the output, meaning that the input current is increased by the boost ratio and the efficiency of the conversion. However, in cases where a low input operating voltage must be supported, the SwoFrcIN = 0 setting allows the input voltage to

drop much lower since the output voltage can be used to enhance the switching FETs of the buck-boost, keeping the on-resistance low. Note that when SwoFrcIN = 1, the buck-boost output automatically shuts down when VIN falls below VIN UVLO F (1.782V typ). Instead when SwoFrcIN = 0 and $\overline{V}_{OUT} \ge 3.3V$ (MAX20343B/E) or 3.2V (all other versions), the output continues to run even when VIN falls very low and is only disabled when the output voltage falls below VOUT UVIO F or when the user disables the device. In this operating mode, the output power capabilities begin to decrease as the input voltage falls. To indicate that the input voltage has fallen to a critical level, the device generates an In UVLO status and interrupt for the system, which means that V_{IN} has dropped below VIN UVIO F and the source might be in a critical state. A comparison of performances for each setting can be found in the Typical Operating Characteristics section.

For each combination of the above settings, there are tradeoffs to consider. <u>Table 2</u> below gives a general outline of the basic characteristics to expect with a given configuration.

Device Control

I²C-Controlled

The I²C-controlled versions of MAX20343 enable system flexibility by providing an interface between the device and a host microcontroller. Different parameters of the regulator, such as output voltage the inductor peak current levels, FET scaling, etc., can be optimized in real time for any application. While default values are programmed by the factory, new values can be set in the I²C registers. For device versions with I²C control take special care to observe the default setting of BBstEn in Table 3. Versions with BBstEn = disabled by default need to have another power supply present that allows the system to wake the buck-boost by I²C command. In versions of the MAX20343 with an I²C interface and an RSEL voltage selection pin, the default voltage selected by the RSEL resistor can be overwritten over I²C after the OutGood (register 0x05[1]) status goes high.

The full configuration settings and status information provided through this interface are detailed in the register descriptions. The slave address information for I²C-controlled versions of MAX20343 can be found in the *Applications Information* section.

Single-Pin-Enable

In the single-pin-enabled, fixed-programming versions of MAX20343, all configuration settings excluding the output voltage are programmed by the factory and cannot be

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modified in an application. Setting EN high turns on the regulator. Two status pins, INGOOD and PGOOD, signal that the input and output voltages are ready to support the full system power requirements, respectively.

When the FAST/RSEL pin of a single-pin-enabled MAX20343 is configured to RSEL, the output voltage is set by the the RSEL resistor at startup. When the FAST/RSEL pin is configured to FAST, the output voltage is set by the factory.

Dynamic Voltage Scaling (DVS)

The output voltage of I²C-controlled MAX20343 devices can be changed at any point while the device is enabled without restarting the device. This feature is known as dynamic voltage scaling. DVS enables systems to operate at different voltage rails when the voltage or power requirements of the system change in different operating modes. By decreasing the voltage to the minimum value required by an operating mode, the overall system efficiency increases. The output voltage is set in BBstVSet[5:0] (register 0x02[5:0]).

RSEL Voltage Setting

RSEL is a unique, single-resistor output voltage selection method that minimizes quiescent current. Once power is applied at V_{IN} and the enable pin is brought high, the MAX20343 starts up and regulates to the minimum programmable voltage (2.5V). Once an internal PGOOD signal indicates that the voltage has reached an acceptable level, the device begins drawing up to 200µA from V_{IN} in order to read the resistor value on RSEL. This current is only present during the RSEL resistor detection time, typically 750µs. After the detection and output voltage programming period, the output increases to the set value. The output rise time is determined by the BBstRampEn setting Figure 8 illustrates this startup sequence.

RSEL has many benefits, including lower cost and smaller size. Only one resistor is needed versus the two resistors required in typical feedback connections. Another benefit of RSEL is that one regulator can be used in multiple projects with different output voltages just by changing a single standard 1% resistor. Lastly, RSEL eliminates wasting current continuously through feedback resistors for ultra-low power, battery-operated products. Select the RSEL resistor value by choosing the desired output voltage in <u>Table 1</u>. Leaving RSEL open sets the output to the default voltage of the device (see <u>Table 3</u> for device configurations).

