

金龙机电股份有限公司

JINLONG MACHINERY & ELECTRONICS

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规格书

SPECIFICATION

	客户名称/Customer	
客户	客户料号/Part No.	
信	客户承认签章	
息	Customer Approved	
	Signatures	

文件编号/Spec No.				
品名/Description	圆柱直流马达/Cylindrical DC motor			
型号/Part No.	Z30C1B839981A			
设计/Designed	审核/Checked	批准/Approved		
的梦桃	F45 3	v stage a		
2015.05.25	2017.05.25	2017.05.25		

KOTL

MATERIAL or METHODS Specification

NO. Z3OC1B839981A

TITLE: Motor, Vibrator, 3.0 Volts, 12000 RPM, 12.5x6.50x3.35mm Flat, SMD

DATE: Dec-20- 16

MEMO: **SN0408000**

408000 ISSUE: 02

PAGE: 1 of 15

Date	Originator	Version		Description of changes			
Dec.20.16	S.Liang	01		Initial	Spec	Release	
May.25.17	S.Liang	02	Colanari	ty with respect	t to A as sta	ndard B&C&D tole	rance changed
Jinlong Mac	Jinlong Machinery & Electronics Co.,Ltd			Approval	Exam	Check	Design
	Jinlong Technology Zone, Jingang Road,						Designer
Baixiang Yue	Baixiang Yueqing Zhejiang China						2017.05.25 SHUAI.L

KOTL MATERIA	L or METHODS Spe	ecification	NO . Z3OC1B839981A				
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Preface:

Thank you very much for your selecting the KOTL Z3OC1B839981A vibrator. Our products have stable performance. To obtain maximum performance from the product, please read this specification first, and keep it handy for future reference.

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This document contains specific electrical and mechanical characters, critical characteristics, reliability tests, packaging condition, guality assurance, reflow profile and etc..

> Horizontal 3.0 V

2.3-3.6V

85 mA Max 100 mA Max

30.0±5.0Ω

12000±2500 rpm

C.W. & C.C.W

70 ms Max

0.20 G Min

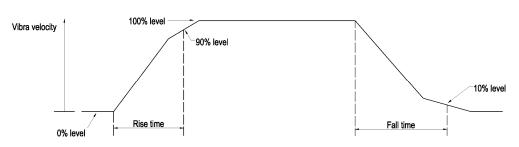
at 100V DC, 1MΩ Min and above

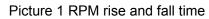
2. MECHANICAL CHARACTERISTIC

- 2.1. Mechanical drawing See appendix 2 2.2. Axial play of shaft 0.3 mm Max 2.3. Counter weight density: 17.0 g / cc Min
- 2.4. Mechanical noise of motor operating at rated speed: 45 dB Max A-weighting Background noise 26dB. (Measured distance 10 cm, see appendix 1 Figure 1.1).

3. **ELECTRICAL CHARACTERISTICS**

- 3.1. Vibrator positioning:
- 3.2. Operating voltage:
- 3.3. Operating voltage range:
- 3.4. Load current at operating voltage:
- 3.5. Starting current at operating voltage:
- 3.6. Insulation resistance and voltage break down:
- 3.7. Terminal resistance:
- 3.8. Load speed:
- 3.9. Rotation direction:
- 3.10. Motor vibration Force:
 - (The G-force is 0.20G min when the motor is under the loading of 100g at rated voltage, see appendix 1 Figure 1.2) 100 ms Max
- 3.11. Rise time (see picture 1)
- 3.12. Rree Fall time (see picture 1)
 - -From zero to 90% of nominal speed
 - -From nominal velocity to 10% of nominal speed





3.13 Standard loaded starting voltage: Under standard loaded condition, towards C.W. rotor shall

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move in all position at 2.3V (counterweight should be turned slowly at 360°)

All mechanical and electrical measurements should measured at room temperature and ordinary humidity.