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Figure 8. MAX20343 RSEL Startup Sequence

Table 1. RSEL Selection Table

OUTPUT VOLTAGE (V)	STD RES 1% (kΩ)
Default	OPEN
2.5	590
2.7	422
3.0	301
3.2	210
3.3	150
3.4	105
3.5	75
3.6	53.6
3.7	37.4
3.8	26.7
4.0	18.7
4.2	13.3
4.5	9.31
5.0	6.65
5.5	SHORT

Table 2. Cha	Iracteris	tics and De	vice Settings					
			CHARACTERISTIC	S		DEV	/ICE SETTINGS	
DEVICE VERSION	MAX OUTPUT POWER (VIN = VOUT 2 3.2V) (W)	QUIESCENT CURRENT	OPTIMIZED FOR: STEADY- STATE LOAD REGULATION ERROR OR LOAD- TRANSIENT SETTLING TIME	EFFICIENCY OPTIMIZED CURRENT RANGE	INPUT OPERATING VOLTAGE < VIN_UVLO_F	BBSTFETSCALE	BBSTINTEGEN	SWOFRCIN
MAX20343B/E	≥ 2.8	INCREASED		Ğ	YES (V _{OUT} ≥ 3.3V)	c	c	c
ALL OTHER VERSIONS	≥ 3.2		SELLEING LIME	ビ り ビ	YES (VoυT ≥ 3.2V)	D	Ð	5
MAX20343B/E	≥ 2.8							
ALL OTHER VERSIONS	≥ 3.2	LOWEST	SETTLING TIME	HIGH	ON	0	0	~
MAX20343B/E	L (INCREASED	LOAD	(YES (Voυτ ≥ 3.3V)	c		C
ALL OTHER VERSIONS	3.5 2.5	MODE	REGULATION	НСН	YES (V _{OUT} ≥ 3.2V)	D		Ð
ALL VERSIONS	≥ 3.5	LOWEST	LOAD REGULATION	HIGH	ON	0	~	-
MAX20343B/E	≥ 1.6	INCREASED		LOW/	YES (VoυT ≥ 3.3V)		c	c
ALL OTHER VERSIONS	≥ 1.75		SELLEING LIME	MEDIUM	YES (V _{OUT} ≥ 3.2V)		Ð	5
MAX20343B/E	≥ 1.6							
ALL OTHER VERSIONS	≥ 1.75	LOWEST	SETTLING TIME	MEDIUM	ON	~	0	~
MAX20343B/E		INCREASED	LOAD	LOW/	YES (Voυτ ≥ 3.3V)			c
ALL OTHER VERSIONS	07.1 >	MODE	REGULATION	MEDIUM	YES (V _{OUT} ≥ 3.2V)	_	_	5
ALL OTHER VERSIONS	≥ 1.75	LOWEST	LOAD REGULATION	LOW/ MEDIUM	ON	Ţ	.	

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Register Map

MAX20343

AD- DRESS	NAME	MSB							LSB
USER									
0x00	ChipID[7:0]				Chipl	D[7:0]			
0x01	BBstCfg0[7:0]	BBstEn	BBstRa mpEn	BBstFast	BBstZC- CmpDis	BBst- LowEMI	BBst- Mode	BBstAct Dsc	BBstPsv Dsc
0x02	BBstVSet[7:0]	BBFHig	hSh[1:0]	BBstVSet[5:0]					
0x03	BBstlSet[7:0]		BBstIPSet2[3:0]				BBstIPS	Set1[3:0]	
0x04	BBstCfg1[7:0]	FstC- mpEn	PasThr- Mode	SwoFrcIN	_	-	BBstInt- egEn	BBstl- PAdptDis	BBstFET Scale
0x05	Status[7:0]	-	-	-	-	_	-	OutGood	InUVLO
0x06	Int[7:0]	_	_	-	_	-	-	Out- GoodInt	InUV- LOInt
0x07	Mask[7:0]	-	-	-	-	-	-	OutGood- IntM	InUV- LOIntM
0x50	LockMsk[7:0]	_	-	_	_	_	_	_	BBLck
0x51	LockUnlock[7:0]				PASSV	VD[7:0]			

Register Details

ChipID (0x00)

BIT	7	7 6 5 4 3 2 1 0							
Field		ChipID[7:0]							
Access Type		Read Only							
BITFIE	LD	BITS		DESCRIPTION					
ChipID		7:0	Chip	ChipID[7:0] indicates the version of the device in use.					

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BBstCfg0 (0x01)

BIT	7		(6	5	4	3	2	1	0
Field	BBstl	En	BBstRampEn BBstFast BBstZCC- mpDis BBstLowE- MI BBstMode BBstActDsc BBst						BBstPsvDsc	
Access Type	Write, F	Read	Write,	Read	Write, Read	Write, Read	Write, Read	Write, Read	Write, Read	Write, Read
BITFIEL	FIELD BITS DESCRIPTION									
BBstEn			7	Buck-Boost Enable 0 = Buck-boost disabled 1 = Buck-boost enabled						
BBstRampEn			6	Buck-Boost Ramp Enable 0 = Output voltage setting transition is performed without intermediate steps 1 = Output voltage setting increases are performed with a digital ramp of 50mV every 56					every 50µs	
BBstFast			5	Buck-Boost Pretrigger Mode Setting Increases the quiescent current of the buck-boost to improve output regulation during load transients. 0 = Normal, low quiescent current operation 1 = Fast response mode enabled. Quiescent current increased to 35µA (typ).					luring load	
BBstZCCmpDi	s		4	Buck-l when 0 = Er 1 = Di	Boost Zero-Cro BBstEn = 0 nabled sabled	ossing Compara	ator Disable. La	atched internall	y, it can only be	e changed
BBstLowEMI			3	Buck- Increa 0 = No 1 = Inc	Boost Low EMI uses the rise/fal prmal operation crease rise/fall	Mode I time of HVLX 1 time on HVLX/	/LVLX to reduce	e EMI, at the c	ost of efficiency	<i>I.</i>
BBstMode			2	Buck-Boost Operating Mode Configures the regulator to operate in buck-boost or buck-only mode. Latched internally, of only be changed while BBstEn = 0. 0 = Buck-boost mode 1 = Buck-only mode					iternally, can	
BBstActDsc			1	Buck-Boost Active Discharge Control 0 = Buck-boost not actively discharged 1 = Buck-boost actively discharged on shutdown						
BBstPsvDsc			0	Buck- 0 = Bu 1 = Bu	Boost Passive ick-boost not p ick-boost passi	Discharge Con assively discha ively discharge	trol arged d on shutdown			

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BBstVSet (0x02)

BIT	7	6	5	4	3	2	1	0		
Field	BBFH	lighSh[1:0]		BBstVSet[5:0]						
Access Type	Wr	ite, Read			Write,	Read				
BITFIE	LD	BITS			DESCR					
BBFHighSh		7:6	Buck-Boost f_{HIGH} Thresholds Selects the switching frequency threshold f_{HIGH} . If the buck-boost switching frequence exceeds the f_{HIGH} rising threshold, all the blocks are kept ON (I_Q is higher) until the frequency reaches the f_{HIGH} falling threshold. A small glitch on V_{OUT} can be present at the f_{HIGH} crossover. 00 = 25kHz rising / 6.125kHz falling 01 = 35kHz rising / 8.25kHz falling 10 = 50kHz rising / 12.5kHz falling 11 = 100kHz rising / 25kHz falling							
BBstVSet		5:0	Buck-Boost O 2.5V to 5.5V, 000000 = 2.5V 000001 = 2.58 ≥111100 = 5.50	output Voltage S Linear Scale, 5 V 5V	Setting 0mV incremen	ts				

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BBstlSet (0x03)

BIT	7	6	5 4 3 2 1 0 Set2[3:0] BBstIPSet1[3:0] BBstIPSet1[3:0] Vrite, Read Vrite, Read <td< th=""></td<>							
Field		BBstIPS	Set2[3:0]	et2[3:0] BBstlPSet1[3:0]						
Access Type		Write,	Read			Write,	Read			
BITFIE	LD	BITS			DESCR					
BBstIPSet2		7:4	Buck-Boost N See buck-bood (minimum t_{ON} OmA (minimum MAX20343B/I BBstFETScale 0000 = 0mA (i 0001 = 41.25r 1111 = 618.75 Recommende V _{OUT} ≤ 2.65V 2.65V < V _{OUT} 3.05V < V _{OUT} 3.60V < V _{OUT} 3.60V < V _{OUT} V _{OUT} > 4.35V BBstFETScale 0000 = 0mA (i 0001 = 25mA 1111 = 375mA Recommende V _{OUT} ≤ 2.65V 2.65V < V _{OUT} 3.05V < V _{OUT} 3.05V < V _{OUT} 3.05V < V _{OUT}	ominal Maximu (st operation set () to 618.75mA m t_{ON}) to 375m E: e = 0: minimum t_{ON}) mA SimA ed settings (: 577.50mA r ≤ 3.05V: 536.1 r ≤ 3.05V: 536.1 r ≤ 3.05V: 536.1 r ≤ 3.05V: 495n r ≤ 4.35V: 453.2 (: 412.50mA e = 1: minimum t_{ON}) A ed settings (: 250mA r ≤ 3.05V: 225n r ≤ 3.60V: 200n r ≤ 4.35V: 175n (: 150mA	Im Peak Curre ection for a des , linear scale, 4 nA, linear scale 25mA nA 75mA	nt Setting cription of the p 11.25mA increme , 25mA increme All other versi BBstFETScale 0000 = 0mA (i 0001 = 50mA 1111 = 750mA Recommende V _{OUT} \leq 2.65V 2.65V $<$ V _{OUT} 3.05V $<$ V _{OUT} 3.60V $<$ V _{OUT} 3.60V $<$ V _{OUT} 0001 = 25mA 1111 = 375mA Recommende V _{OUT} \leq 2.65V 2.65V $<$ V _{OUT} 3.05V $<$ V _{OUT}	beak current senents for BBstFents for BastFents for Bast	ttings. 0mA ETScale = 0. TScale = 1. (1) nA (1001) nA (1000) nA (0111) (1) (1) (1) (1) (1) (1) (1)		