0.75g

30N Min

4. ADDITIONAL INFORMATION

- 4.1. Vibrator weight
- 4.2. Pull out strength of counter weight and shaft

4.3. Acceleration level at nominal RPM (Grms) (test jig mounted in freely suspended)

4.4. Speed and current variation (function of temperature, -20°C to +70°C)

5. CRITICAL CHARACTERISTICS

- 5.1. Functional dimensions
- 5.2. Rated current at specified rotating speed
- 5.3. Operating speed at operating voltage
- 5.4. Starting current at operating voltage
- 5.5. Min. starting Voltage

6. ENVIRONMENTAL CHARACTERISTICS

6.1. Operating temperature ranges:	-20°C to +70°C
6.2. Storage temperature ranges:	-40°C to +85°C

7. RELIABILITY TESTS

7.1 We have already performed reliability tests and measure nom rotation speed, nom load current, nom resistance, nom starting currents and nom starting voltage before and after tests, please check following table1 for detail reliability test information. Each test we use at least 10 samples for verification.

	Items	Test conditions	Judgment
7.2	Low temperature storage test	Storage test -40±3°C/96h, recovery 1~2h Measurements with test jig.	No mechanical damage. Normal performance of vibrator. (Max +/-30% variation of nom RPM)

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Motor, Vibrator, 3.0 Volts, 12000 RPM, 12.5x6.50x3.35mm Flat, SMD TITLE: DATE: Dec-20- 16 SN0408000 PAGE: 6 of 15 ISSUE: **02** MEMO: 7.3 Storage test No mechanical damage. High $80\pm3^{\circ}C/96h$, recovery $1\sim2h$ temperature Normal performance of Measurements with test jig. storage test vibrator. (Max +/-30% variation of nom RPM) 7.4 Temperature Storage test No mechanical damage. cyclic test Temperature & humidity: +80±3°C/6h(RH85%); Reduced performance of -40±3°C/6h with 6h maximum transition time vibrator. between temperatures. 24h/cycles, totally 6 cycles. (Max +/-30% variation of Recovery 1~2h. Performance check daily. nom RPM) Measurements with test jig. (1 cycle) performance check 80±3℃ 85%RH 25±5℃ 50%RH -40±3℃ зн | 6H 6H 6H 3H 1~2H time 7.5 Thermal shock Storage test No mechanical damage. Temperature & humidity: -40±3°C/30minutes; test Normal performance of +85±3°C/30minutes with a 20sec maximum vibrator. transition time between temperatures. (Max +/-30% variation of 1h/cycle, totally 50 cycles. nom RPM) Recovery 1~2h. Measurements with test jig. (1 cycle) **85±3℃** -40±3℃ 30minutes 20sec 30min. 20sec time 7.6 Operational test: apply operating voltage No mechanical damage. Room temperature Temperature & humidity: 25±3°C, RH 50% After 100,000cycles: lifetime test On/off time: 2.5s on/off, 300,000 cycles. Normal performance of Performance check: before, after test and every vibrator. (Max +/-30% 20,000 cycles. variation of nom RPM) Recovery 1-2h. Measurements with test jig. After 300,000cycles: The vibrator should operate.

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7.7	High temperature lifetime test	Tempe On/off Perforr 20,000	erational test: apply operating voltage operature : 55±3°C off time: 2.5s on/off, 53,000 cycles. formance check: before, after test and every 000 cycles. overy 1~2h. Measurements with test jig.				No mechanical damage. Normal performance of vibrator. (Max +/-30% variation of nom RPM)	
7.8	Low temperature lifetime test	Tempe On/off Perforr 20,000	Dperational test: apply operating voltage Temperature : -20±3°C Dn/off time:2.5s on/off, 53,000 cycles. Performance check: before, after test and every 20,000 cycles. Recovery 1~2h. Measurements with test jig.				-	No mechanical damage. Normal performance of vibrator. (Max +/-30% variation of nom RPM)
7.9	H ₂ S corrosion test	Conce Tempe	Storage test Concentration: 3±1ppm Temperature & humidity: 40±3°C, RH 80% Exposure time: 24hours				No mechanical damage. Normal performance of vibrator. (Max +/-30% variation of nom RPM)	
7.10	Free Fall	weight times i	ount the vibrator in the dummy box.(dummy box hight 100g), Drop height 1.5 m onto concrete. 3 hes in each 6 directions. easurements with test jig.				No mechanical damage. Normal performance of vibrator. (Max +/-30% variation of nom RPM)	
7.11	Random vibration test		10minutes per axis, 6.06Grms quency (Hz) A.S.D.(G²/Hz) 20 0.0098 80 0.04 350 0.04 2000 0.0069 rements with test jig.			No mechanical damage. Normal performance of vibrator. (Max +/-30% variation of nom RPM)		
7.12	Shock test	Time c directic Accele	of test and direction: 3times in each 6 ion. Total 18 times. eration: Half-sinusoidal 500G ion:2ms				No mechanical damage. Normal performance of vibrator. (Max +/-30% variation of nom RPM)	