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BITFIELD	BITS	DESC	RIPTION
		Buck-boost nominal peak current setting 1 Nominal peak current when charging induce operation section for a description of the p 618.75mA, linear scale, 41.25mA increment t_{ON}) to 375mA, linear scale, 25mA increment	ctor between V _{IN} and GND. See buck-boost beak current settings. 0mA (minimum t _{ON}) to nts for BBstFETScale = 0. 0mA (minimum ents for BBstFETScale = 1.
		MAX20343B/E: BBstFETScale = 0: 0000 = 0mA (minimum t _{ON}) 0001 = 41.25mA	All other versions: BBstFETScale = 0: 0000 = 0mA (minimum tON) 0001 = 50mA
		 1111 = 618.75mA	 1111 = 750mA
BBstIPSet1	3:0	Recommended settings $V_{OUT} \le 4.55V: 330mA$ $4.55V < V_{OUT} \le 4.90V: 412.50mA$ $4.90V < V_{OUT} \le 5.30V: 453.75mA$ $V_{OUT} > 5.3V: 495mA$ BBstFETScale = 1: $0000 = 0mA (minimum t_{ON})$ 0001 = 25mA 1111 = 375mA	Recommended settings $V_{OUT} \le 3.40V: 200mA (0100)$ $3.40V < V_{OUT} \le 3.80V: 250mA (0101)$ $3.80V < V_{OUT} \le 4.15V: 300mA (0110)$ $4.15V < V_{OUT} \le 4.55V: 350mA (0111)$ $4.55V < V_{OUT} \le 4.90V: 400mA (1000)$ $4.90V < V_{OUT} \le 5.30V: 450mA (1001)$ $V_{OUT} > 5.30V: 500mA (1010)$ BBstFETScale = 1: $0000 = 0mA (minimum t_{ON})$ 0001 = 25mA
		Recommended settings $V_{OUT} \le 3.40V: 100mA$ $3.40V < V_{OUT} \le 3.80V: 125mA$ $3.80V < V_{OUT} \le 4.15V: 150mA$ $4.15V < V_{OUT} \le 4.55V: 175mA$ $4.55V < V_{OUT} \le 4.90V: 200mA$ $4.90V < V_{OUT} \le 5.30V: 225mA$ $V_{OUT} \ge 5.30V: 250mA$	$\begin{split} &1111 = 375 \text{mA} \\ &\text{Recommended settings} \\ &V_{OUT} \leq 3.40 \text{V}: 100 \text{mA} (0100) \\ &3.40 \text{V} < V_{OUT} \leq 3.80 \text{V}: 125 \text{mA} (0101) \\ &3.80 \text{V} < V_{OUT} \leq 4.15 \text{V}: 150 \text{mA} (0110) \\ &4.15 \text{V} < V_{OUT} \leq 4.55 \text{V}: 175 \text{mA} (0111) \\ &4.55 \text{V} < V_{OUT} \leq 4.90 \text{V}: 200 \text{mA} (1000) \\ &4.90 \text{V} < V_{OUT} \leq 5.30 \text{V}: 225 \text{mA} (1001) \\ &V_{OUT} > 5.30 \text{V}: 250 \text{mA} (1010) \end{split}$

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BBstCfg1 (0x04)

BIT	7	6	5	4	3	2	1	0
Field	FstCmpE	n PasThr- Mode	SwoFrcIN	- - BBstIntegEn BBstIPAdpt- Dis BBst FETSc d - - Write, Read Write, Read				
Access Type	Write, Rea	ad Write, Read	Write, Read	-	_	Write, Read	Write, Read	Write, Read
BITFIE	LD	BITS			DESCR	IPTION		
FstCmpEn		7	FAST Compa The FAST mod 0 = FAST pin 1= FAST pin d	rator Enable de comparator is does not contro can set the dev	enabled by the ol FAST mode ice into FAST r	logical AND of mode	the FAST pin an	id FstCmpEn.
PasThrMode		6	Pass Through Mode Bypasses the regulator to connect V_{OUT} to V_{IN} . This can only be enabled when BBstEn = 0 (register 0x01). 0 = Pass Through Mode disabled 1 = Pass Through Mode enabled. Enable only when BBstEn = 0.					
SwoFrcIN		5	Force Switch-Over Controls how the device powers the internal circuitry. 0 = Switch-over supply forced to V _{OUT} when V _{OUT} > V _{OUT_UVLO_R} . 1 = Switch-over supply forced to V _{IN} .					
BBstIntegEn		2	Buck-Boost Ir The Integrato of load regula 0 = Integrator 1 = Integrator	ntegrator Enabl r can be disable tion error. Latcl disabled enabled	e ed to improve s hed internally, i	settling time on t can only be c	load transients hanged when E	s at the cost 3BstEn = 0.
BBstlPAdptDis		1	Adaptive Peak/Valley Current Adjustment Disable 0 = Enabled 1 = Disabled, peak current fixed to the values set by BBstIPSet1 and BBstIPSet2. Valley current is fixed to 0mA. This setting is equivalent to forcing discontinuous conduction mode and greatly diminishes the output power capability of the part. Generally this is not a recommended setting					stIPSet2. tinuous ie part.
BBstFETScale		0	 FET Scale Reduces FET sizes by a factor of 2. This setting can be used to optimize efficiency f lighter loads if it is acceptable to support lower maximum output power. If BBstFETScale = 0, the part requires a 1µH inductor and at least twice the derated capacitance in Figure 9. If BBstFETScale = 1, the part requires a 2.2µH inductor and at least the derated capacitance in Figure 9. Latched internally, it can only be change when BBstEn = 0. 0 = FET scaling disabled 1 = FET scaling enabled 					

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Status (0x05)

BIT	7	6	5	4	3	2	1	0
Field	-	-	-	-	-	-	OutGood	InUVLO
Access Type	Access Type –		-	-	-	-	Read Only	Read Only
BITFIE	LD	BITS	DESCRIPTION					
OutGood		1	Status of Output Voltage 0 = Output has not reached full power capability 1 = Output voltage is high enough to support full power capability					
InUVLO		0	Status register showing whether input voltage is low enough to enable parallel input NMOS. $0 = V_{IN}$ high enough for full power operation 1 = Power may be limited due to low V _{IN}					

Int (0x06)

BIT	7	6	5	4	3	2	1	0
Field	-	-	-	-	-	-	OutGoodInt	InUVLOInt
Access Type	-	-	-	-	-	-	Read Only	Read Only
BITFIE	LD	BITS	DESCRIPTION					
OutGoodInt		1	Change in OutGood caused an interrupt					
Outobouint		•	enange in ee		an intoirapt			

Mask (0x07)

BIT	7	6	5	4	3	2	1	0
Field	_	-	-	-	-	-	OutGood- IntM	InUVLOIntM
Access Type	_	-	Write,					Write, Read
BITFIEI	LD	BITS	DESCRIPTION					
OutGoodIntM		1	OutGoodIntM masks the OutGoodInt interrupt. 0 = Not masked 1 = Masked					
InUVLOIntM		0	InUVLOIntM masks the InUVLOInt interrupt. 0 = Not masked 1 = Masked					

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LockMsk (0x50)

BIT	7	6	5	4	3	2	1	0
Field	-	-	-	-	-	-	-	BBLck
Access Type	-	-	-	-	-	-	-	Write, Read
BITFIE	LD	BITS	DESCRIPTION					
BBLck		0	Lock Mask for Buck-Boost Registers 0 = Buck-Boost Registers not masked from locking/unlocking 1 = Buck-Boost Registers masked from locking/unlocking					

LockUnlock (0x51)

BIT	7	6	5	4	3	2	1	0	
Field			PASSWD[7:0]						
Access Type			Write, Read						
BITFIEI	LD	BITS	DESCRIPTION						
PASSWD		7:0	Lock/Unlock Password Write 0xAA with BBLck unmasked to lock the BBstVSet[5:0] field Write 0x55 with BBLck unmasked to unlock the BBstVSet[5:0] field						

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Applications Information

Input and Output Capacitance

The MAX20343 is designed to be compatible with small case-size ceramic capacitors. As such, the device has low-input and low-output capacitance requirements to accommodate the steep voltage derating of 0603 and 0402 (imperial) capacitors. The sample derating curve in Figure 9 presents the minimum capacitance required at IN and OUT. To ensure stability and low noise, the capacitance on IN should be the minimum of 5µF and the value of Figure 9 at the lowest expected V_{IN}. The capacitance on OUT should be equal to the value of Figure 9 at the highest expected V_{OUT} for BBstFETScale = 1 and twice that value for BBstFETScale = 0.