Table1 Reliability test

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. EXPECTED SHIPPING AND	STORAGE CONDITIONS			
8.1. Relative humidity	15%	%~70%		
8.2. Temperature	-5°(C~40°C		
8.3. Sulphur dioxide average		mg/m ³		
8.4. Sulphuretted hydrogen ave	erage 0.1	mg/ m ³		
8.5. Storage period	12	months		
(Vibrator has to be rotate	d at least once within 12 m	onths from the date	e of receipt)	
. QUALITY ASSURANCE				
	ning Out-going inspection o	lata sheet (n=35pc	s)	
Inspection item: Load speed Load current				
	g current g voltage			
•	sistance			
- Customer reject material ra				
- Customer satisfaction				
- Cpk/Cp control for all critica	al narameters (excent start	ing voltage)		
		ing voltage/		
IO. MATERIALS				
- Counterweight				
- Brush				
- Commutator				
- Case				

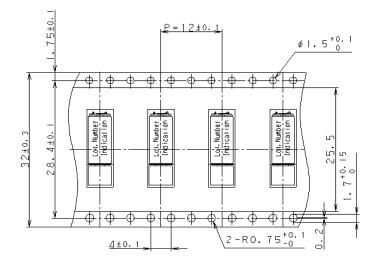
- Terminal
- Bracket
- Washer
- End cover
- Bearing
- Magnet
- Copper wire
- Shaft
- Core
- Varistor

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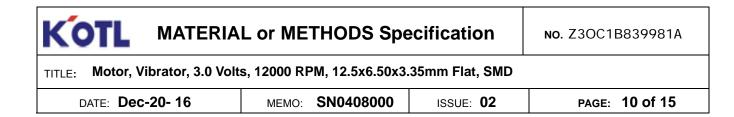
P.S.: All the materials included in vibrator can meet 2002/95/EC & KOTL RoHS requirement KOTL-III-TD-001.

11. PACKAGING CONDITION

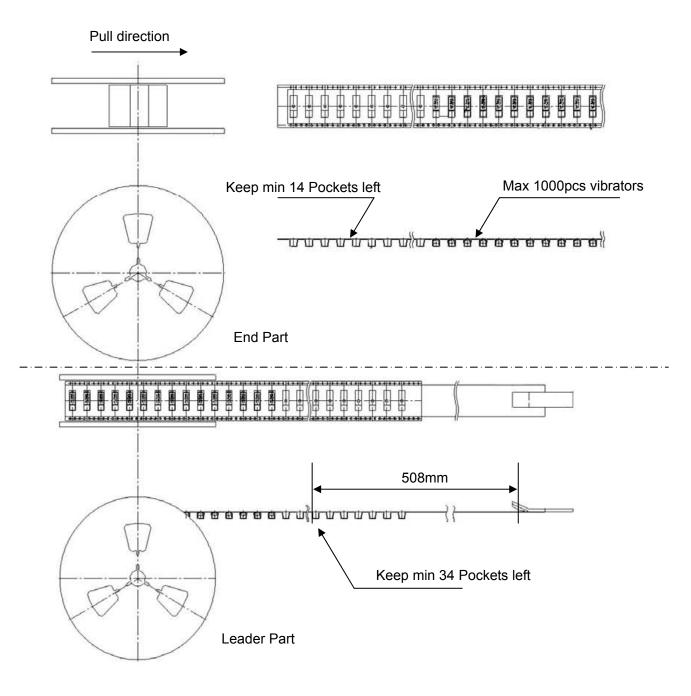
A detailed mechanical drawing for packing condition as followed with dimensions and tolerances: 12.1 Smallest packing