Inductor Selection

Inductor selection for the MAX20343 should be optimized for the intended application. A 2.2 μ H inductor value is required when FET scaling is enabled (BBstFETScale = 1) while 1 μ H is required when FET scaling is disabled (BBstFETScale = 0). Aside from the inductor value physical size, DC resistance (DCR), maximum average current, and saturation current are the primary factors to consider. The maximum average inductor current is obtained using the following equation:

$$I_{L_MAX} = \frac{V_{OUT_MAX} \times I_{OUT_MAX}}{\eta \times V_{IN_MIN}}$$

where,

V_{OUT MAX} = Maximum expected operating voltage,

IOUT MAX = Maximum expected output current,

V_{IN MIN} = Minimum expected operating input voltage,

 η = Expected worst-case efficiency in the minimum input voltage and maximum output power case (see the <u>Typical</u> Operating Characteristics for help in estimating efficiency).

The average inductor current calculated above dictates the required maximum average current for temperature rise on the inductor. In order to determine the required inductor



Figure 9. Capacitor Derating for Input and Output Capacitance

saturation current, the peak current must be calculated. The peak current for this converter can be calculated as:

where BBstIPSet1 is the peak current setting described in register 0x03.Then selecting an inductor, one primary factor in achieving high efficiency is the DCR of the inductor. For maximum efficiency, select an inductor with the lowest DCR possible in the required package size. Another factor to consider is magnetic losses. Generally magnetic losses are lower in inductors with larger physical size and/or higher saturation current ratings. In most cases, ferrite inductors should be avoided as they tend to exhibit poor AC characteristics, especially in discontinuous conduction mode (DCM).

I²C Interface

The MAX20343 contains an I²C-compatible interface for data communication with a host controller (SCL and SDA). On MAX20343B/E interface requires a minimum 400kHz clock frequency and supports frequencies up to 680kHz. All other versions of the MAX20343 can support I²C frequencies from 0kHz to 680kHz. SCL and SDA require pullup resistors that are connected to a positive supply.

Slave Address

The MAX20343B/E 7-bit slave address is 0b0101000 (0x28) plus the Read/Write bit. Set the Read/Write bit high to configure the MAX20343B/E to read mode (0x51). Set the Read/Write bit low to configure the MAX20343B/E to write mode (0x50). For all other versions of the MAX20343, the slave address is configured at the factory by the SlaveAddr bit to be either 0b1101000 (0x68) plus the Read/Write bit or 0b1101100 (0x6C) plus the Read/Write bit. For versions with the 7-bit slave address 0x68 Set the Read/Write bit high to configure the MAX20343 to read mode (0xD1) or set the Read/Write bit low to configure the MAX20343 to write mode (0xD0). For versions with the 7-bit slave address 0x6C Set the Read/Write bit high to configure the MAX20343 to read mode (0xD8) or set the Read/Write bit low to configure the MAX20343 to write mode (0xD9). See SlaveAddr in Table 3 for the slave address for a given part number. The address is the first byte of information sent to the MAX20343 after the START condition.

Start, Stop, and Repeated Start Conditions

When writing to the MAX20343 using I^2C , the master sends a START condition (S) followed by the MAX20343 I^2C write address. After the address, the master sends the register address of the register that is to be programmed. The master then ends communication by issuing a STOP condition (P) to relinquish control of the bus, or a REPEATED START condition (Sr) to communicate to another I^2C slave. See Figure 10.

Bit Transfer

One data bit is transferred on the rising edge of each SCL clock cycle. The data on SDA must remain stable during the high period of the SCL clock pulse. Changes in SDA

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while SCL is high and stable are considered control signals (see the <u>Start, Stop, and Repeated Start Conditions</u> section). Both SDA and SCL remain high when the bus is not active.

Single-Byte Write

In this operation, the master sends an address and two data bytes to the slave device (Figure 11). The following procedure describes the single byte write operation:

- The master sends a START condition.
- The master sends the 7-bit slave address plus a write bit (low).
- The addressed slave asserts an ACK on the data line.
- The master sends the 8-bit register address.
- The slave asserts an ACK on the data line only if the address is valid (NACK if not).
- The master sends 8 data bits.
- The slave asserts an ACK on the data line.
- The master generates a STOP condition.