Picture 3 Smallest packing condition



11.2 Reel packing condition

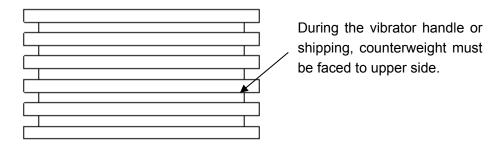


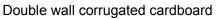
Picture 4 Reel packing condition

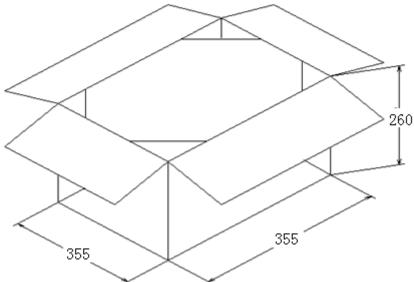
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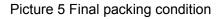
11.3 Final packing condition

1000pcs/reel X 6reel= total 6000pcs









11.4 Accessories included in final package

Out-going inspection data sheet (n=35pcs) will be attached for each lot, we do implemented inspection after reflow. Inspection item including:

- Load speed Load current Starting current
- Starting voltage
- Coil resistance

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12. RECOMMENDED REFLOW PROFILE FOR VIBRATOR

12.1 Definitions

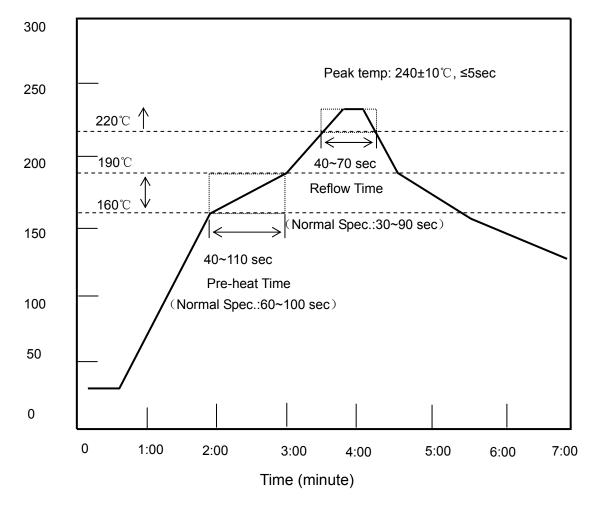
Reflow Profile = Time vs. temperature plot

Peak temperature = Maximum temperature reached on the component Convection = Forced air heating

12.2 Recommended temperature check method of reflow furnace

The reflow furnace used should be 100% convection reflow. Thermocouples should be securely attached to the top surface of vibrator to insure the temperature exposure is met. Profile should be recorded by data acquisition for future reference.

12.3 Recommended reflow Profile for Pb-Free soldering



Temperature(℃)

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13. NOTES ON USE

13.1 Pay attention to the voltage and current ranges which applied to the vibrator, and use the vibrator in accordance with this specification, otherwise, it will reduce the life and performance of the vibrator.

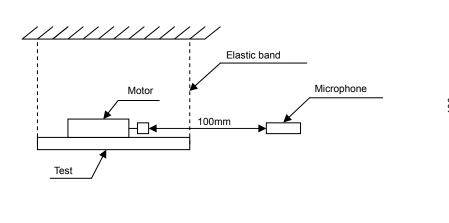
13.2 Do not use hot gun to puff the surface of vibrator from PCB directly.

- 13.3 Do not locking the motor with current applied for long time, which may cause the motor to overheat and short circuit.
- 13.4 Do not exert pressure the terminals, otherwise, it will result in terminal deformation.
- 13.5 Do not bring magnetized objects near or contact with the surface of vibrator, which will demagnetize the magnetism of vibrator and result in noise failure.

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Appendix 1

Figure 1.1: Mechanical noise measurements setup



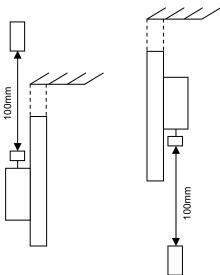


Figure1.2:Test jig, weight 100g