Figure 10. I²C START, STOP, and REPEATED START Conditions



Figure 11. Write Byte Sequence

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Burst Write

In this operation, the master sends an address and multiple data bytes to the slave device (Figure 12). The slave device automatically increments the register address after each data byte is sent, unless the register being accessed is 0x00, in which case the register address remains the same. The following procedure describes the burst write operation:

- The master sends a START condition.
- The master sends the 7-bit slave address plus a write bit (low).
- The addressed slave asserts an ACK on the data line.
- The master sends the 8-bit register address.
- The slave asserts an ACK on the data line only if the address is valid (NACK if not).
- The master sends 8 data bits.
- The slave asserts an ACK on the data line.
- Repeat 6 and 7 N-1 times.
- The master generates a STOP condition.

Single Byte Read

In this operation, the master sends an address plus two data bytes and receives one data byte from the slave device (Figure 13). The following procedure describes the single byte read operation:

- The master sends a START condition.
- The master sends the 7-bit slave address plus a write bit (low).
- The addressed slave asserts an ACK on the data line.
- The master sends the 8-bit register address.
- The slave asserts an ACK on the data line only if the address is valid (NACK if not).
- The master sends a REPEATED START condition.
- The master sends the 7-bit slave address plus a read bit (high).
- The addressed slave asserts an ACK on the data line.
- The slave sends 8 data bits.
- The master asserts a NACK on the data line.
- The master generates a STOP condition.



Figure 12. Burst Write Sequence



Figure 13. Read Byte Sequence

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Burst Read

In this operation, the master sends an address plus two data bytes and receives multiple data bytes from the slave device (Figure 14). The following procedure describes the burst byte read operation:

- The master sends a START condition.
- The master sends the 7-bit slave address plus a write bit (low).
- The addressed slave asserts an ACK on the data line.
- The master sends the 8-bit register address.
- The slave asserts an ACK on the data line only if the address is valid (NACK if not).
- The master sends a REPEATED START condition.
- The master sends the 7-bit slave address plus a read bit (high).
- The slave asserts an ACK on the data line.

- The slave sends 8 data bits.
- The master asserts an ACK on the data line.
- Repeat 9 and 10 N-2 times.
- The slave sends the last 8 data bits.
- The master asserts a NACK on the data line.
- The master generates a STOP condition.

Acknowledge Bits

Data transfers are acknowledged with an acknowledge bit (ACK) or a not-acknowledge bit (NACK). Both the master and the MAX20343 generate ACK bits. To generate an ACK, pull SDA low before the rising edge of the ninth clock pulse and hold it low during the high period of the ninth clock pulse (Figure 15). To generate a NACK, leave SDA high before the rising edge of the ninth clock pulse and leave it high for the duration of the ninth clock pulse. Monitoring for NACK bits allows for detection of unsuccessful data transfers.



Figure 14. Burst Read Sequence



Figure 15. Acknowledge Bits

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Table 3. Register Bit Default Values

		DEV	/ICE	
REGISTER BITS	MAX20343B	MAX20343E	MAX20343F	MAX20343G
BBstEn	Disabled	Disabled	Enabled	Disabled
BBstRampEn	Single Step	Single Step	Single Step	Single Step
BBstFast	Low I _Q Mode	Low I _Q Mode	Low I _Q Mode	Low I _Q Mode
BBstZCCmpDis	ZCC Disabled	ZCC Disabled	ZCC Disabled	ZCC Disabled
BBstLowEMI	High Efficiency	High Efficiency	High Efficiency	High Efficiency
BBstMode	Buck-Boost	Buck-Boost	Buck-Boost	Buck-Boost
BBstActDsc	Active Discharge on Shutdown (50ms)	Active Discharge on Shutdown (50ms)	Active Discharge on Shutdown (50ms)	Active Discharge on Shutdown (50ms)
BBstPsvDsc	Passive Discharge in Shutdown	Passive Discharge in Shutdown	Passive Discharge in Shutdown	Passive Discharge in Shutdown
BBstFHighSh[1:0]	100kHz/25kHz	100kHz/25kHz	100kHz/25kHz	100kHz/25kHz
SwoFrcIN	Switch-Over Forced to V _{OUT} when OutGood = 1	Switch-Over Forced to V _{IN}	Switch-Over Forced to V _{OUT} when OutGood = 1	Switch-Over Forced to V _{OUT} when OutGood = 1
BBstVSet[5:0]	3.20V	5.00V	3.30V	3.20V
BBstIntegEn	Disable Integrator	Disable Integrator	Enable Integrator	Disable Integrator
BBstIPAdptDis	Adaptive Peak Current Enabled	Adaptive Peak Current Enabled	Adaptive Peak Current Enabled	Adaptive Peak Current Enabled
BBstFETScale	FET Scaling Enabled	FET Scaling Enabled	FET Scaling Disabled	FET Scaling Enabled
FastRSELMode	FAST	FAST	FAST	FAST
EnI2CMode	I ² C Control	I ² C Control	I ² C Control	I ² C Control
BBstIPSet1[3:0]	100mA	225mA	400mA	100mA
BBstIPSet2[3:0]	BBstIPSet1 + 200mA	BBstIPSet1 + 150mA	BBstIPSet1 + 600mA	BBstIPSet1 + 200mA
BBstIP1SS[3:0]	375mA	375mA	750mA	375mA
BBstIP2SS[3:0]	BBstIPSet1 + 75mA	BBstIPSet1 + 75mA	BBstIPSet1 + 150mA	BBstIPSet1 + 75mA
Slave_Addr	0x50/0x51	0x50/0x51	0xD0/0xD1	0xD0/0xD1

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Table 4. Register Default Values

REGISTER	NAME	DEVICE			
		MAX20343B	MAX20343E	MAX20343F	MAX20343G
0x00	ChipID	0x01	0x01	0x01	0x02
0x01	BBstCfg0	0x13	0x13	0x93	0x13
0x02	BBstVSet	0xCE	0xF2	0xD0	0xCE
0x03	BBstlSet	0x84	0x69	0xC8	0x84
0x04	BBstCfg1	0x81	0xA1	0x84	0x81
0x05	Status	0x00	0x00	0x02	0x00
0x06	Int	0x00	0x00	0x00	0x00
0x07	Mask	0x03	0x03	0x03	0x03
0x50	LockMsk	0x01	0x01	0x01	0x01
0x51	LockUnlock	0xFF	0xFF	0xFF	0xFF

Typical Application Circuits

Optical Heart Rate LED Supply



Ultra-Low Quiescent Current, Low Noise 3.5W Buck-Boost Regulator

Typical Application Circuits (continued)

LPWAN Radio Supply



Ordering Information

PART NUMBER	TEMP RANGE	PIN-PACKAGE
MAX20343BEFC+*	-40°C to +85°C	12 FC2QFN
MAX20343BEFC+T*	-40°C to +85°C	12 FC2QFN
MAX20343EEFC+*	-40°C to +85°C	12 FC2QFN
MAX20343EEFC+T*	-40°C to +85°C	12 FC2QFN
MAX20343GEFC+*	-40°C to +85°C	12 FC2QFN
MAX20343GEFC+T*	-40°C to +85°C	12 FC2QFN
MAX20343BEWE+	-40°C to +85°C	16 WLP
MAX20343BEWE+T	-40°C to +85°C	16 WLP
MAX20343EEWE+	-40°C to +85°C	16 WLP
MAX20343EEWE+T	-40°C to +85°C	16 WLP
MAX20343FEWE+ *	-40°C to +85°C	16 WLP
MAX20343FEWE+T *	-40°C to +85°C	16 WLP
MAX20343GEWE+	-40°C to +85°C	16 WLP
MAX20343GEWE+T	-40°C to +85°C	16 WLP

+ Denotes a lead(Pb)-free/RoHS-compliant package.

T = Tape-and-reel.

*Future product—contact factory for availability.

See $\underline{\text{Table 3}}$ for specific device settings and defaults to select a part.

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Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	3/19	Initial release	_
1	3/19	Corrected typos; updated BBstFETScale Bit Description (and corrected typo), and added future product designation to MAX20343EEWE+ and MAX20343EEWE+T	19, 21, 25, 34
2	4/19	Updated the General Description, Benefits and Features, Absolute Maximum Ratings, Package Information, Pin Configuration, Pin Description, Buck-Boost Mode and Inductor Peak and Valley Current Limits sections, and Register Map and BBstCfg0 (0x01) tables; added MAX20343BEFC+ and MAX20343BEFC+T as future parts to the Ordering Information table	1, 3, 12–13 16, 18, 20–21, 34
3	6/19	Removed future part designation from MAX20343EEWE+ and MAX20343EEWE+T in the <i>Ordering Information</i> table	34
4	1/20	Updated the General Description, Benefits and Features, Electrical Characteristics, Typical Operating Characteristics, Pin Description, Startup Voltage, Architectural Design, Switching Phases, Buck-Boost Mode, Buck-Only Mode, Inductor Peak and Valley Current Limits, Integrator Control Loop Disable, Input Operating Voltage, I ² C-Controlled, Input and Output Capacitance, I ² C Interface, Slave Address, and Ordering Information sections; updated the Simplified Block Diagram, Pin Configurations, Functional Diagrams, Figures 4–Figure 7, Table 1, BBstlSet (0x03), BBstCfg1 (0x04), and Table 4; replaced Table 3; added the Inductor Selection and Output Operating Power and Other Optimization sections	1–2, 4–20, 23–25, 28, 32, 34
4.1		Corrected typo	1

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